



Decision Support for Time Critical Strike: Land Based Target Area Of Uncertainty (LBTAOU) Prototype

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Partnership



Research and development center for submarine systems, autonomous underwater systems, and undersea offensive/defensive weapons

Serves as a liaison between the University of Massachusetts Dartmouth (UMASSD) and industry, forming partnerships with regional technology-based corporations and laboratories, providing educational and research opportunities for UMASSD students

- To evaluate the application of Geographic Information Systems (GIS)-based decision support technologies to address Naval Capability Gaps
 - Persistent ISRT for accurate target discrimination and location (gap no. 5)
 - Rapid movement of mobile/emergent target data to shooters (gap no. 7)
 - Persistent high speed strike weapon to engage time critical targets (gap no. 12)



Key To Time-Critical Strike Capability



“We need a decision-making aid with software where we can tie in ISR and factor in such things as rules of engagement and other sensitivities, blast fragment pattern [to avoid collateral damage], target priority, target location, etc. That would really shorten the time between identifying a target and getting permission to drop.... “

**Rear Adm. (select) Joseph F. Kilkenny,
Office of the Chief of Naval Operations
www.navyleague.org**

Areas of Interest



- Time-critical, mobile targeting
 - Support High Speed Weapon and advanced versions of TacTom
- Integrated Land Attack
 - Assess tactical application for mission planning, loiter planning, and increasing situational awareness for the shooter
- Common Human Computer Interfaces (HCI)
 - Evaluate the use of GIS as a common presentation layer for complete situational awareness
- Develop solutions that extend to other tactical areas
 - Unmanned Aerial Vehicle (UAV) search planning
 - Unmanned Combat Aerial Vehicle (UCAV) targeting
- Examine and apply Artificial Intelligence to GIS applications
 - Apply Fuzzy Logic to spatial analysis
 - Predict target movements based on mission/intent

Tomahawk Background



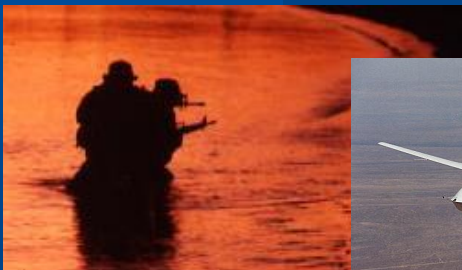
- Block III
 - Used against high-priority, long-dwell targets
- Block IV or Tactical Tomahawk
 - Initial Operational Capability FY04
 - Additional capabilities
 - Satellite communication
 - In-flight retargeting
 - Loiter capability
 - Health and status reporting

The Problem



Limited capability against mobile, time-critical targets

- Weapons cannot be recalled, unlike an Unmanned Aerial Vehicle (UAV)
- Short endurance limits ability to loiter
- Call-For-Fire (CFF) requests
 - Require detailed mission planning
 - Response time may be significant
- During in-flight time, a target need only move a short distance to evade strike

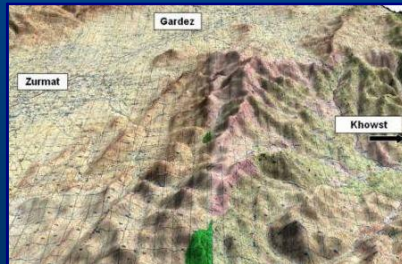


Approach

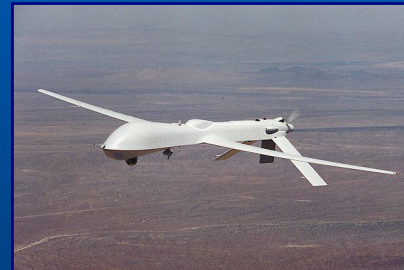
To provide a tool that allows mobile targets to be quickly relocated/retargeted via an optimized search route based on :



