

The Role of the Operator and System Engineer in the Force Modernization Environment

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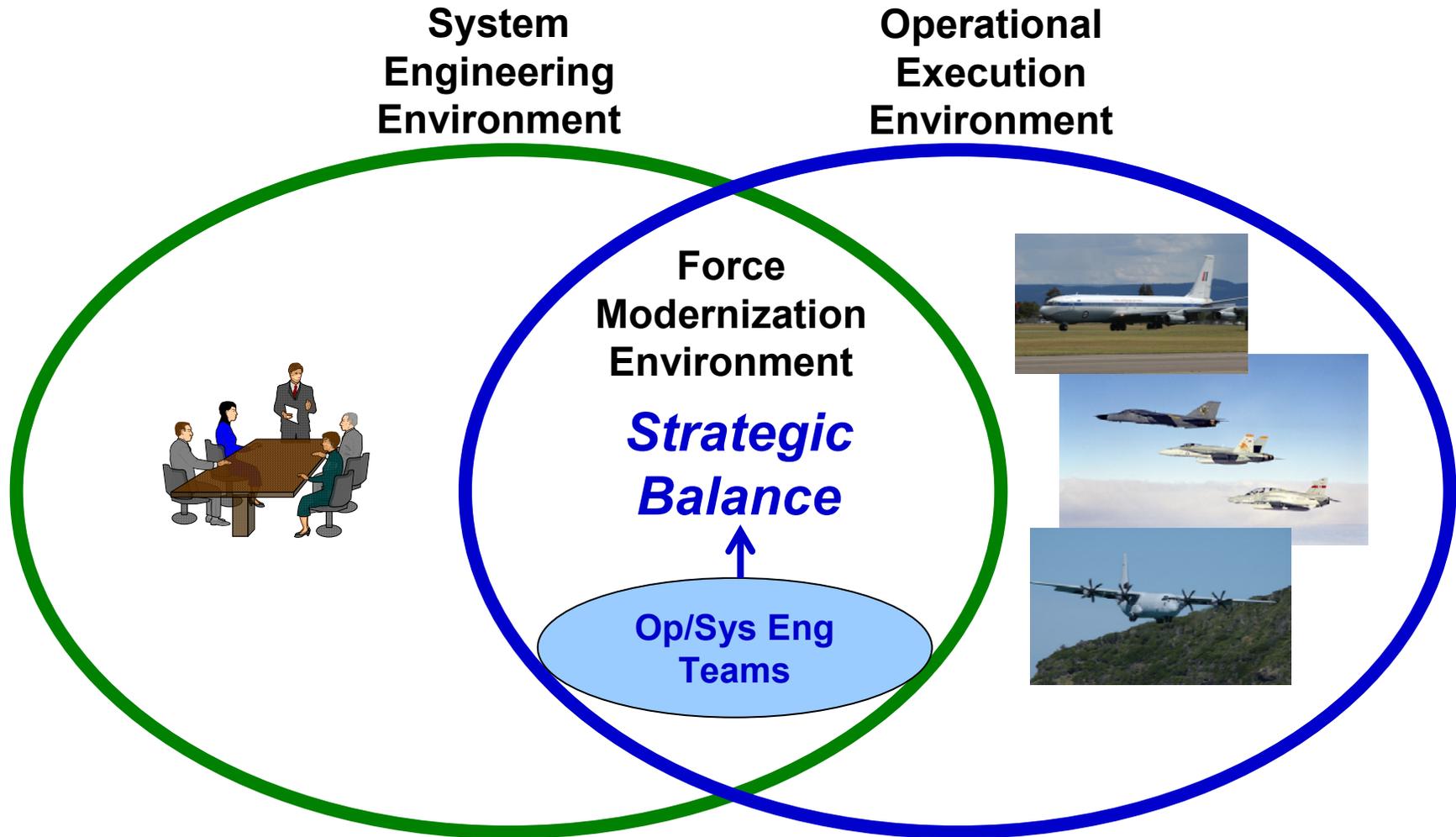
Purpose

- Present one person's perspective of the advantages of the operator-system engineer "team" in today's force modernization environment
- Illustrate some analytic approaches to consider in addressing your operational and systems engineering issues
- Illustrate some data framing concepts to consider in your future systems engineering work
- Find you one good idea that helps your own corporate "operator-system engineer" teams solve problems

PM's Are Under Acquisition Assault

- **Brief the link between national need and operator need**
- **Demonstrate the correlation between the design's focus and the user's priorities**
- **Show adjustments in operational concepts which have allowed cost containment and a reduction in complexity**
- **Show the relationship between high LCC drivers and critical needs**
- **Identify to oversight authority the areas of trade zones which are available to reduce cost and risk yet still fulfill service needs in capability**

The Basic Team-Based Solution



Fundamental Op/Sys Eng Team Triad

System

An interacting combination of elements to accomplish a defined objective. These include hardware, software, firmware, people, information, techniques, facilities, services, and other support elements.

Operator

A person who is “well-trained and well-motivated” with respect to the operation of a particular system

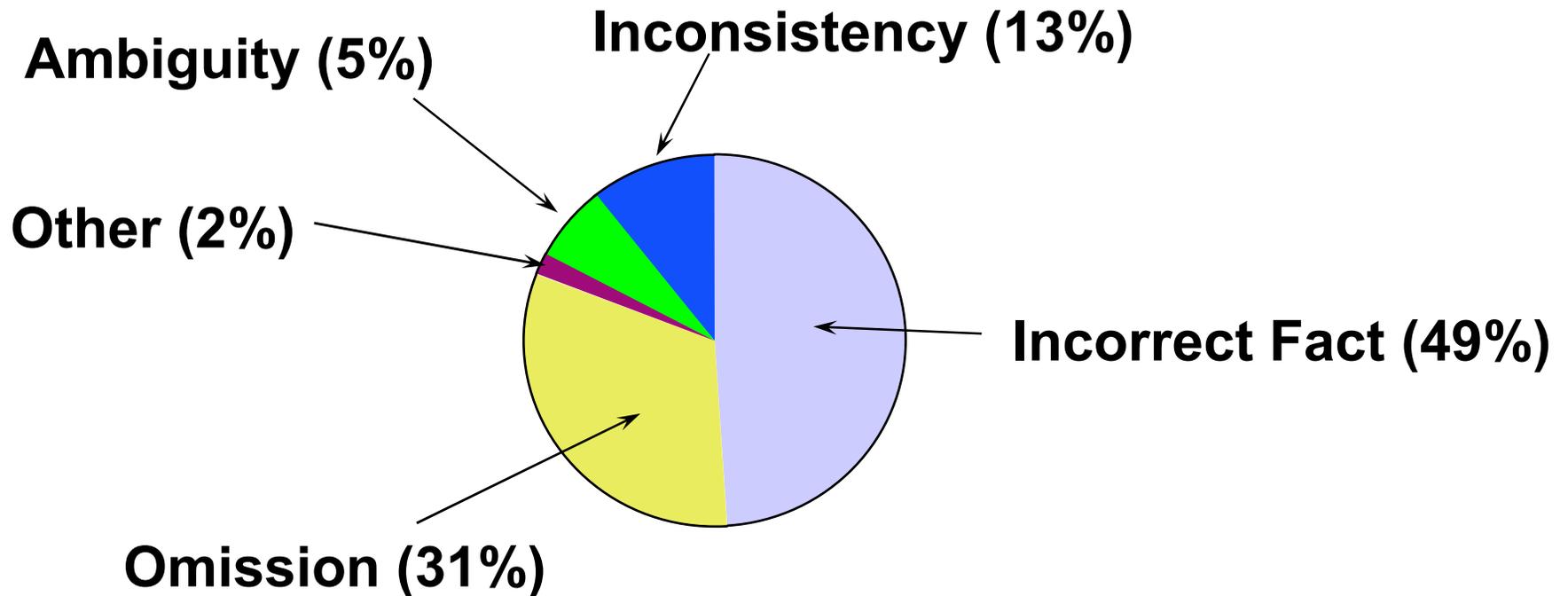
- Has a set of reasonably well specified goals with respect to operation and performance of a system
- Has a set of reasonably well-defined activities with respect to system operation and maintenance

Systems Engineer

A person “well-trained and well motivated” in interdisciplinary approaches to enable the realization of successful systems.

