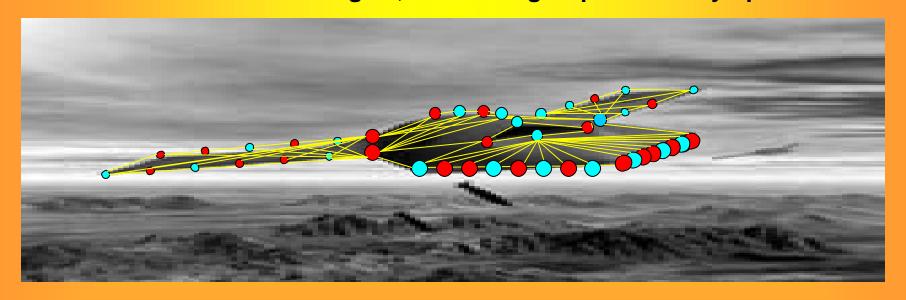
## **NEURAL NETWORKS**

# THE BRAIN OF THE TRULY AUTONOMOUS UAV

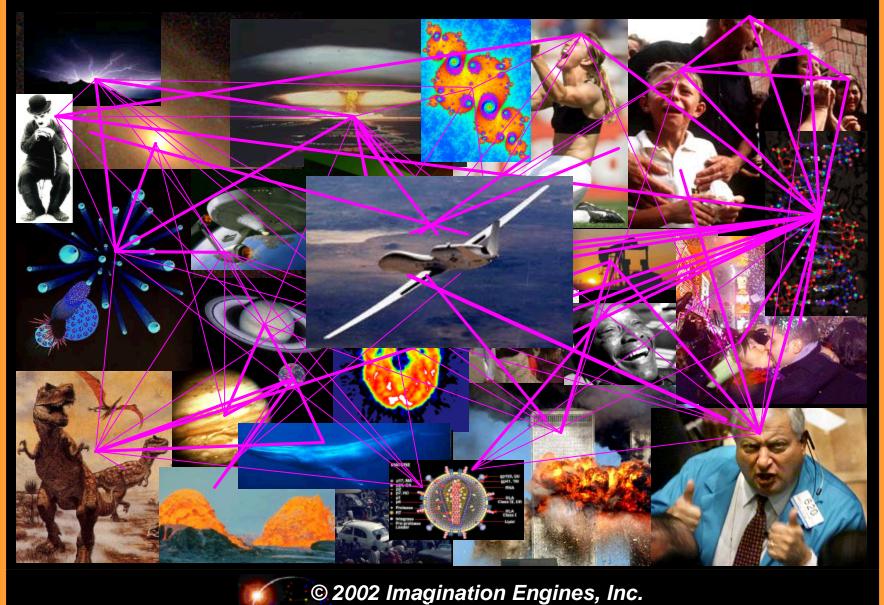
Stephen L. Thaler, Ph.D.

President & CEO, Imagination Engines, Inc.