Target Capabilities



Operating Terrain

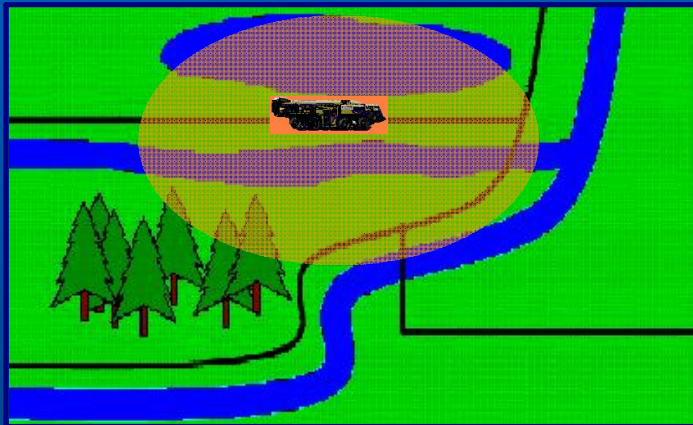


Reconnaissance Vehicle Capabilities



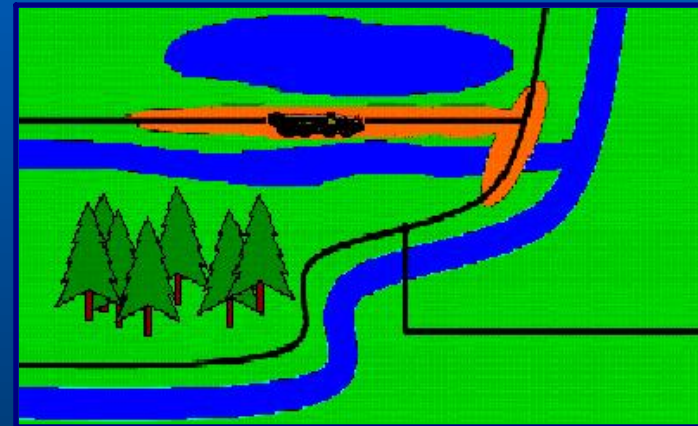
Weapon Capabilities

Search Areas



Typical AOU

VS.



Optimized AOU

Using LBTAOU against a mobile, time-critical target:

1. Transporter/Erector/Launcher (TEL) has been identified as a target by UAV
2. Tomahawk (or High Speed Weapon) is targeted
3. A later pass of the UAV indicates the target is no longer present
4. LBTAOU calculates an optimized search region, search route, and loiter area
5. UAV is routed to search the region
6. Tomahawk's current position and fuel status is queried
7. Tomahawk loiters while the target is reacquired
8. Once the target is located, the optimal strike area is selected
9. Weapon is retargeted

Goals



- Identify the AOU for land-based targets as a function of
 - Target Parameters
 - Dimensions, turn radius, max speed, terrain capability, etc.
 - Geographic Features
 - Roads, bridges, landmarks, elevation, terrain, rivers, etc.
- Provide optimized search routes
 - Reduce reacquisition times
- Provide optimal missile loiter position
 - Reduce missile loiter-to-strike time
- Identify target vulnerability windows in environment
- Identify optimal strike locations

Employed Technologies



- Combine mature algorithms, motion analysis techniques, and Geographic Information Systems (GIS)
 - Reduces development time
 - Increases reliability
 - Decreases risk
- Employ GIS Spatial Queries for terrain data access
 - Describes relationship between map locations and geographic features

- The LBTAOU prototype currently uses four terrain layers which include:
 - Slope
 - Compared to the max gradient of the targeted vehicle
 - Water Depth
 - Compared to the maximum water depth that the targeted vehicle can traverse
 - Terrain
 - Compared to the ground clearance and terrain capability of the targeted vehicle
 - Forest Density
 - Compared to the width of the land-based target



