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# Improvements to Airborne Ladar Man-in-the-Loop Operations

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# Outline

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- Objectives
- Test Description
- Results
- Analysis
- Conclusions



# Ladar Visualization and Analysis (LAVA) Test



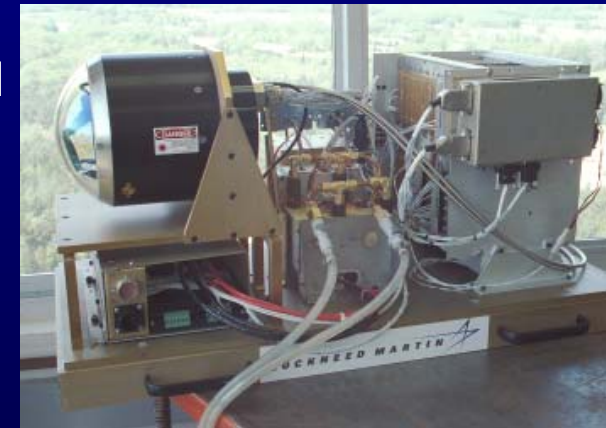
## Objective:

- Collect Ladar imagery over UAV type scenarios
- Improve visualization processes and techniques employed by UAV sensor technology



## Approach:

- Conduct captive flight test (CFT) utilizing the Lockheed STAR Ladar seeker
- Collect Ladar imagery over RSA and surrounding urban area

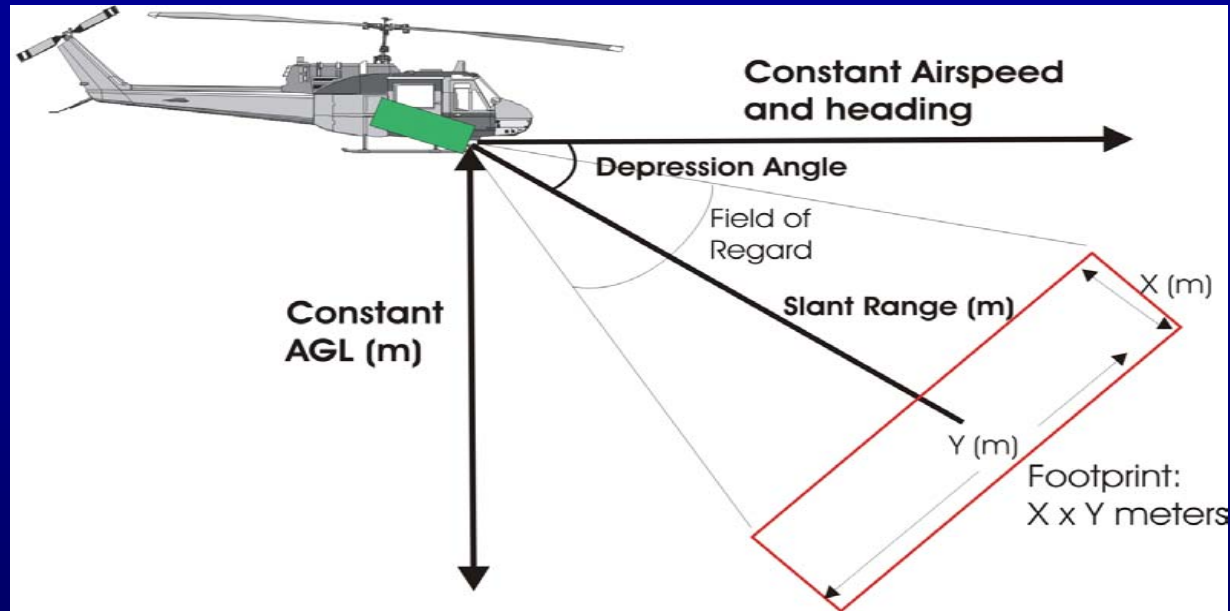


## Payoff:

- *Provide additional dataset to improve man-in-the loop operations and ATR development for UAV tactical environments.*



# Test Description



**Waypoint Flight Path**

	Flight Configuration #1	Flight Configuration #2
Speed	50 kts	50 kts
Altitude (AGL)	2121 feet	3182 feet
Sensor Depression Angle	45°	45°
Sensor Slant Range	1000m	1500m
Sensor Scan Footprint	59m x 436m	89m x 655m
Sensor FOR	25 deg	25 deg
Spot Size at Range	40cm	60cm