40th Annual NDIA Air Targets, UAVs Range Operations Symposium

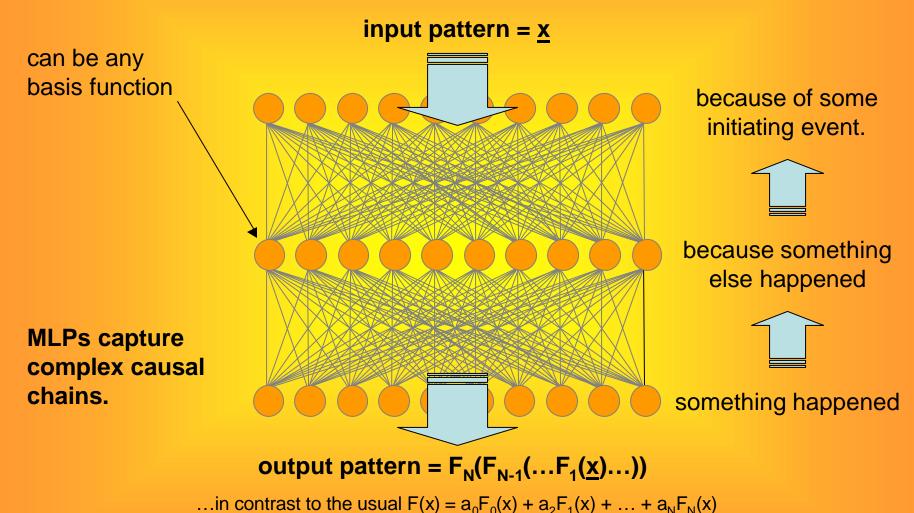


# **UNIVERSE IS A COMPLEX NETWORK**



#### **NEURAL NETS MODEL UNIVERSE**

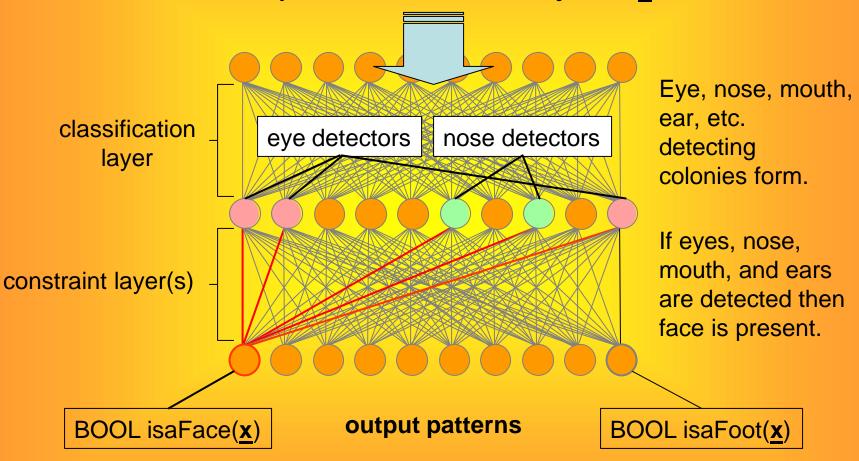
Connection weights are tantamount to expansion coefficients within a curve fit.



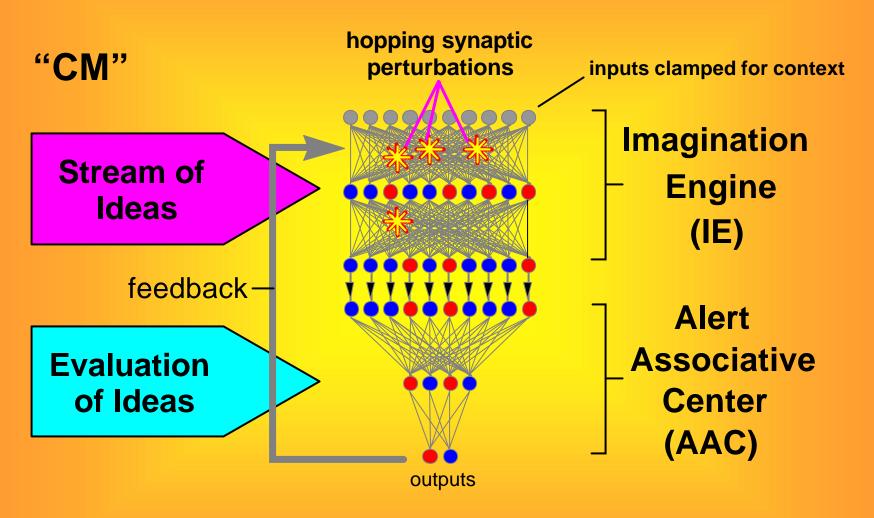
## MLPS\* CAPTURE ENTITIES & CONNECTS

\* MLP = Multi-Layer Perceptron, the workhorse of artificial neural networks.