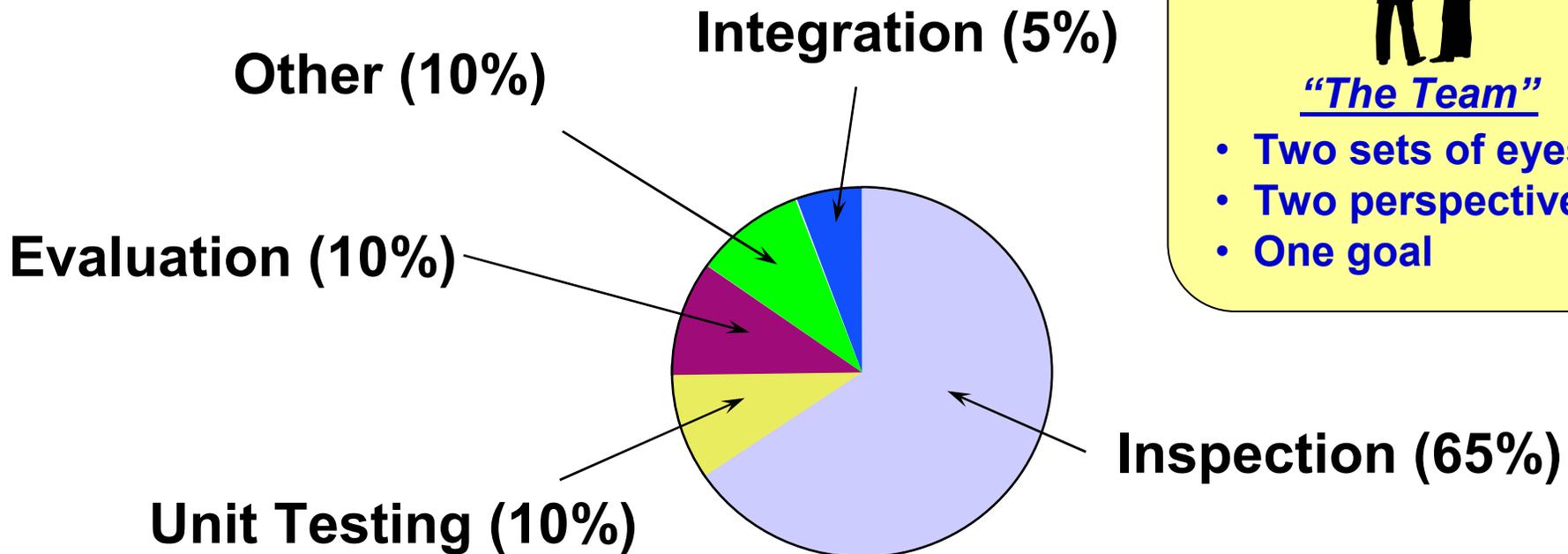
- Selectively uses a logical, systematic set of processes to accomplish Systems Engineering tasks.
- Assesses the arrangement of elements and subsystems and the allocation of functions to meet system requirements

Where Errors Come From



**“Evaluation of a Software Requirements Document by Analysis of Change Data”
by Basili, V. and Weiss, D.
Fifth IEEE International Conference on Software Engineering
1981, Washington D.C.**

How Errors Are Detected



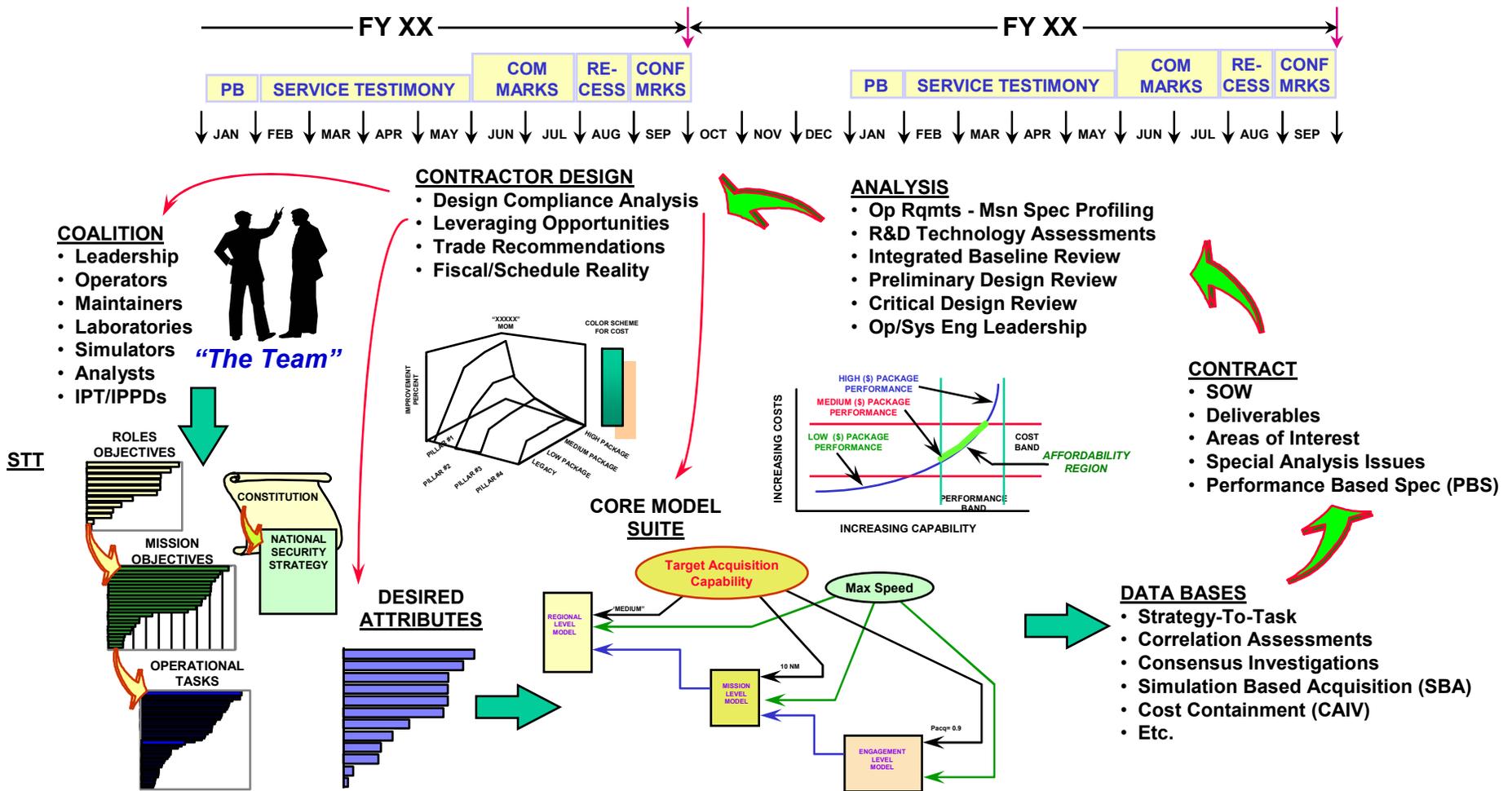
"The Team"