# LADAR CFT Data Collection Areas



Test Area 3, RSA



Building 5400, RSA



RMF, RSA



Whitesburg Bridge, HSV



US Hwy 231, HSV



Space/Rocket Ctr, HSV



I-565, HSV

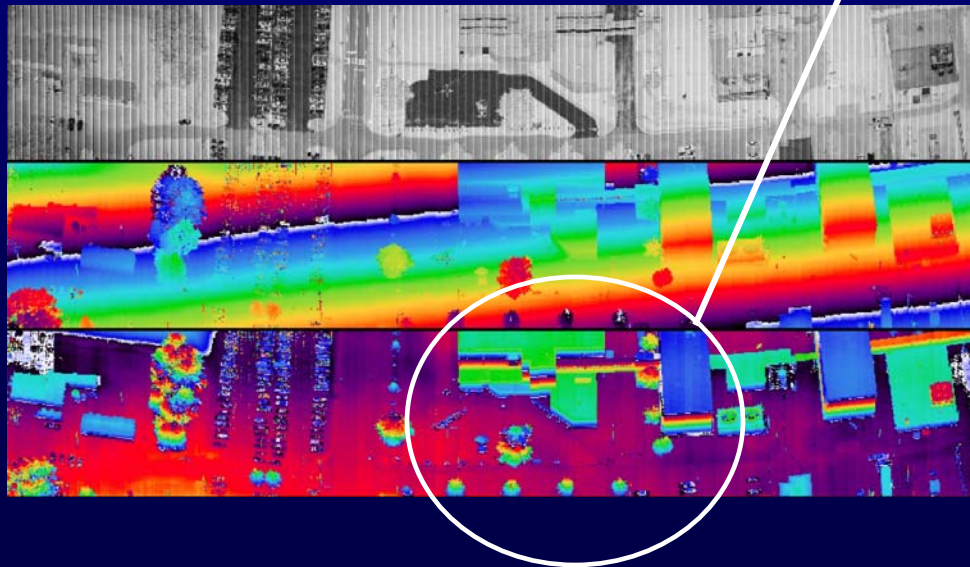
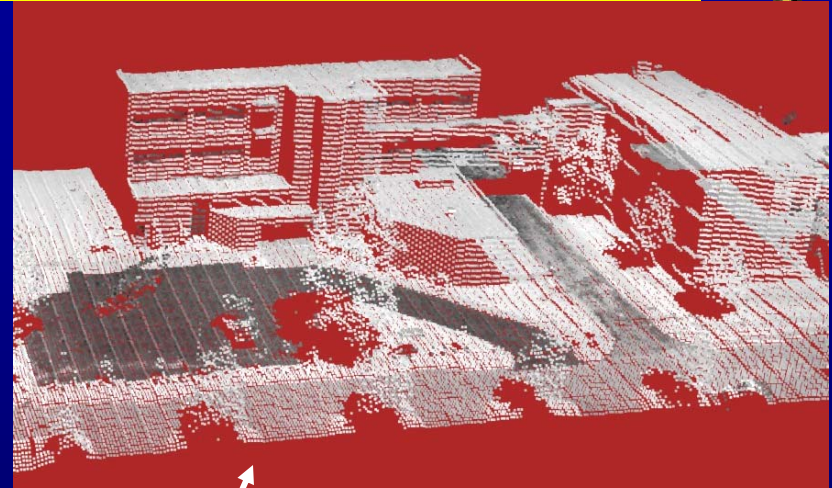


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# Data Results / Examples from CFT