Current LBTAOU Algorithm Suite

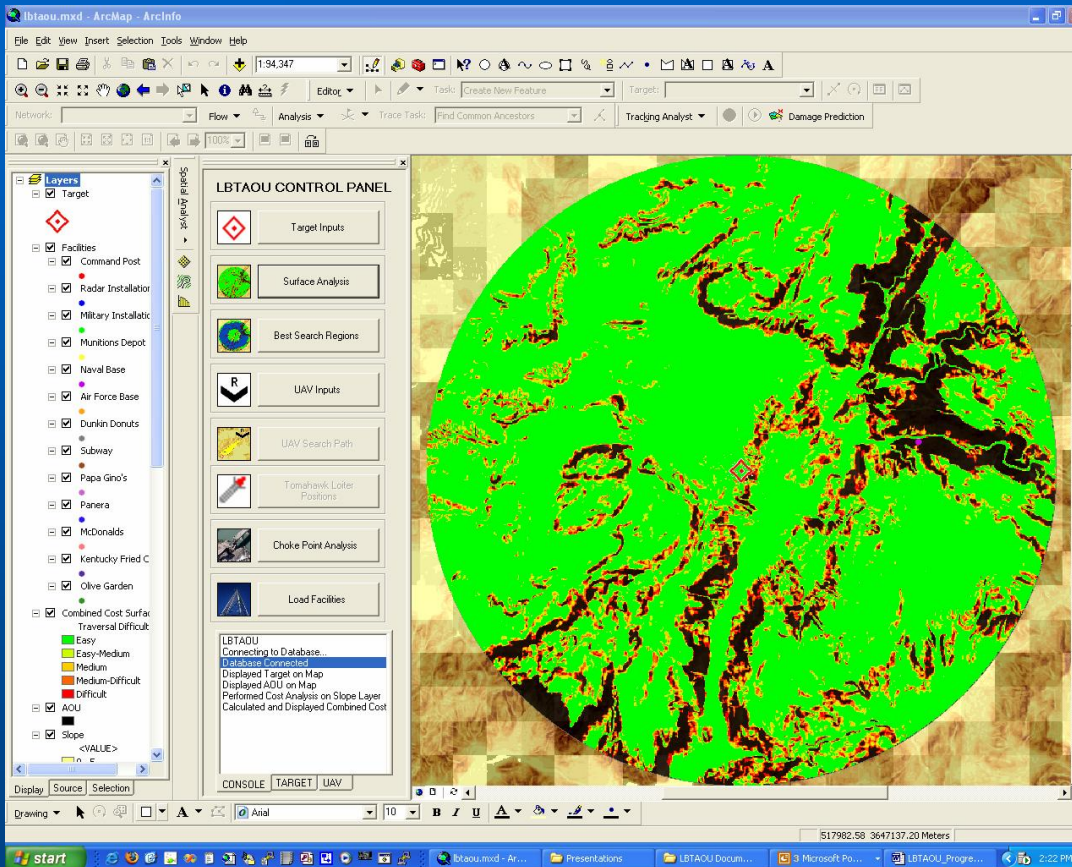


- Combined Cost Surface
- Search Region
- UAV Search Route
- Loiter Position
- Battle Damage Query

Combined Cost Surface



Cost Surface of AOU



The Cost Surface Algorithm will eliminate any region that is unreachable by the target, and rate the difficulty to traverse the land. This region will be given a non-traversable value.