- Two sets of eyes
- Two perspectives
- One goal

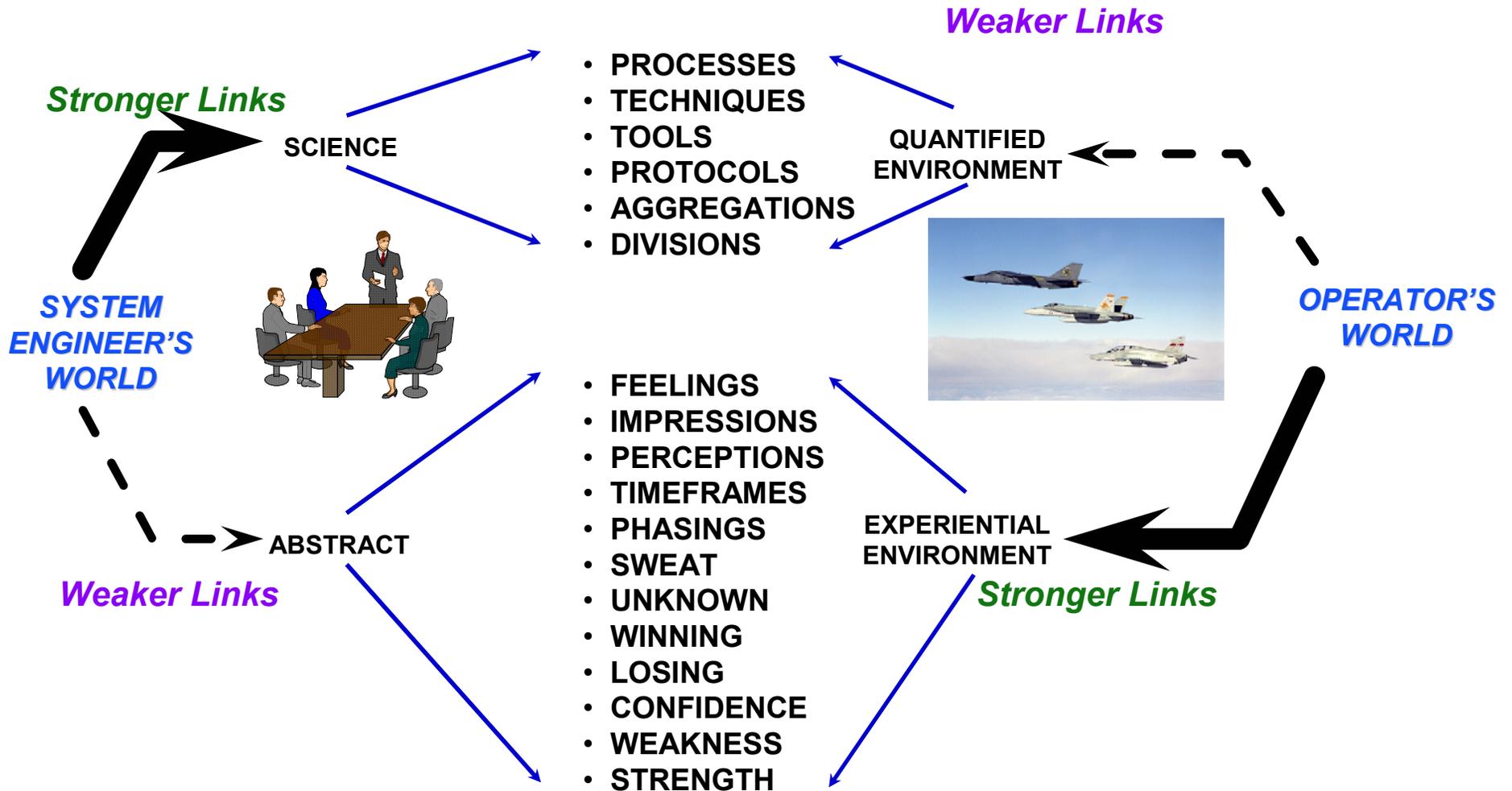
"Software Engineering Management, Personnel, and Methodology"
by Bruggere, T.
Fourth IEEE International Conference on Software Engineering
1979, Washington D.C.

Op/Sys Eng Team Battlespace

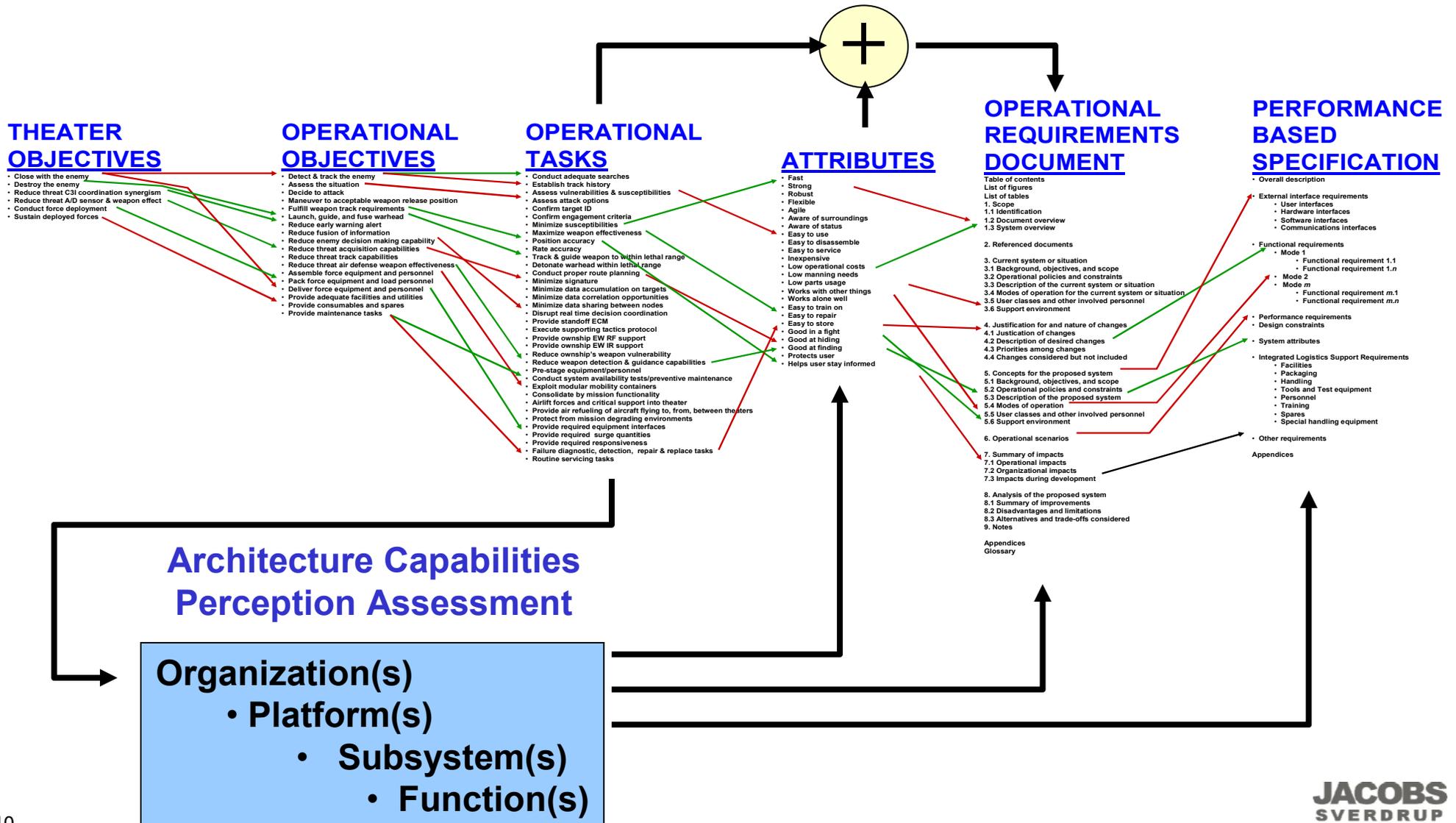
Requirements/acquisition strategy package updated prior to each Budget Review cycle



Synergistic Traits of the Team



The Team Detects Critical Linkages



Operator-System Engineer Product Line

The foundation for formulating answers to questions often starts with discovering the fundamental requirement priorities of the operators

The Operator-System Engineer Team must show where dollars can be saved,...or, where dollars are to be spent, they will have the most impact