# Building 5400, Redstone Arsenal, AL



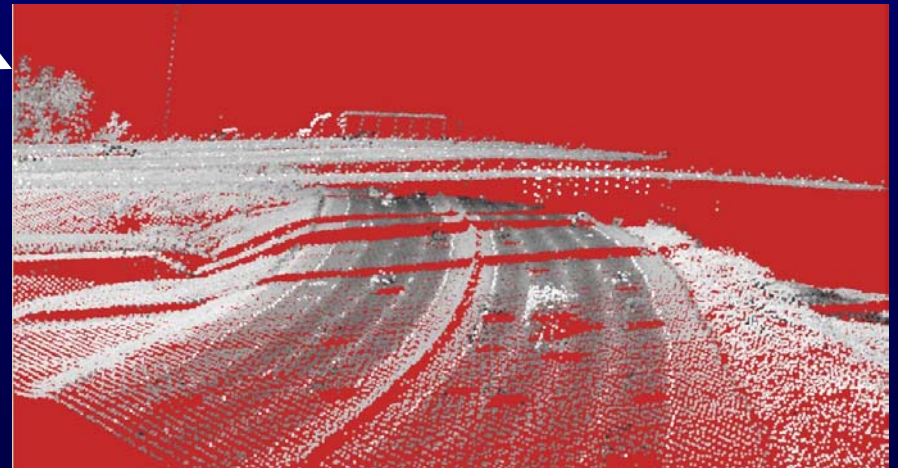
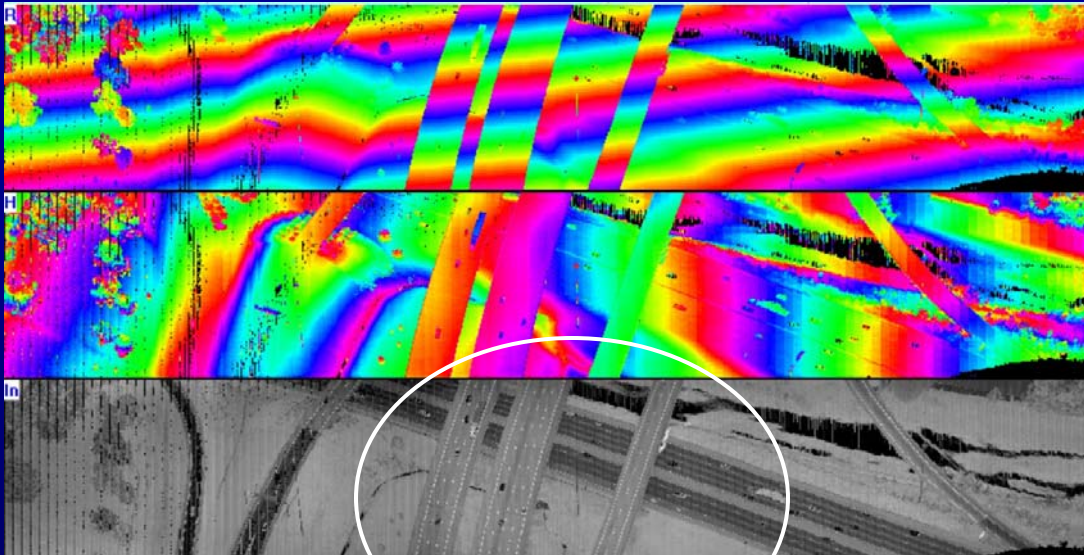
Intensity