#### bitmaps of faces and other objects = $\underline{x}$



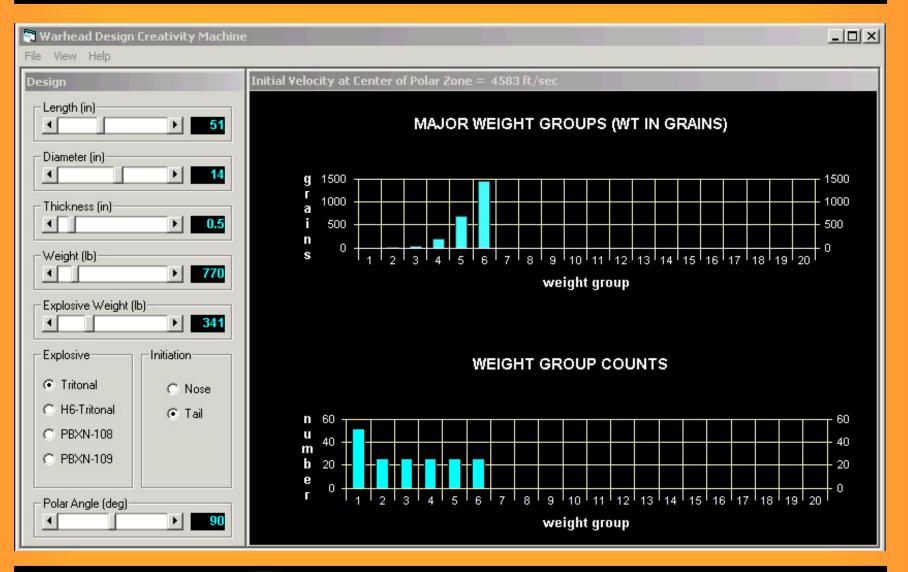
## **CREATIVITY MACHINE PARADIGM**



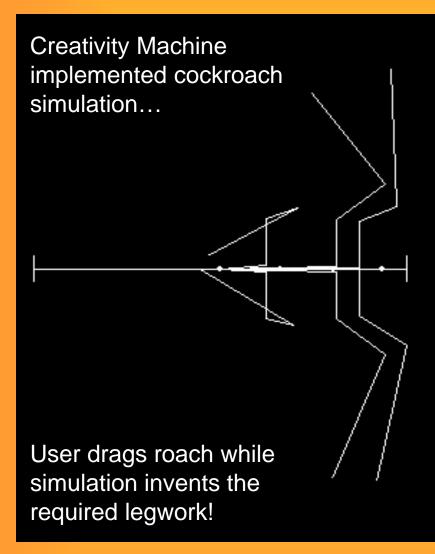
US05659666, 08/19/199, Device for the Autonomous Generation of Useful Information



## **AUTONOMOUS WARHEAD ADAPTATION**



## **AUTONOMOUS MOTION PLANNING**

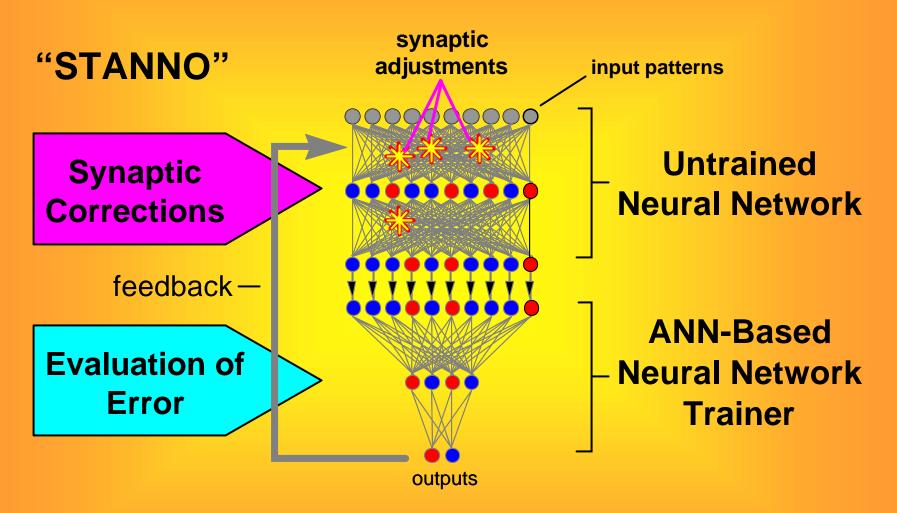


30 degree of freedom mastered in 30 seconds. A 1,000+ degree of freedom system represented in flight controls do not pose a problem.



All that need be supplied is a 'will' to proceed in a certain direction, toward a particular goal, as represented by the cursor drag.