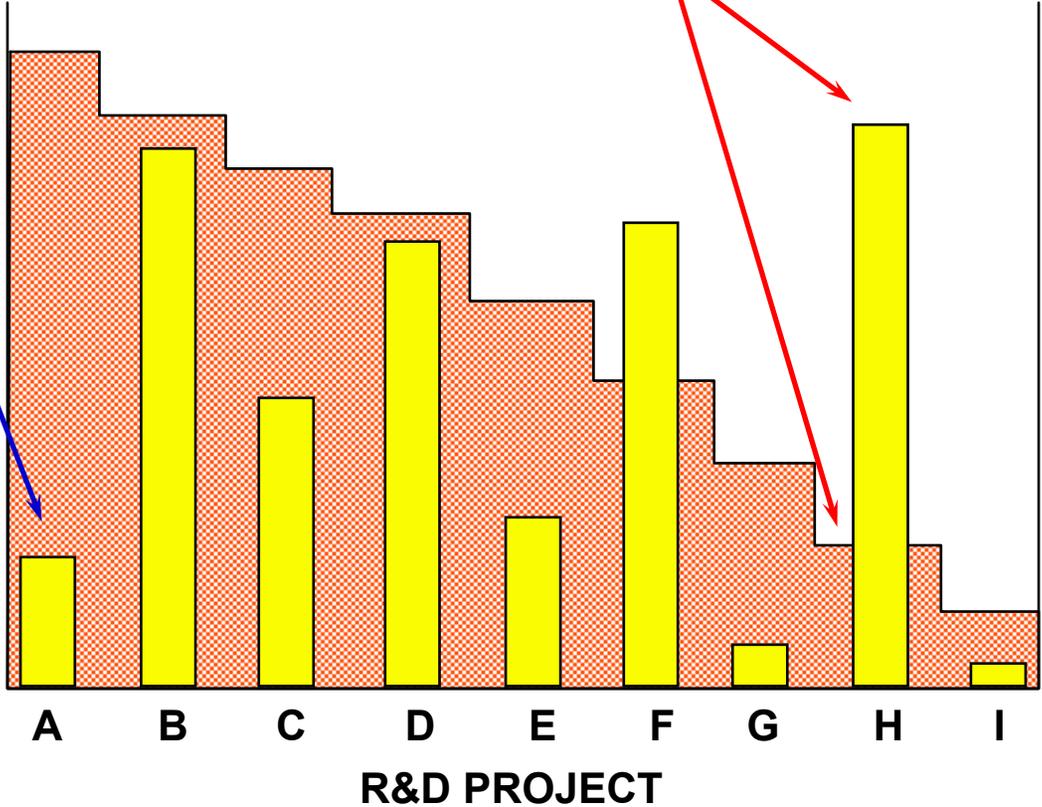
The Team Finds R&D Cost Effectiveness

PROJECT "A"
HIGH UTILITY SCORE,
LOW DOLLAR RQMT

PROJECT "H"
LOW UTILITY SCORE,
HIGH DOLLAR RQMT

PROJECT
QFD SCORE

FUNDS (\$) ALLOCATED TO PROJECT



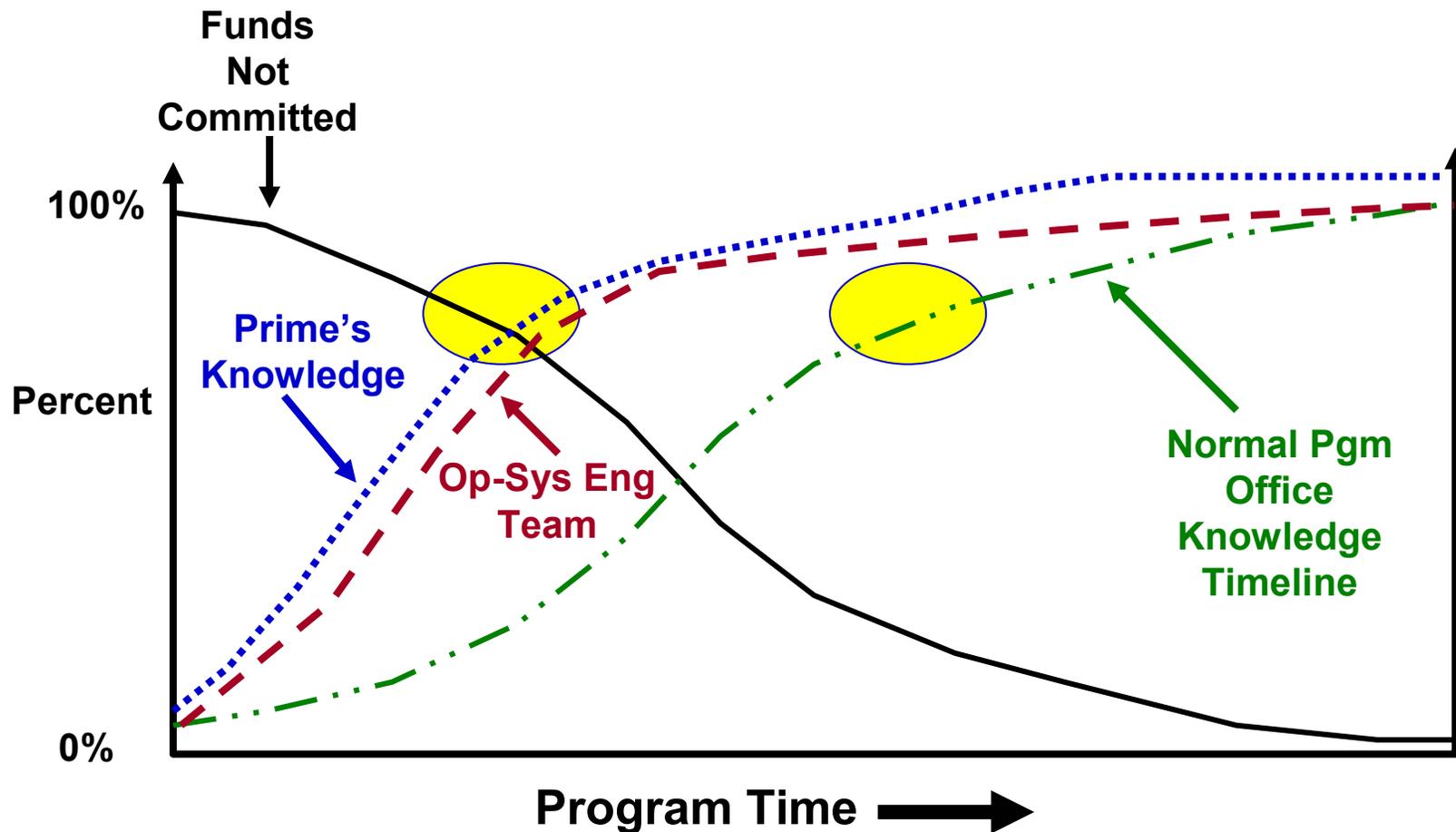
Force Modernization CONOPS

The idea is to devise a way to visualize and integrate into your decision process all the tangible and intangible ideas, concepts and facts that influence your reasoning process.

You do this first,... to give yourself the most comprehensive understanding possible (for knowledge is power), and secondly,... to frame and articulate your solutions and decisions in such a logical manner that you are able to persuade both your colleagues and oversight authorities that your path is the right path.

The Race for Knowledge

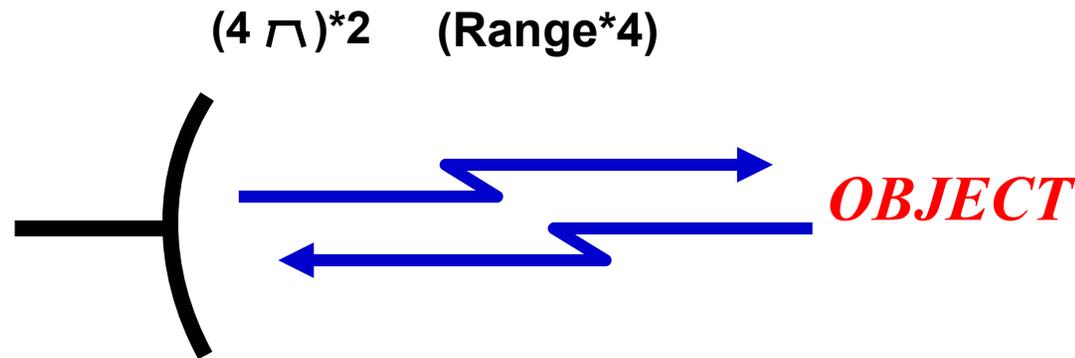
Everyone on a program gets total enlightenment,...the question is will it be before or after your money is committed?