Range

Height



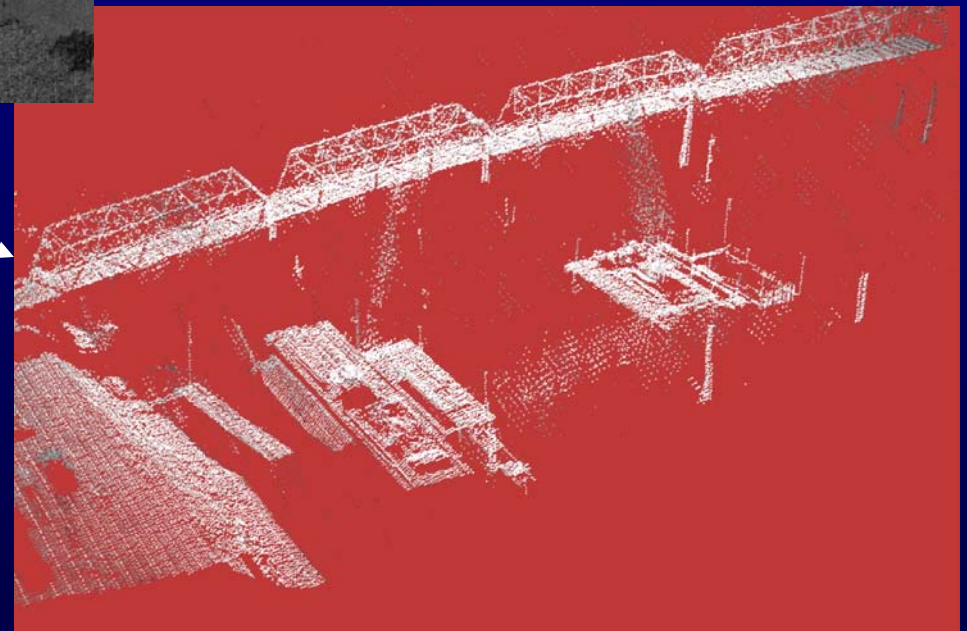
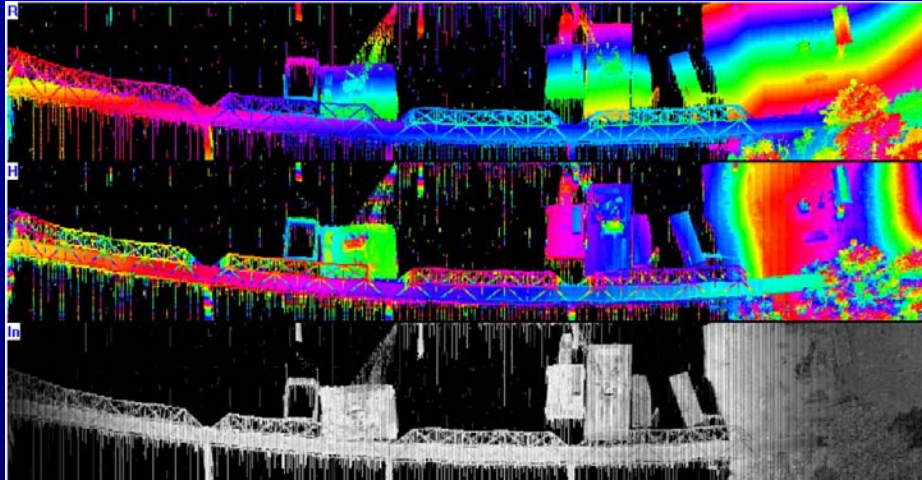
# I-565 over Highway 231, Huntsville, AL