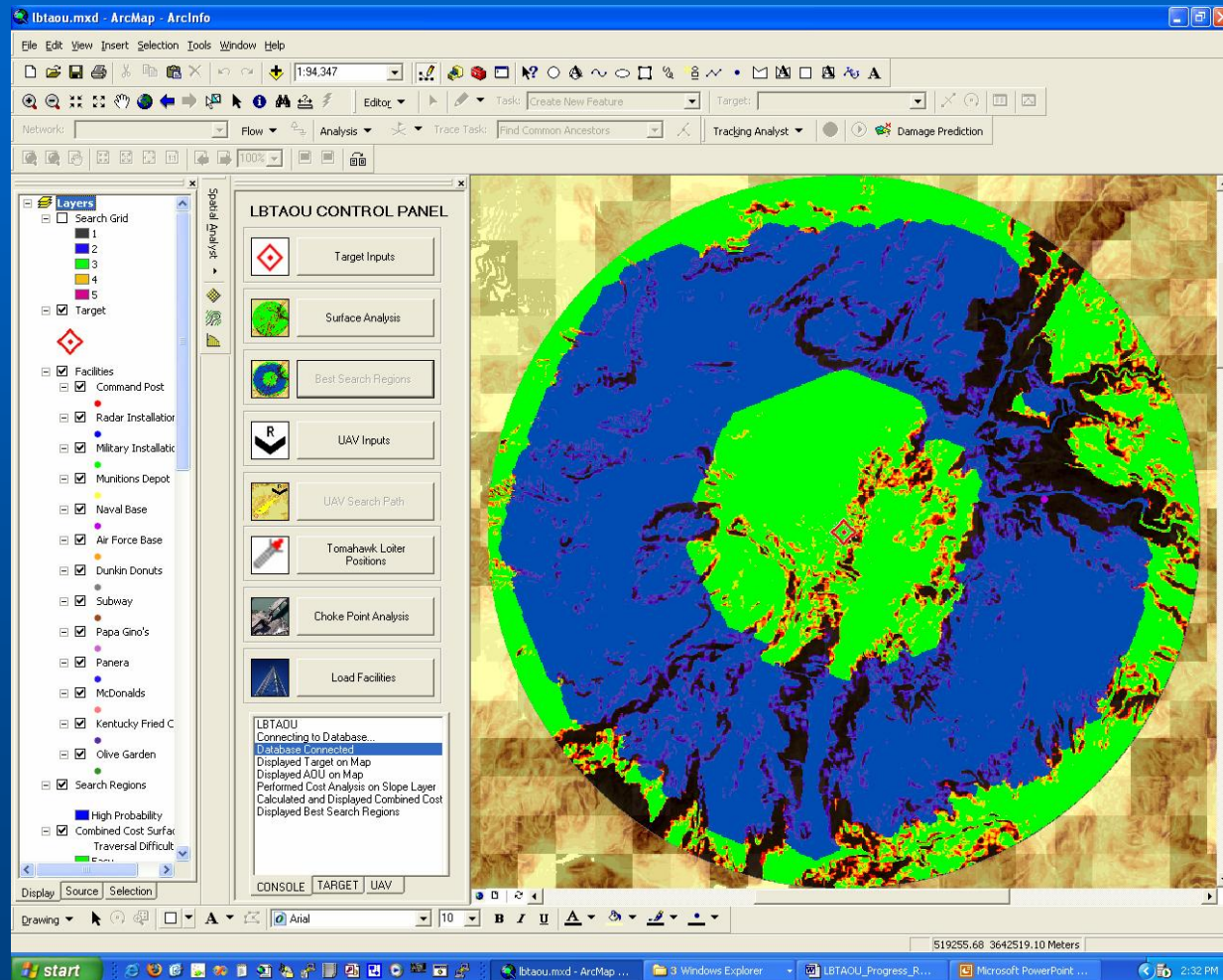


- **Determining the Search Region**
 - **Calculate Cost Distances for land-based target.**
 - Raster containing distance information extending from initial position
 - **Calculate Outer Extent of Search Region:**
 - Cost Distance (meters) \leq Radius of AOU (straight line distance)
 - Radius of AOU = (MAX Speed) * (time elapsed)
 - Eliminates areas where target cannot possibly be in the elapsed time.
 - **Calculate Inner extent of Search Region:**
 - Inner extent = INITIAL speed * time elapsed