Aggressive Op/Sys Eng Interplay is Key

Simplified Radar Range Equation

Transmitting Antenna Gain	Average Transmitted Power	Radar Cross Section	Effective Antenna Area	Integration Time
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Modernization Knowledge State Options

- **They don't know what they don't know (Unknown Unknowns)**
- **They know they don't know something (Known Unknowns)**
- **They don't understand all they know (constrained awareness)**
- **They understand what they know**

“Unknown Unknowns” State

- Serenity
- Acceptance
- Contentment
- Comfortable routine

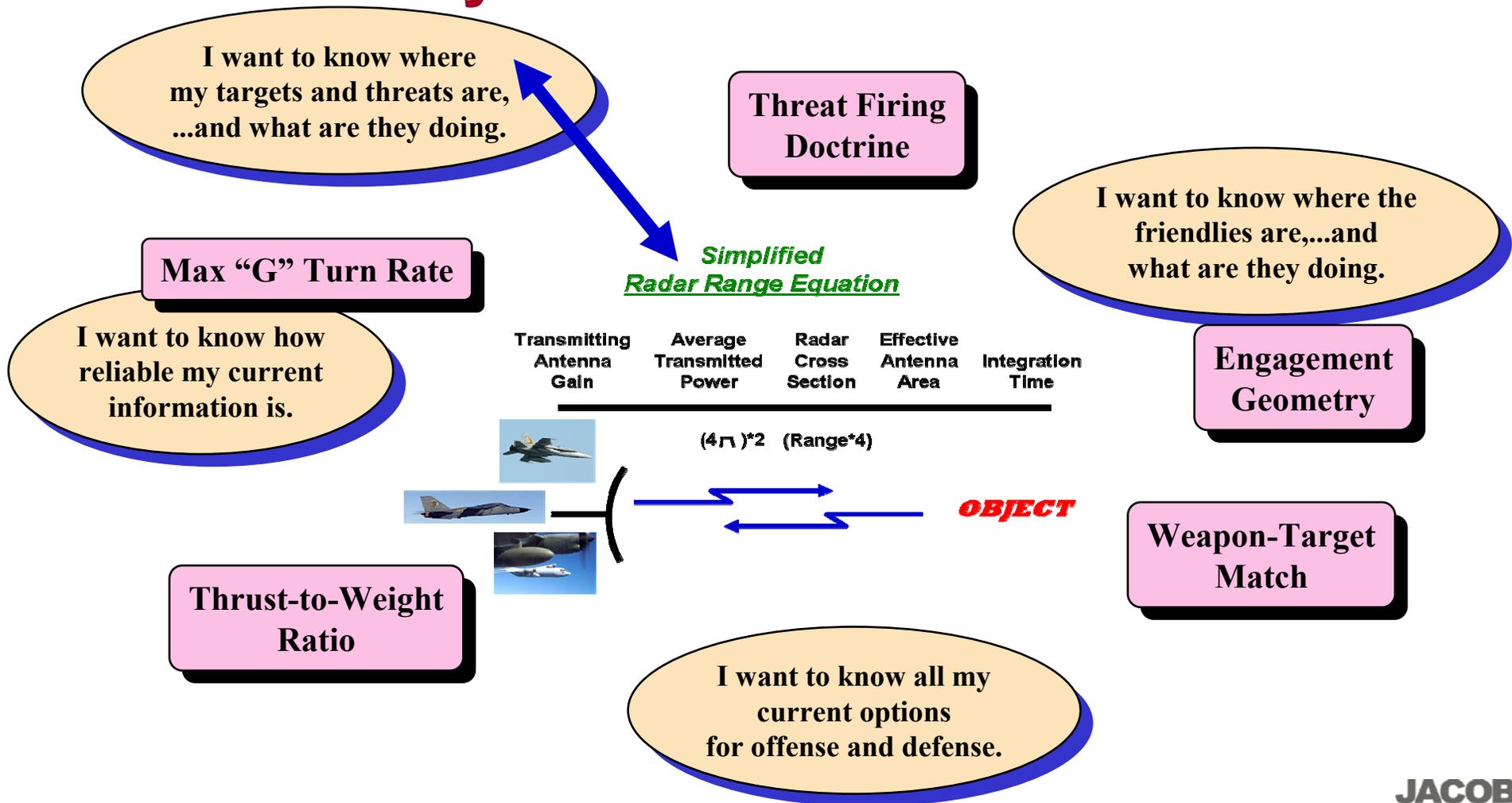
*Strategic planner's
nightmare*

*Acquisition
manager's
nightmare*

- **Low accountability regardless of personal traits**
- **High levels of “reactiveness” to problems**

“Known Unknowns” State

“Why aren’t we better.....”



“Constrained Awareness” State

MANUFACTURER

“We have the solution to your getting better...”

- \$20,000
 - \$16,000
 - \$7,000
 - \$4,000
 - \$1,500
 - \$28,000
 - \$8,000
 - \$1,800
 - \$3,000
 - \$9,000
 - \$5,000
 - \$7,000
 - \$19,000
 - \$7,000
 - \$4,000
 - \$15,000
 - \$28,000
 - \$3,000
 - \$1,000
 - \$8,000
 - \$28,000
 - \$8,000
 - \$1,800
 - \$3,000
 - \$6,000
 - \$3,000
- Constant false alarm rate (CFAR) detector
 - Active guidance
 - Discrete Fourier Transform (DFT)
 - Linear frequency modulation
 - Digital automatic gain control (DAGC)
 - Angle tracking
 - Pulse compression
 - Mainlobe clutter
 - Amplitude weighting
 - Blanking
 - Automatic gain control
 - Multi-look capability
 - Doppler beam sharpening (DBS)
 - Beam steering
 - Interferometry
 - Lowpass filter
 - Injection locking
 - Illumination tapering
 - Electronic scanning
 - Ensemble detection
 - Coherent on receive
 - Envelope detector
 - Clutter referenced MTI
 - Ground moving targets (GMT)
 - Pulse delay ranging
 - Clutter canceller

Radar Improvement Functions

INTRODUCTION TO AIRBORNE RADAR
George W. Stimson
Library of Congress
From Glossary (pg 593)
card number - 83-83041