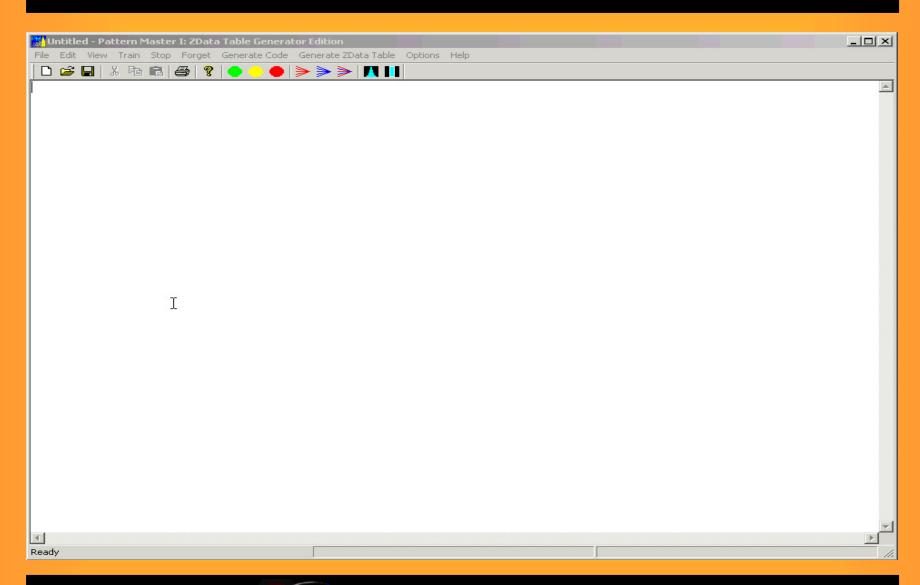
## **SELF-TRAINING ANN OBJECT**



US05845271, 12/01/1998, Non-Algorithmically implemented artificial neural networks and components thereof

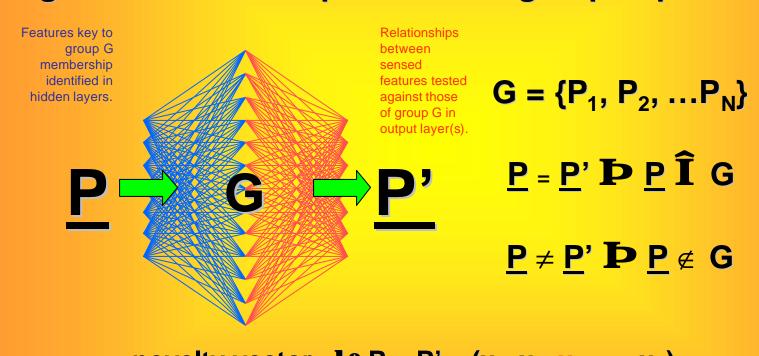


# STANNO-BASED ZDATA GENERATOR



#### **MEMBERSHIP / ANOMALY DETECTION**

Intact feed forward passage through auto-associative net, trained upon some interrelated group of patterns, signifies membership within that group of patterns.

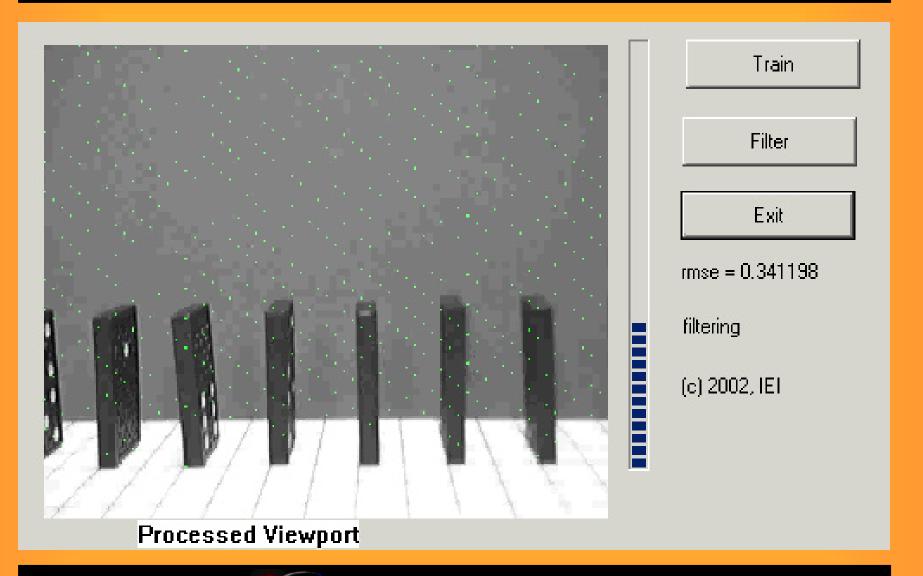


novelty vector,  $\underline{\mathbf{d}} \cdot \underline{\mathbf{P}} - \underline{\mathbf{P}}' = (\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3, ..., \mathbf{x}_N)$ 