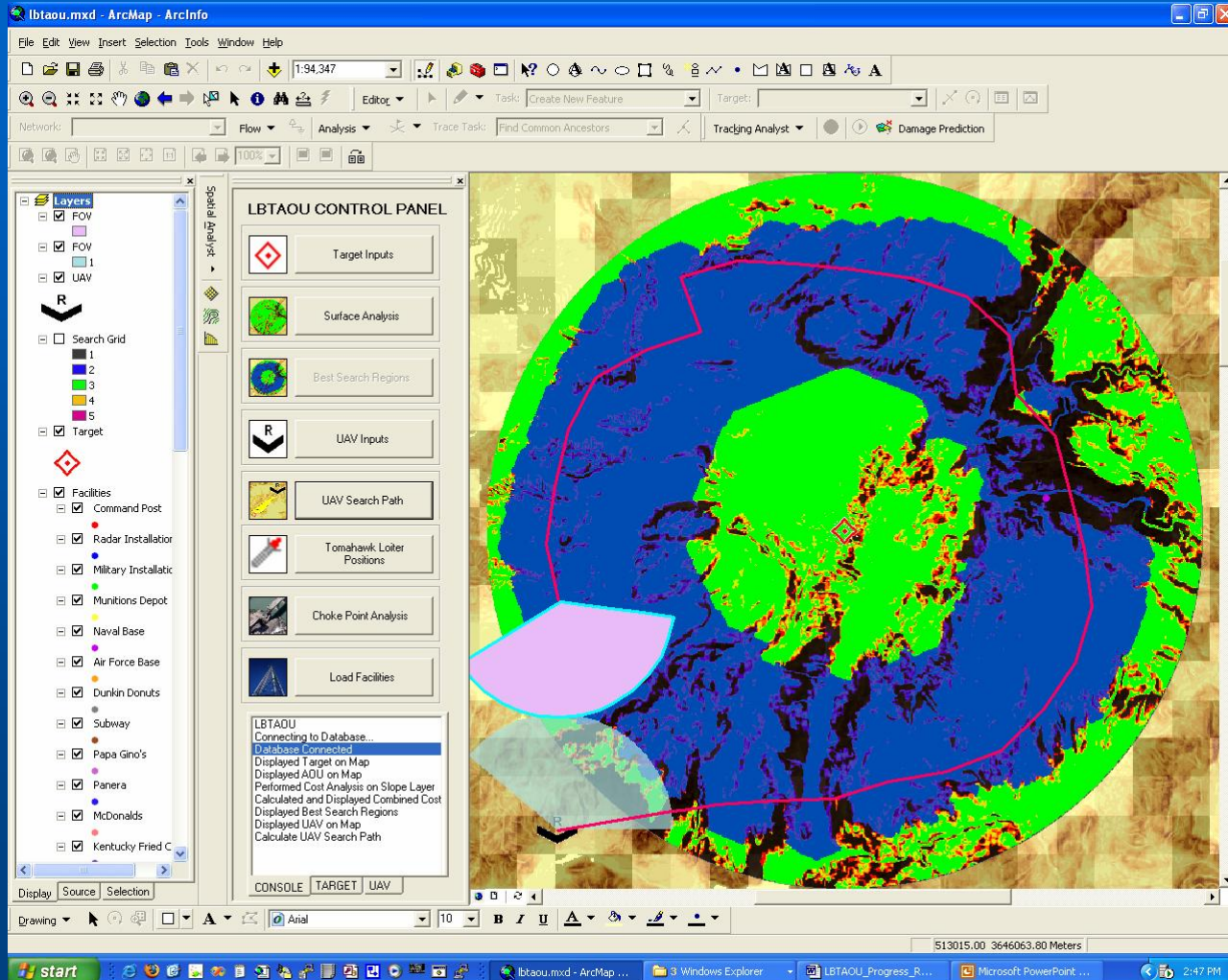
Search Region



Search Regions Overlay of Combined Cost Surface



UAV Search Route Example



Tomahawk Loiter Position



The screenshot displays the ArcMap interface with the LBTAOU Control Panel open. The map shows a coastal region with a central area highlighted in green and yellow, indicating search regions or target areas. The control panel includes several functional buttons:

- Target Inputs
- Surface Analysis
- Best Search Regions
- UAV Inputs
- UAV Search Path
- Tomahawk Loiter Positions
- Choke Point Analysis
- Load Facilities