“Understand” State – Level 1

SUBSYSTEM FUNCTIONS

MISSION SPECTRUM

	Mission 1	Mission 2	Mission 3	Mission 4	Mission 5	Mission 6	Mission 7	Mission 8	Mission 9	Mission 10	Mission 11	Mission 12	Mission 13	Mission 14	Mission 15	Mission 16
Constant false alarm rate (CFAR) detector	3.70	4.30	3.00	7.40	2.90	3.60	4.90	3.20	3.30	1.70	2.50	4.00	2.70	3.20	3.20	2.50
Active guidance	9.10	28.70	13.60	26.40	4.30	25.50	23.30	26.40	12.50	27.30	12.50	14.70	29.40	24.70	16.40	25.30
Discrete Fourier Transform (DFT)	2.40	6.30	4.50	2.40	3.00	4.30	4.70	6.10	5.70	3.20	5.80	5.5	8.90	3.80	4.60	2.20
Linear frequency modulation	4.80	18.40	5.40	16.50	5.90	13.40	9.50	16.40	3.70	16.30	5.70	9.40	16.20	8.50	8.80	9.40
Digital automatic gain control (DAGC)	3.90	3.80	2.60	3.80	3.00	2.90	4.60	7.50	5.30	4.30	4.50	3.60	4.30	2.60	3.20	1.90
Angle tracking	7.80	26.50	6.30	24.60	2.40	23.50	16.70	24.90	15.30	19.90	12.60	15.80	15.50	16.40	7.70	22.30
Pulse compression	7.30	8.30	7.30	9.80	2.00	8.90	7.40	8.80	3.50	8.50	7.10	5.40	8.80	7.80	8.40	9.90
Mainlobe clutter	4.90	27.50	16.90	9.00	8.50	23.10	19.50	27.80	15.30	27.00	8.90	16.90	13.30	24.30	16.90	24.60
Amplitude weighting	5.40	7.80	2.40	8.40	3.00	8.90	8.30	8.30	3.70	7.90	9.40	7.60	9.60	8.40	7.70	8.20
Blanking	3.60	8.80	3.50	114.80	5.40	17.30	7.30	11.40	6.70	14.60	6.40	7.60	16.70	9.50	5.20	14.80
Automatic gain control	3.8	10.40	3.60	13.30	6.90	8.50	2.40	10.50	7.40	9.90	9.90	8.60	9.90	3.50	7.50	6.40
Multi-look capability	9.30	28.90	18.40	27.40	7.90	24.80	14.70	25.70	17.50	27.80	12.10	18.40	16.70	17.30	12.40	27.10
Doppler beam sharpening (DBS)	3.20	6.40	6.10	5.30	3.00	6.60	6.30	8.30	2.90	7.60	8.70	7.40	6.30	6.20	3.90	5.30
Beam steering	4.30	25.50	13.90	24.30	4.90	25.40	16.80	27.40	7.80	18.30	6.70	18.40	26.70	8.90	18.40	23.50
Interferometry	3.40	16.40	2.80	18.90	4.60	14.50	8.50	17.90	4.20	13.50	7.80	8.50	13.90	9.60	6.30	9.90
Lowpass filter	3.20	13.40	8.90	16.30	8.40	12.70	7.70	12.80	4.50	8.40	4.50	8.90	9.40	6.90	6.30	9.30
Injection locking	4.10	19.40	6.50	18.40	5.30	16.90	13.60	18.90	6.40	12.90	7.40	12.90	18.40	13.60	7.50	17.50
Illumination tapering	3.50	7.60	9.90	4.20	2.40	7.00	4.70	6.70	1.50	7.30	4.90	6.80	7.30	4.80	7.50	9.60
Electronic scanning	5.20	29.10	16.20	28.50	2.10	27.50	19.30	29.20	19.40	28.70	11.90	16.20	26.20	22.80	13.20	25.60
Ensemble detection	3.00	12.80	6.20	11.50	7.40	5.90	4.70	11.90	4.40	5.60	8.40	8.40	6.70	5.30	4.20	5.50
Coherent on receive	8.90	22.10	15.30	19.60	3.3	24.40	15.30	17.50	8.90	17.40	7.30	13.90	16.60	15.60	13.90	19.30
Envelope detector	3.60	9.00	4.50	9.30	7.30	8.70	3.70	8.70	6.30	7.40	7.70	8.80	7.70	7.40	6.30	3.20
Clutter referenced MTI	5.80	26.30	5.30	22.10	3.30	13.90	15.30	9.50	13.40	28.50	11.50	8.70	15.20	19.90	7.90	17.30
Ground moving targets (GMT)	5.80	7.30	4.50	7.10	4.30	6.20	7.50	7.30	2.40	8.90	5.80	4.30	4.30	4.60	3.50	6.60
Pulse delay ranging	5.40	8.30	4.20	10.10	1.00	13.90	5.60	8.10	2.30	9.60	4.50	5.70	7.60	8.70	6.20	13.30
Clutter canceller	2.70	15.50	5.90	12.90	3.90	18.30	19.60	12.30	8.90	16.90	6.30	7.90	14.40	18.30	6.70	13.30

INTRODUCTION TO AIRBORNE RADAR
George W. Stimson
Library of Congress catalog card number - 83-83041
From Glossary (pg 593)

Cell Score = Subsystem Mission Contribution

“Understand” State – Level 2

SUBSYSTEM FUNCTIONS	MISSION SPECTRUM															
	Mission 1	Mission 2	Mission 3	Mission 4	Mission 5	Mission 6	Mission 7	Mission 8	Mission 9	Mission 10	Mission 11	Mission 12	Mission 13	Mission 14	Mission 15	Mission 16
Constant false alarm rate (CFAR) detector	3.70	4.30	3.00	7.40	2.90	3.60	4.90	3.20	3.30	1.70	2.50	4.00	2.70	3.20	3.20	2.50
Active guidance	9.10	28.70	13.60	26.40	4.30	25.50	23.30	26.40	12.50	27.30	12.50	14.70	29.40	24.70	16.40	25.30
Discrete Fourier Transform (DFT)	2.40	6.30	4.50	2.40	3.00	4.30	4.70	6.10	5.70	3.20	5.80	5.5	8.90	3.80	4.60	2.20
Linear frequency modulation	4.80	18.40	5.40	16.50	5.90	13.40	9.50	16.40	3.70	16.30	5.70	9.40	16.20	8.50	8.80	9.40
Digital automatic gain control (DAGC)	3.90	3.80	2.60	3.80	3.00	2.90	4.60	7.50	5.30	4.30	4.50	3.60	4.30	2.60	3.20	1.90
Angle tracking	7.80	26.50	6.30	24.60	2.40	23.50	16.70	24.90	15.30	19.90	12.60	15.80	15.50	16.40	7.70	22.30
Pulse compression	7.30	8.30	7.30	9.80	2.00	8.90	7.40	8.80	3.50	8.50	7.10	5.40	8.80	7.80	8.40	9.90
Mainlobe clutter	4.90	27.50	16.90	9.00	8.50	23.10	19.50	27.80	15.30	27.00	8.90	16.90	13.30	24.30	16.90	24.60
Amplitude weighting	5.40	7.80	2.40	8.40	3.00	8.90	8.30	8.30	3.70	7.90	9.40	7.60	9.60	8.40	7.70	8.20
Blanking	3.60	8.80	3.50	114.80	5.40	17.30	7.30	11.40	6.70	14.60	6.40	7.60	16.70	9.50	5.20	14.80
Automatic gain control	3.8	10.40	3.60	13.30	6.90	8.50	2.40	10.50	7.40	9.90	9.90	8.60	9.90	3.50	7.50	6.40
Multi-look capability	9.30	28.90	18.40	27.40	7.90	24.80	14.70	25.70	17.50	27.80	12.10	18.40	16.70	17.30	12.40	27.10
Doppler beam sharpening (DBS)	3.20	6.40	6.10	5.30	3.00	6.60	6.30	8.30	2.90	7.60	8.70	7.40	6.30	6.20	3.90	5.30
Beam steering	4.30	25.50	13.90	24.30	4.90	25.40	16.80	27.40	7.80	18.30	6.70	18.40	26.70	8.90	18.40	23.50
Interferometry	3.40	16.40	2.80	18.90	4.60	14.50	8.50	17.90	4.20	13.50	7.80	8.50	13.90	9.60	6.30	9.90
Lowpass filter	3.20	13.40	8.90	16.30	8.40	12.70	7.70	12.80	4.50	8.40	4.50	8.90	9.40	6.90	6.30	9.30
Injection locking	4.10	19.40	6.50	18.40	5.30	16.90	13.60	18.90	6.40	12.90	7.40	12.90	18.40	13.60	7.50	17.50
Illumination tapering	3.50	7.60	9.90	4.20	2.40	7.00	4.70	6.70	1.50	7.30	4.90	6.80	7.30	4.80	7.50	9.60
Electronic scanning	5.20	29.10	16.20	28.50	2.10	27.50	19.30	29.20	19.40	28.70	11.90	16.20	26.20	22.80	13.20	25.60
Ensemble detection	3.00	12.80	6.20	11.50	7.40	5.90	4.70	11.90	4.40	5.60	8.40	8.40	6.70	5.30	4.20	5.50
Coherent on receive	8.90	22.10	15.30	19.60	3.3	24.40	15.30	17.50	8.90	17.40	7.30	13.90	16.60	15.60	13.90	19.30
Envelope detector	3.60	9.00	4.50	9.30	7.30	8.70	3.70	8.70	6.30	7.40	7.70	8.80	7.70	7.40	6.30	3.20
Clutter referenced MTI	5.80	26.30	5.30	22.10	3.30	13.90	15.30	9.50	13.40	28.50	11.50	8.70	15.20	19.90	7.90	17.30
Ground moving targets (GMT)	5.80	7.30	4.50	7.10	4.30	6.20	7.50	7.30	2.40	8.90	5.80	4.30	4.30	4.60	3.50	6.60
Pulse delay ranging	5.40	8.30	4.20	10.10	1.00	13.90	5.60	8.10	2.30	9.60	4.50	5.70	7.60	8.70	6.20	13.30
Clutter canceller	2.70	15.50	5.90	12.90	3.90	18.30	19.60	12.30	8.90	16.90	6.30	7.90	14.40	18.30	6.70	13.30