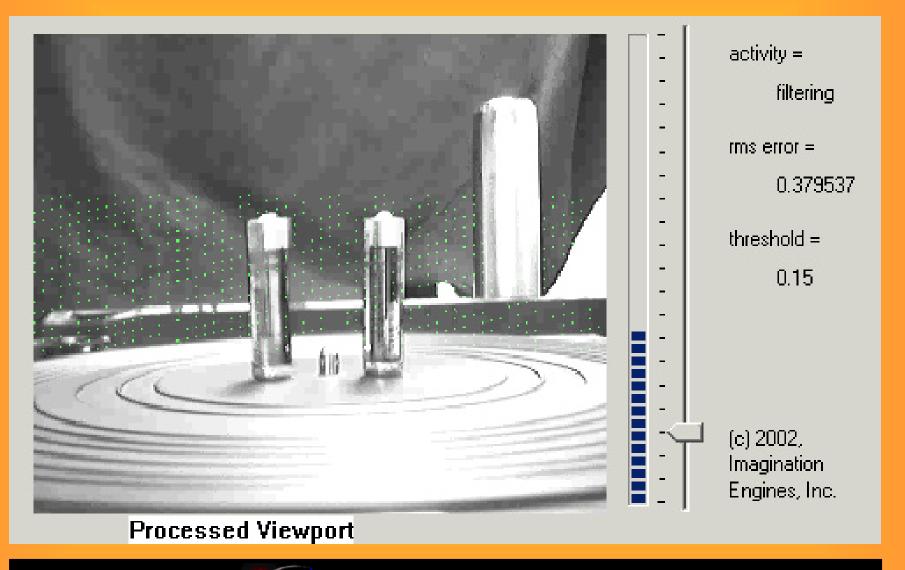
US05852816, 12/22/1998, Neural network based database scanning system