The console window at the bottom of the control panel shows the following log output:

```

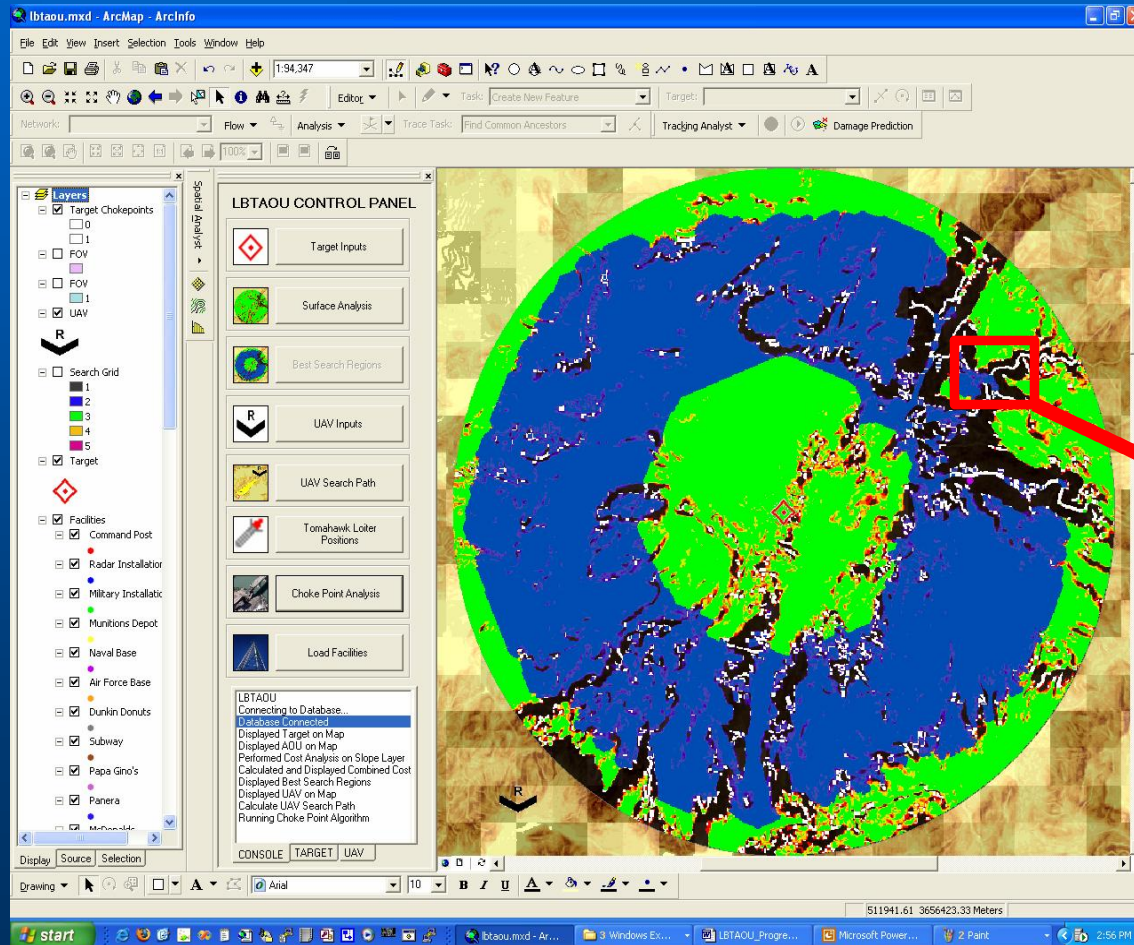
LBTAOU
Connecting to Database...
Database Connected
Displayed Target on Map
Displayed AOI on Map
Performed Cost Analysis on Slope Layer
Calculated and Displayed Combined Cost
Displayed Best Search Regions
Displayed UAV on Map
Calculate UAV Search Path
Running Choke Point Algorithm
    
```

The Layers panel on the left shows the following checked items:

- LoiterPosition
- UAV
- Target
- Facilities
 - Command Post
 - Radar Installator
 - Military Installatic
 - Munitions Depot
 - Naval Base
 - Air Force Base
 - Dunkin Donuts
 - Subway

The status bar at the bottom indicates the coordinates 511716.94 3647486.68 Meters and the time 2:59 PM.