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Subsystem Mission Contribution

1 - <10 = White
 10 - <20 = Yellow
 20 - <30 = Red

“Understand” State – Level 3

MISSION SPECTRUM

SUBSYSTEM FUNCTIONS	MISSION SPECTRUM																
	Mission 1	Mission 11	Mission 9	Mission 7	Mission 14	Mission 16	Mission 10	Mission 2	Mission 8	Mission 4	Mission 6	Mission 13	Mission 12	Mission 15	Mission 3		Mission 5
Constant false alarm rate (CFAR) detector	3.7	2.5	3.3	4.9	3.2	2.5	1.7	4.3	3.2	7.4	3.6	2.7	4.0	3.2	3.0	2.9	56.1
Digital automatic gain control (DAGC)	3.9	4.5	5.3	4.6	2.6	1.9	4.3	3.8	7.5	3.8	2.9	4.3	3.6	3.2	2.6	3.0	61.8
Discrete Fourier Transform (DFT)	2.4	5.8	5.7	4.7	3.8	2.2	3.2	6.3	6.1	2.4	4.3	8.9	5.5	4.6	4.5	3.0	73.4
Doppler beam sharpening (DBS)	3.2	4.2	2.9	6.3	6.2	5.3	7.6	6.4	8.3	5.3	6.6	6.3	7.4	3.9	6.1	3.0	89.0
Amplitude weighting	5.4	5.1	3.7	8.3	8.4	8.2	7.9	7.8	8.3	8.4	8.9	9.6	7.6	7.7	2.4	3.0	110.7
Pulse compression	7.3	7.1	3.5	7.4	7.8	9.9	8.5	8.3	8.8	9.8	8.9	8.8	5.4	8.4	7.3	2.0	119.2
Pulse delay ranging	5.4	4.5	2.3	5.6	8.7	13.3	9.6	8.3	8.1	10.1	13.9	7.6	5.7	6.2	4.2	1.0	114.5
Blanking	3.6	6.4	6.7	7.3	9.5	14.8	14.6	8.8	11.4	12.8	17.3	16.7	7.6	5.2	3.5	5.4	151.6
Clutter canceller	2.7	6.3	8.9	19.6	18.3	13.3	16.9	15.5	12.3	12.9	18.3	14.4	7.9	6.7	5.9	3.9	183.8
Clutter referenced MTI	5.8	11.5	13.4	15.3	19.9	17.3	28.5	26.3	9.5	27.5	13.9	15.2	8.7	7.9	5.3	3.3	229.3
Angle tracking	7.8	12.6	15.3	16.7	16.4	27.3	19.9	26.5	24.9	21.3	23.5	15.5	15.8	7.7	6.3	2.4	259.9
Multi-look capability	9.3	12.1	17.5	14.7	17.3	27.1	27.8	28.9	25.7	29.5	21.9	16.7	18.4	12.4	18.4	7.9	305.6
Active guidance	9.1	12.5	12.5	23.3	24.7	27.4	27.3	28.7	26.4	27.4	23.1	29.4	14.7	16.4	13.6	4.3	320.8
Electronic scanning	5.2	11.9	19.4	19.3	22.8	25.6	28.7	29.1	29.2	28.9	23.1	26.2	16.2	13.2	16.2	2.1	317.1
Mainlobe clutter	4.9	7.4	15.3	19.5	24.3	24.6	27.0	27.5	27.8	9.0	23.1	13.3	16.9	16.9	16.9	8.5	282.9
Beam steering	4.3	6.7	7.8	16.8	8.9	28.5	18.3	25.5	27.4	24.3	22.9	26.7	18.4	18.4	13.9	4.9	273.7
Coherent on receive	8.9	7.3	8.9	15.3	15.6	19.3	17.4	22.1	17.5	19.6	21.5	16.6	13.9	13.9	15.3	3.4	236.5
Injection locking	4.1	7.4	6.4	13.6	13.6	17.5	12.9	19.4	18.9	18.4	16.9	18.4	12.9	7.5	6.5	5.3	199.7
Interferometry	3.4	5.8	4.2	8.5	9.6	9.9	13.5	16.4	17.9	13.2	14.5	13.9	8.5	6.3	2.8	4.6	153.0
Linear frequency modulation	4.8	5.7	3.7	9.5	8.5	9.4	16.3	18.4	16.4	11.7	13.4	16.2	9.4	8.8	5.4	5.9	163.5
Lowpass filter	3.2	4.5	4.5	7.7	6.9	9.3	8.4	13.4	12.8	12.9	12.7	9.4	8.9	6.3	8.9	8.4	138.2
Automatic gain control	3.8	3.5	7.4	2.4	3.5	6.4	9.9	10.4	10.5	10.3	8.5	9.9	8.6	7.5	3.6	6.9	109.3
Ensemble detection	3.0	5.3	4.4	4.7	5.3	5.5	5.6	12.8	11.9	11.5	5.9	6.7	8.4	4.2	6.2	7.4	108.8
Envelope detector	3.6	2.1	6.3	3.7	7.4	3.2	7.4	9.0	8.7	9.3	8.7	7.7	8.8	6.3	4.5	7.3	104.0
Ground moving targets (GMT)	5.8	5.8	2.4	7.5	4.6	6.6	8.9	7.3	7.3	7.1	6.2	4.3	4.3	3.5	4.5	4.3	90.4
Illumination tapering	3.5	4.9	1.5	4.7	4.8	9.6	7.3	7.6	6.7	4.2	7.0	7.3	6.8	7.5	2.5	2.4	88.3
	124.3	173.4	193.2	271.9	282.6	345.9	359.4	398.8	373.5	359.0	351.5	332.7	254.3	213.8	190.3	116.5	

1 - <10 = White
 10 - <20 = Yellow
 20 - <30 = Red

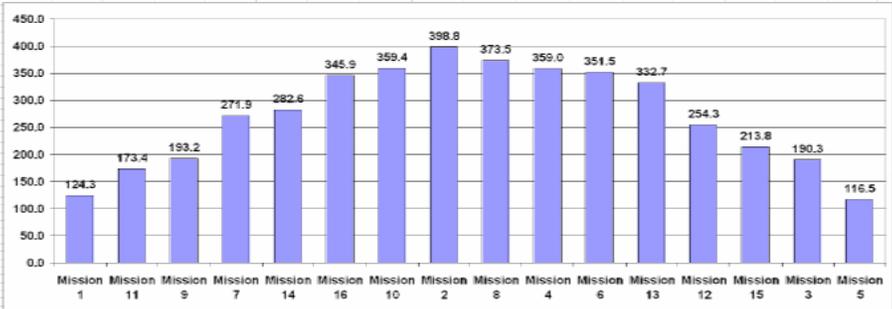
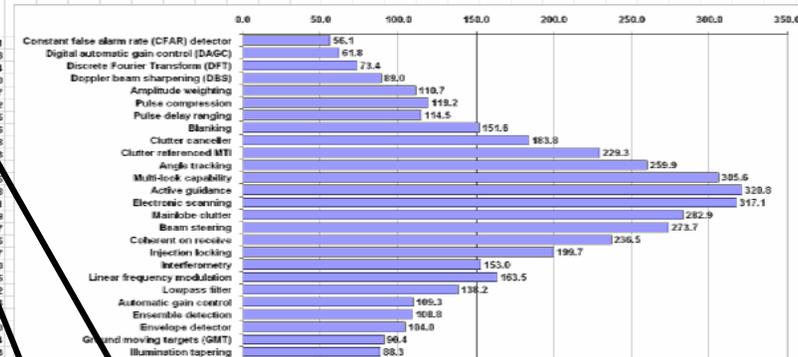
Subsystem Mission Contribution