# Whitesburg Bridge, Huntsville, AL



Reverse Angle



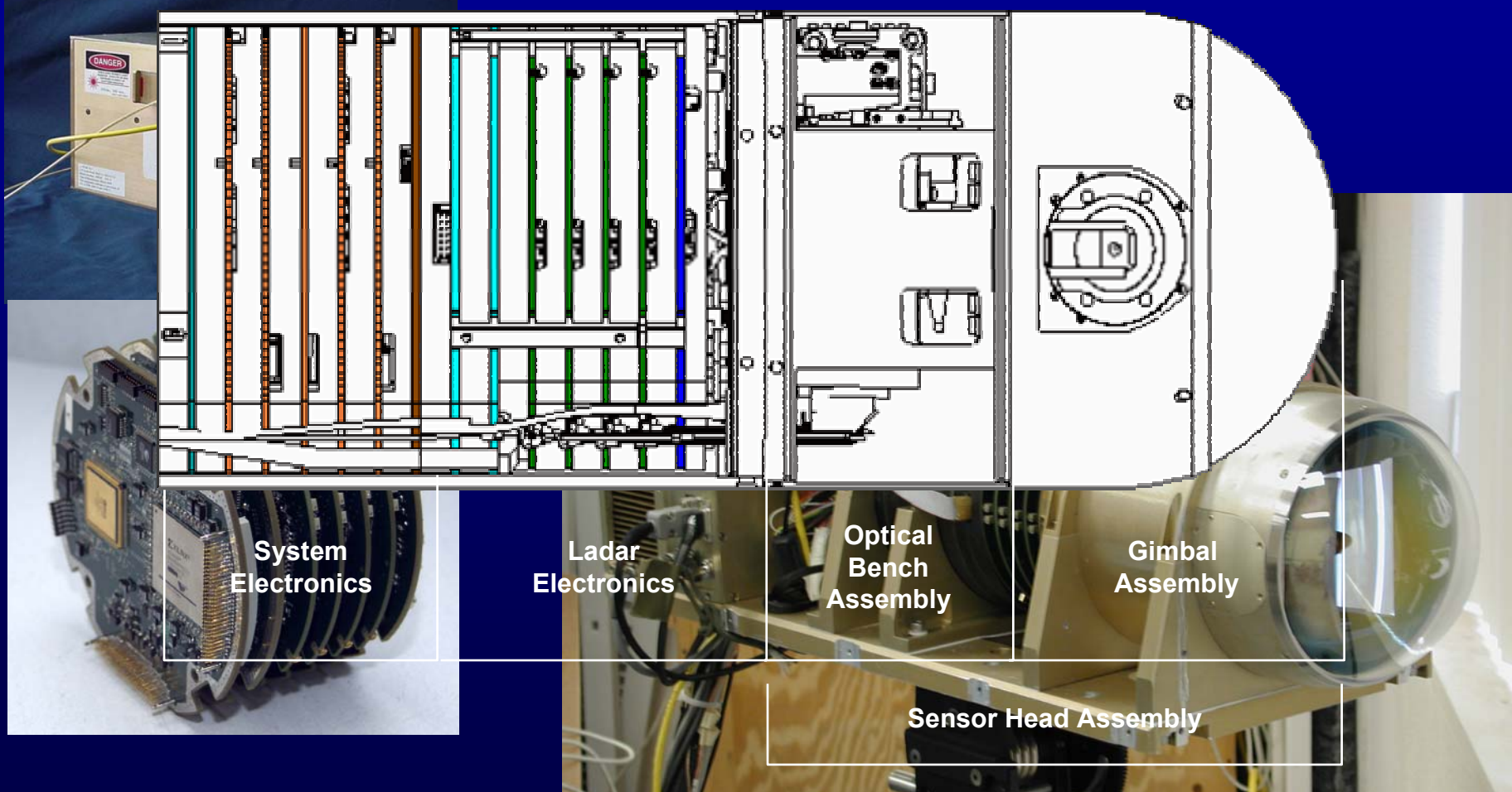
# CLAS Test Summary



- Test designed for advanced LADAR ATR algorithm development
- Data successfully collected for all test scenarios
  - Targets imaged from less than 250 meters to over 4 Km
- 3 Days, ~20 scenarios, thousands of images
  - Moving, confusers, long range, variable resolution, stationary, clutter, camouflage, dismounts, urban data
- System was operational in < 2 hrs after arrival on site
  - No failures in 2 weeks of CY2004 testing and significant transport



# Common LADAR Seeker (CLAS)



System Electronics

Ladar Electronics

Optical Bench Assembly

Gimbal Assembly

Sensor Head Assembly



# Russell Measurement Facility (RMF) Laboratory Tower



**Total Tower Height: 329 feet**



**Top Laboratory Height  
(from ground to floor):  
300 feet**



**Floor Dimensions: 34 x 17 feet**



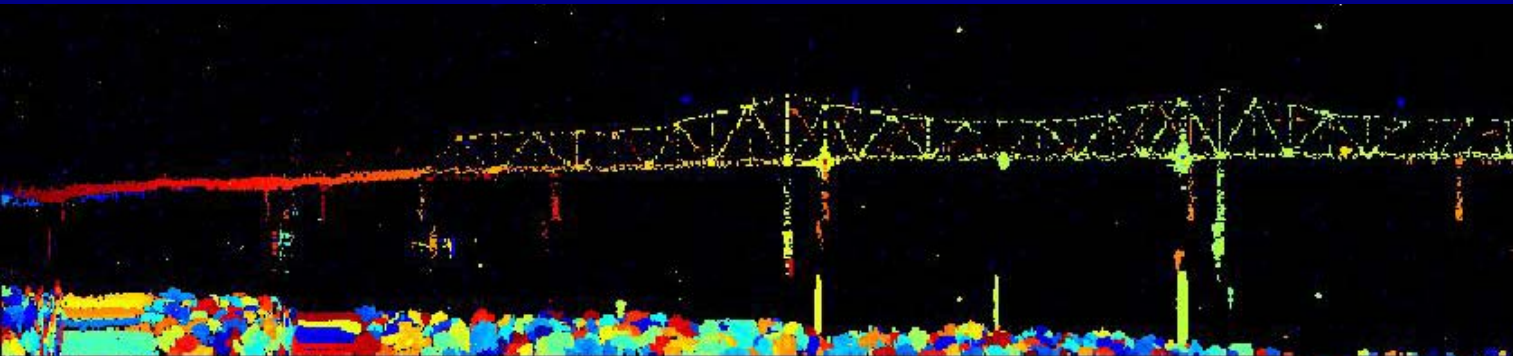
**Elevator Laboratory  
Floor Dim.: 10x6 ft.  
30 floor stops**