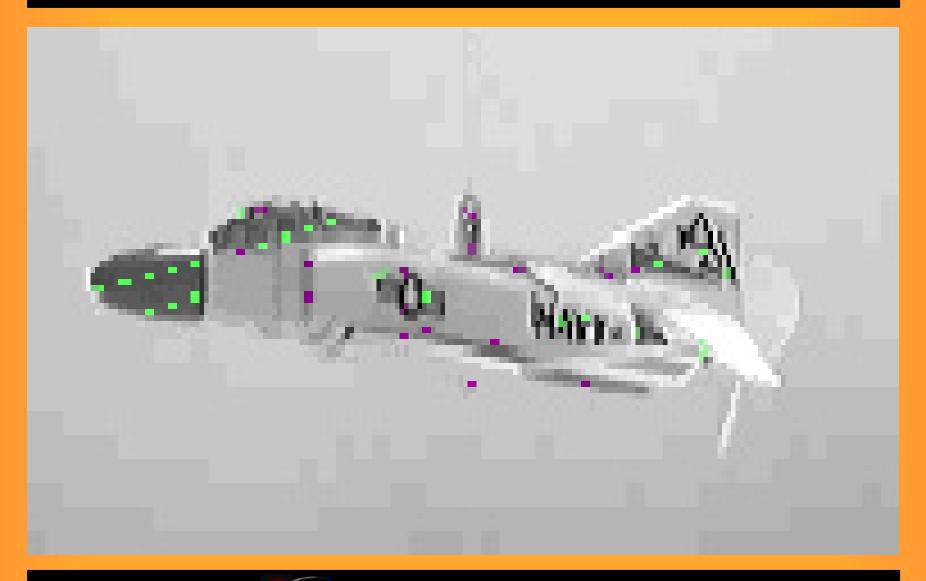
# **BATTLE DAMAGE ASSESSMENT**

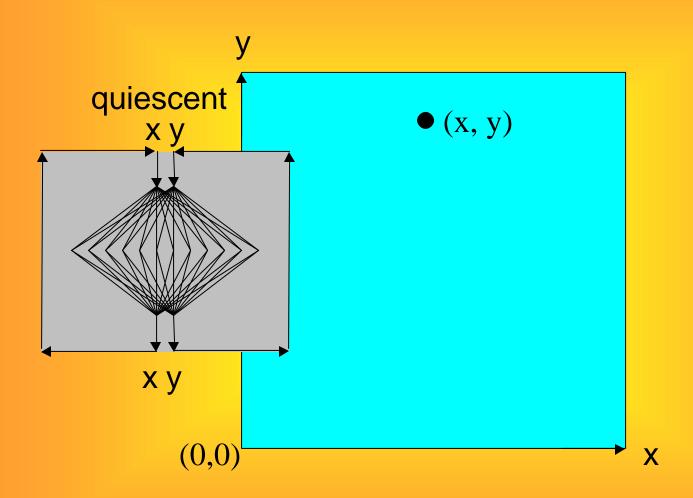


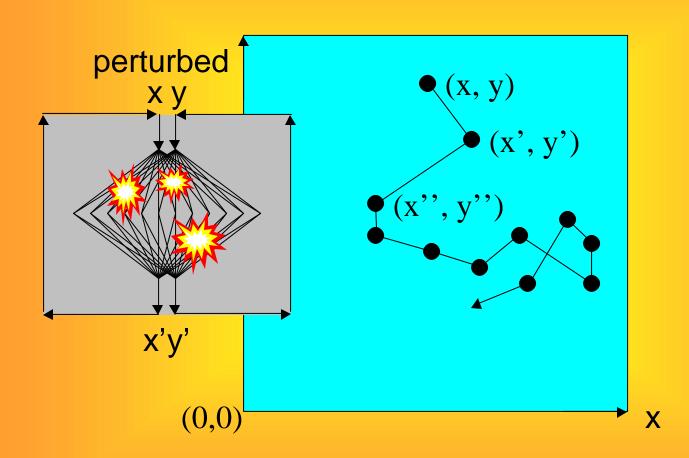
# **BATTLE DAMAGE ASSESSMENT**

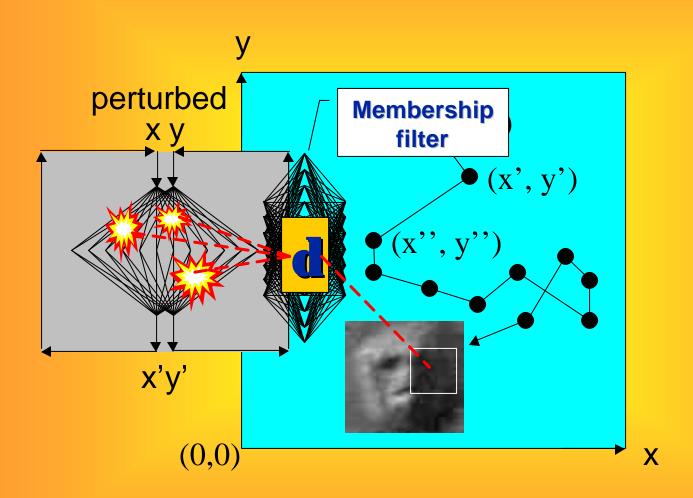


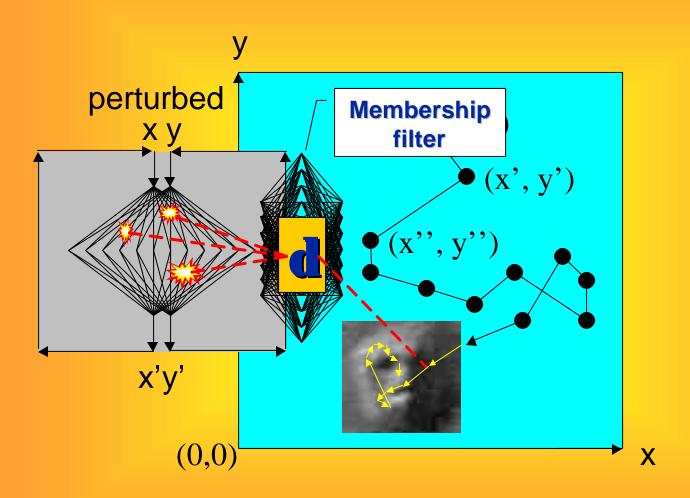
# **AUTONOMOUS TARGET RECOGNITION**





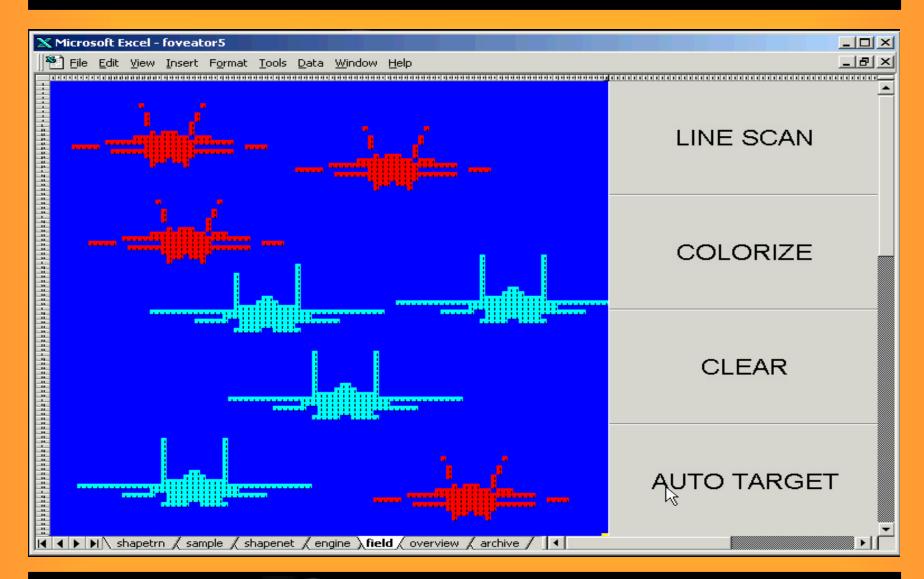






US05852816, 12/22/1998, Neural network based database scanning system

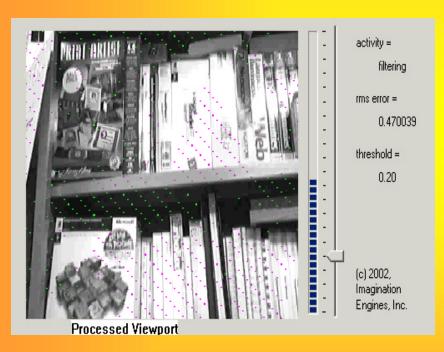


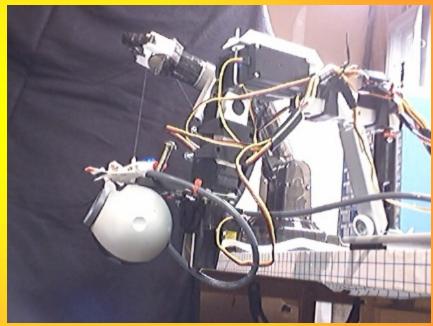


#### Objective: Autonomously find the toy F4...

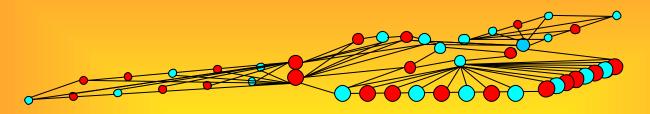
#### attention window

#### robot held camera





# **AUTONOMOUS, BRILLIANT UAVS**



Creativity Machines + STANNOs + Group/Anomaly Filters

Aircraft / UAV Design...... Let them design themselves.

Web-based Logistical Support ...... Let them search for their own components.

Field Kit for Tailored Assembly...... Let them recommend their own field configurations.

Self-diagnosis..... Let them tell us when / if they're ready to go.

Flight Control / Dogfight / Egress..... Let them fly themselves.

Massively Parallel Sensor Integration.... Let them fuse inputs and resolve ambiguities.

Mission / Sortie Planning.....Let them plan based on loosely posed objectives.

Strategy / Tactics..... Let them improvise as battlefield evolves.

Battle Damage Recovery..... Let them repair themselves in flight.

Low Observables Adaptation..... Let them reconfigure themselves to evade.

Autonomous Targeting..... Let them lock on without slow human judgment.

Battle Damage Assessment.....Let them evaluate their effects on target and react.

Legal Repercussions.....Let them be their own, instantaneous cyber-lawyer.

Political/Philosophical Perception.....Let them have similar motivating "feelings."