INTRODUCTION TO AIRBORNE RADAR
 George W. Stimson
 Library of Congress catalog card number - 83-83041
 From Glossary (pg 593)

Decision Quality “Understanding”

MISSION SPECTRUM

SUBSYSTEM FUNCTIONS	Mission 1	Mission 11	Mission 9	Mission 7	Mission 14	Mission 16	Mission 10	Mission 2	Mission 8	Mission 4	Mission 6	Mission 13	Mission 12	Mission 15	Mission 3	Mission 5	
Constant false alarm rate (CFAR) detector	3.7	2.5	3.3	4.9	3.2	2.5	1.7	4.3	3.2	7.4	3.6	2.7	4.9	2	3.0	2.9	56.1
Digital automatic gain control (DAGC)	3.9	4.5	5.3	4.9	2.6	1.9	4.3	3.9	7.5	3.8	2.9	4.3	3.6	4.7	4.5	3.0	61.8
Discrete Fourier Transform (DFT)	2.4	5.8	5.7	4.7	3.8	2.2	3.2	6.3	6.1	2.4	4.3	8.9	5.5	3.6	4.5	3.0	73.4
Doppler beam sharpening (DBS)	3.2	4.2	2.9	6.3	6.2	5.3	7.6	6.4	8.3	5.3	6.6	6.3	7.4	3.9	6.1	3.0	89.0
Amplitude weighting	5.4	5.1	3.7	8.3	6.4	8.2	7.9	7.8	8.3	8.4	8.9	9.6	7.6	2.7	2.4	3.0	116.7
Pulse compression	7.3	7.1	3.5	7.4	7.8	9.9	8.5	8.3	8.6	9.8	9.9	8.6	5.4	8.4	7.3	2.0	119.2
Pulse delay ranging	5.4	4.5	2.3	5.6	6.7	11.3	8.6	8.3	8.1	10.1	13.9	7.6	5.7	6.2	4.2	1.0	114.5
Blanking	3.6	6.4	6.7	7.3	9.5	14.8	14.6	8.8	11.4	12.8	17.3	16.7	7.6	5.2	3.5	5.4	114.6
Clutter canceller	2.7	6.3	8.9	19.6	18.3	13.3	16.9	15.5	12.3	12.9	18.3	14.4	7.9	6.7	5.9	3.9	114.8
Clutter referenced MTI	5.8	11.5	13.4	15.3	19.9	17.3	26.6	26.3	8.5	27.5	13.9	15.2	8.7	7.8	5.3	3.3	228.9
Angle tracking	7.9	12.6	15.3	16.7	16.4	23.2	19.9	20.4	24.8	21.3	23.6	15.5	15.8	7.7	6.3	2.4	256.9
Multi-look capability	9.3	12.1	17.5	14.7	17.3	22.1	27.8	28.6	25.7	26.5	21.8	16.7	10.4	12	11.1	2.5	305.9
Active guidance	9.1	12.5	12.5	23.3	24.7	27.4	27.3	28.7	28.4	27.4	23.1	28.4	14.7	16.2	13.6	4.3	328.8
Electronic scanning	5.2	11.9	19.4	19.3	22.8	25.8	29.7	29.1	23.2	28.9	23.1	28.2	16.2	13.2	16.2	2.1	317.1
Mainlobe clutter	4.9	7.4	15.3	18.5	19.6	24.4	29.6	27.5	27.8	9.8	22.1	13.3	16.9	16.9	15.9	8.5	282.9
Beam steering	4.3	6.7	7.8	16.6	8.9	28.5	16.3	25.1	27.4	28.8	22.8	16.7	10.4	16.4	13.9	4.8	273.7
Coherent on receive	8.9	7.3	6.8	15.3	15.6	19.3	17.4	22.1	17.5	19.6	21.5	16.6	13.9	13.8	15.3	3.4	236.5
Injection locking	4.1	7.4	6.4	13.6	13.6	17.5	12.9	19.4	18.9	16.4	16.9	18.4	12.9	7.5	6.5	5.3	199.7
Interferometry	3.4	5.8	4.2	8.5	9.6	9.9	13.5	16.4	17.9	13.2	14.5	13.9	8.5	8.3	2.8	4.6	153.0
Linear frequency modulation	4.8	5.7	3.7	9.5	8.5	9.4	16.3	19.4	16.4	11.7	13.4	16.2	9.4	8.8	5.4	5.9	193.5
Lowpass filter	3.2	4.5	4.5	7.7	6.9	9.3	8.4	13.4	12.9	12.9	12.7	9.4	8.9	6.3	5.9	8.4	138.2
Automatic gain control	3.8	3.5	7.4	2.4	3.5	6.4	9.9	10.4	10.5	10.3	8.5	9.9	8.6	7.5	3.6	6.9	109.3
Ensemble detection	3.0	5.3	4.4	4.7	5.3	5.5	5.6	12.8	11.9	11.5	5.9	6.7	8.4	4.2	6.2	7.4	104.0
Envelope detector	3.6	2.1	6.3	3.7	7.2	3.2	7.4	9.9	8.7	9.3	8.7	7.7	8.8	6.3	4.5	7.3	104.0
Ground moving targets (GMT)	5.8	5.8	2.4	7.5	4.6	6.6	8.9	7.3	7.3	7.1	6.2	4.3	4.3	3.5	4.5	4.3	96.4
Illumination tapering	3.5	4.9	1.5	4.7	4.8	9.6	7.3	7.6	6.7	4.2	7.0	7.3	6.8	7.5	2.5	2.4	88.3
	124.3	173.4	193.2	271.9	282.6	345.9	359.4	398.8	373.5	350.0	351.5	332.7	254.3	213.8	190.3	116.5	



- Cost of Functions in the Radar**
- \$20,000 Constant false alarm rate (CFAR) detector
 - \$16,000 Digital automatic gain control (DAGC)
 - \$7,000 Discrete Fourier Transform (DFT)
 - \$4,000 Doppler beam sharpening (DBS)
 - \$1,500 Amplitude weighting
 - \$28,000 Pulse compression
 - \$8,000 Pulse delay ranging
 - \$1,800 Blanking
 - \$3,000 Clutter canceller
 - \$9,000 Clutter referenced MTI
 - \$5,000 Angle tracking
 - \$7,000 Multi-look capability
 - \$19,000 Active guidance
 - \$7,000 Electronic scanning
 - \$4,000 Mainlobe clutter
 - \$15,000 Beam steering
 - \$28,000 Coherent on receive
 - \$3,000 Injection locking
 - \$1,000 Interferometry
 - \$8,000 Linear frequency modulation
 - \$28,000 Lowpass filter
 - \$8,000 Automatic gain control
 - \$1,800 Ensemble detection
 - \$3,000 Envelope detector
 - \$6,000 Ground moving targets (GMT)
 - \$3,000 Illumination tapering

QUESTION

Can you see how the mathematics of the system engineer's analysis enables the warfighter to orient and develop rationale for a desired recommendation?

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Op/Sys Eng Team Lessons Learned

- Team mates must be equally adept and authorized to both persuade and compromise on major issues
- A learning curve period of time is always necessary to preclude forming a hasty fundamental relationship architecture
- Accountability speeds up exposure of the issues and assessment process
- Decisions will always be made with some concerns still unresolved

Summary

- **Manage coalition expectations with facts**
- **Focus on the whole,...not just familiar parts**
- **Identify detailed components and functionality**
- **Recognize restrictions, caveats, assumptions**
- **Recognize the nature of conflicting truths**
- **Perform subject matter analysis & decomposition**
- **Identify metrics and range of value zones**
- **Discriminate between activity,...and actual progress**
- **Discriminate between pgm milestones & sys eng criteria**
- **Hunt down and destroy ambiguity**