Choke Point Identification

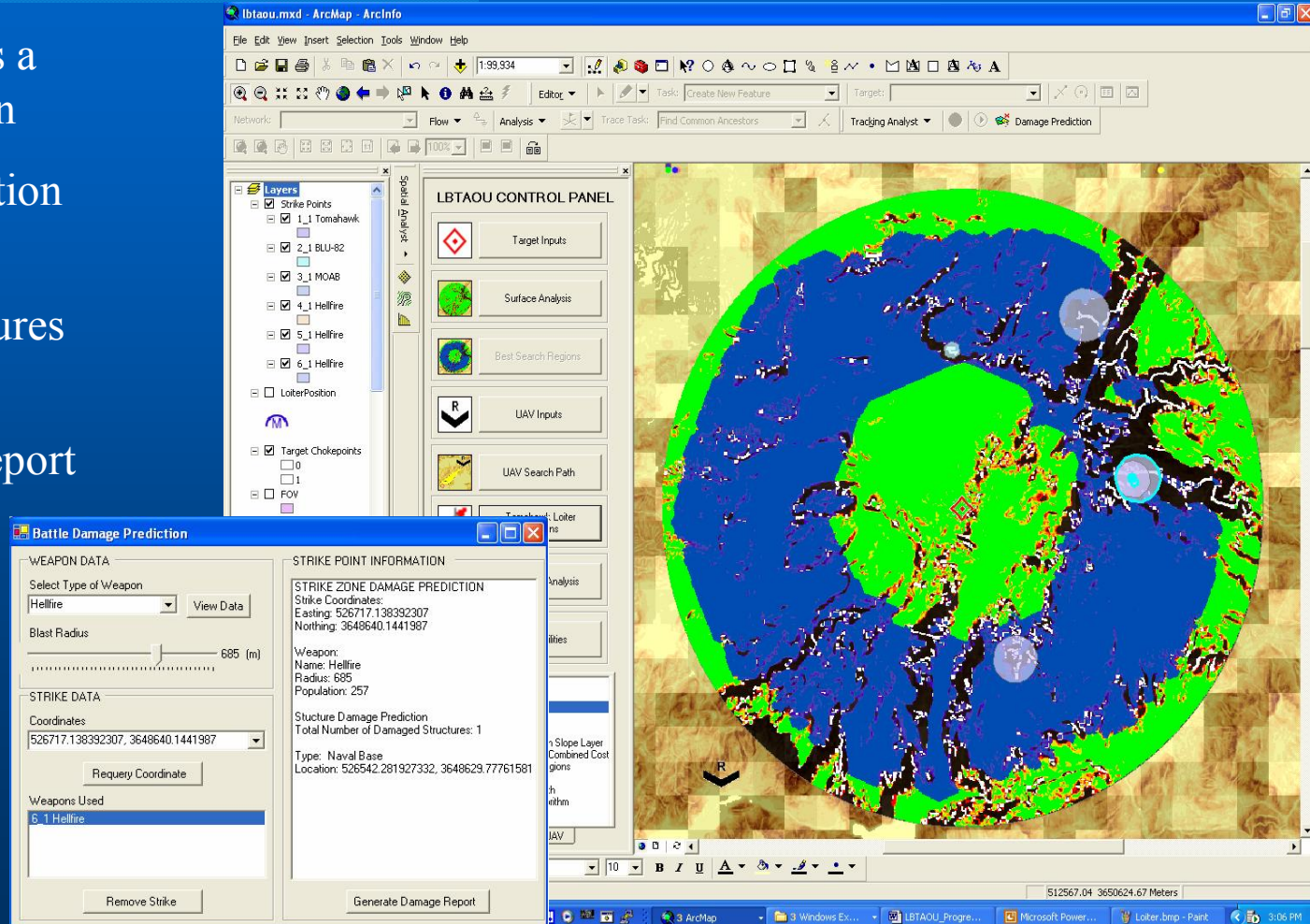


- Determine areas that limited target's ability to evade
- These areas are represented in white



Battle Damage Query

- Graphically displays a strike from a weapon
- Displays the population in the area affected
- Describes the structures in the area affected.
- Generates a Web Report using XML



Battle Damage Prediction

WEAPON DATA

Select Type of Weapon: Hellfire [View Data]

Blast Radius: 685 (m)

STRIKE DATA

Coordinates: 526717.138392307, 3648640.1441987 [Request Coordinate]

Weapons Used: 6.1 Hellfire [Remove Strike]

STRIKE POINT INFORMATION

STRIKE ZONE DAMAGE PREDICTION

Strike Coordinates: Easting: 526717.138392307, Northing: 3648640.1441987

Weapon: Name: Hellfire, Radius: 685, Population: 257

Structure Damage Prediction: Total Number of Damaged Structures: 1

Type: Naval Base, Location: 526542.281927332, 3648629.77761581

[Generate Damage Report]

- Investigate application of Fuzzy Logic to GIS spatial analysis
 - Spatial features often do not have clearly defined boundaries, and concepts such as "steep," "close," or "suitable" can better be expressed with degrees of membership to a fuzzy set than with a binary yes/no classification.
- Apply AI to target movement prediction
- Explore Multiple Objective Decision Support
 - Determine best strike coordinates as a function of population and religious sites, within weapon capability restraints
 - Provide target prioritization based on target threat/intent, loitering weapon status, rules of engagement, etc.
- Develop sensor visibility performance models
 - Examine effects of weather on sensor performance
- Develop Command & Control Information Exchange Data Model (C2IEDM) interfaces
 - Supports NATO multilateral data connectivity
 - Supports Sea Trials



Point of Contact



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