# Data Results / Examples from Tower Test



# Whitesburg Bridge



Range



Intensity

Target imaged during degraded weather conditions



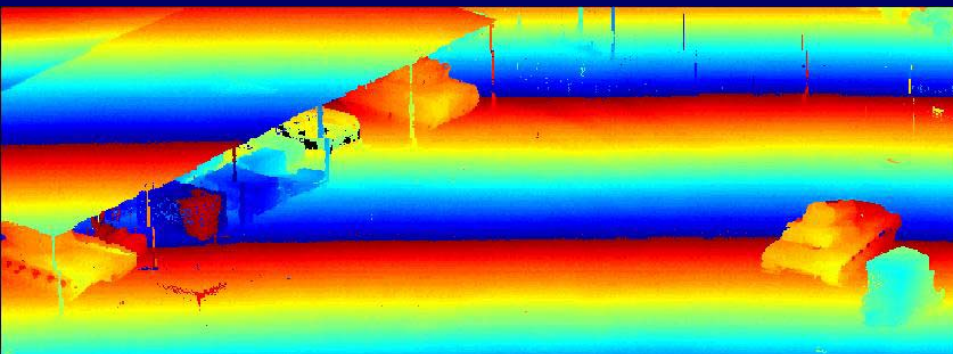
# Compound Test Area



Data Collection at short range:

- < 250 meters
- Targets in occlusion or open

Range Image



Intensity Image





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# Conclusions





# Ladar Data in a World Context



Simulator Quality Terrain

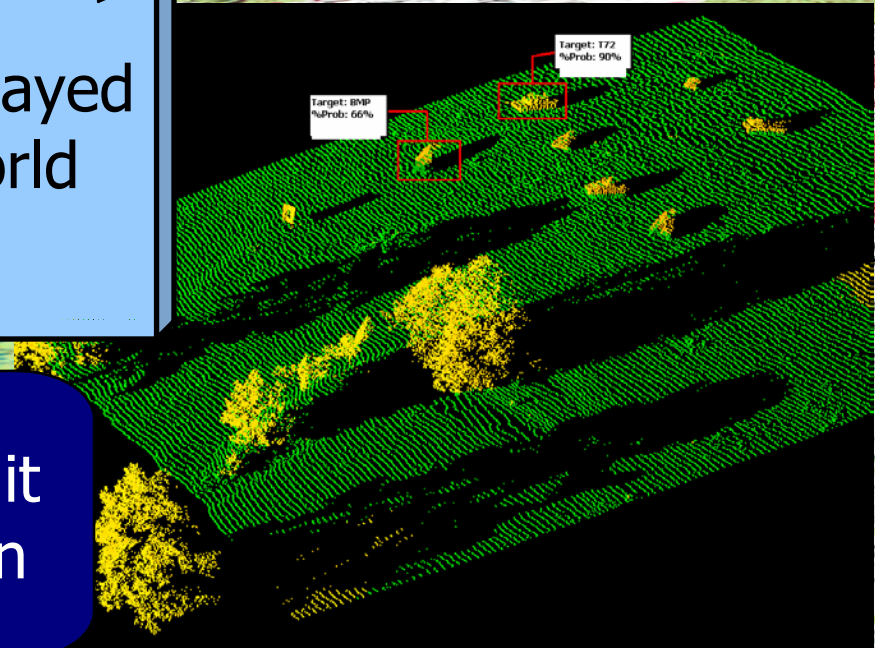
Tactical Situational Awareness

Enhanced Data Visualization

LADAR Sensor Data can be displayed to the Warfighter in a Real World Visual Context

Proximity to Roads and Natural Features

Friendly Unit Designation



SNSR: 1043, TIME 10:47Local



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*Questions?*