



### Challenges: The Stage



Urban











Caves





**Riverine** 

Jungles/Canopy



### Challenges: The Environment





Urban / Cave Warfare Requires Sensors for Detecting the Enemy



Riverine – Limited Access Environment



Excessive Heat, Humidity, and Dust in the Environment



#### Non Line of Sight in Urban Environments





Jungle Canopy –
degraded
mobility, aerial
surveillance,
and
communications



### **Emerging Solutions**









**Persistent ISR to OIF** 









**Microsystems** 

**Family of UGS** 

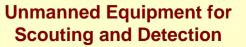


Persistent Threat
Detection System to OIF

Wearable Sensors







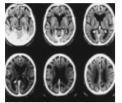


#### A Look into the Future - Basic Research... The Next Generation of Disruptive **Technologies**



### Decade of the 1970's

Structural Imaging Artificial Intelligence



1971 - First Practical X-ray Computed Tomography Image



1970-Shakey the robot Supercomputing



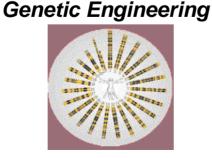
1971 – First 4 Bit Microprocessor in Production



1975 - Cray I Supercomputer

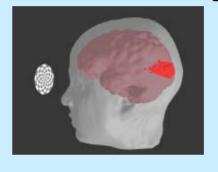


Arcade **Games** 



Today for 2020 and beyond...

Functional Brain Imaging



**Robotics** 



Nanotechnology

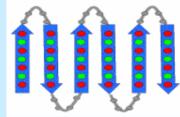


*Immersive* **Environments** 



**Quantum Computing** 

**Biotechnology** 



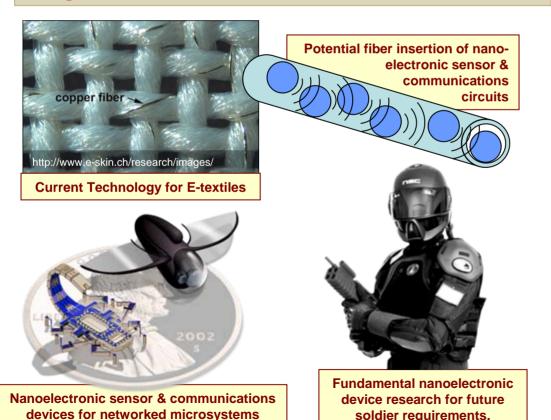


# Nanoelectronics: Devices & Sensors



GOAL: Multifunctional 3-D nanodevice architectures for electronic textiles and networked microsystems for remote sensing applications

**OBJECTIVE:** Fundamental research on integrated nanoelectronic devices



ARL's *in-house* nanoelectronics basic research capability:

- Discrete nanodevice fabrication:
  - Thermal CVD SW-CNT growth
  - Directed nanoscale assembly
  - Nanoscale manipulation
  - 3-D nanoscale architectures
  - Microfluidic channels
- Nanoelectronic device testing:
  - Micro- to nanoscale probing
  - DC to 110 GHz
  - 4.5-475 K
  - fA sensitivity
  - Controlled ambient environments

#### Research focus:

- Amperometric sensors
- Ultra-high frequency (GHz-THz) communications & sensor devices
- Nanoscale thermal management
- Ensemble effects in nanoelectronic devices



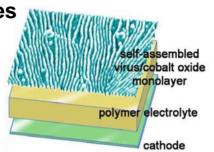
#### **Biomimetics**



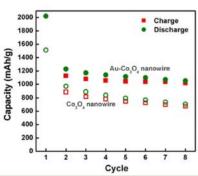
#### **Biologically directed assembly of flexible batteries:**

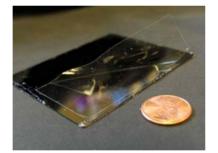
 Use genetically modified viruses to control assembly of cobalt oxide anode

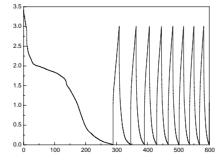
- Polymer electrolyte
- Standard cathodes (metal rod or sheet shown)







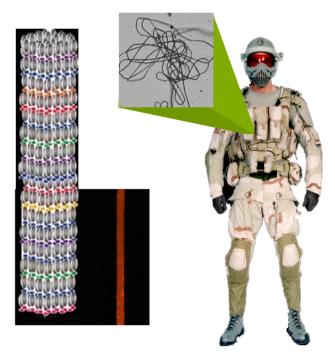




**Higher Capacity, Faster Reaction Rates** 

#### Virus fibers for use in multifunctional textiles:

- Virus-assembled barcodes
- Electro-spun virus fibers for sensor & electronics applications

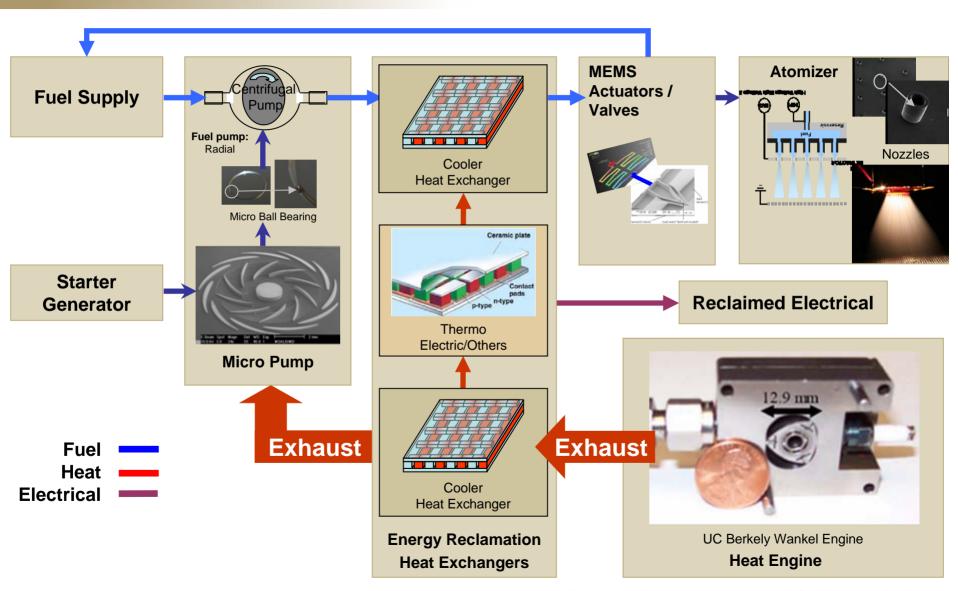


Prof. Angie Belcher, MIT
Dr. Charlene Mello, NSRDEC
TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED, 2



### MEMS for Power & Energy

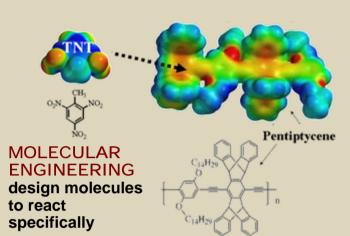






# Chem-Bio Detection and Defense







# SCIENCE Amplifying Fluorescing Polymer (AFP) developed by MIT ISN Prof. Swager glows green, but quenches when TNT is present.



#### MEMS Photo Acoustic Sensor



#### Science Making a Difference for Soldiers: FIDO Explosives Detector





#### DETECTION OPPORTUNITY

Hidden explosives give off traces of chemicals, which may be detected.

FIDO Units in Iraq for Evaluation (2005) – Integrated on robot and handheld



Integration of Chemical /
Biological
Sensing with Electronics.

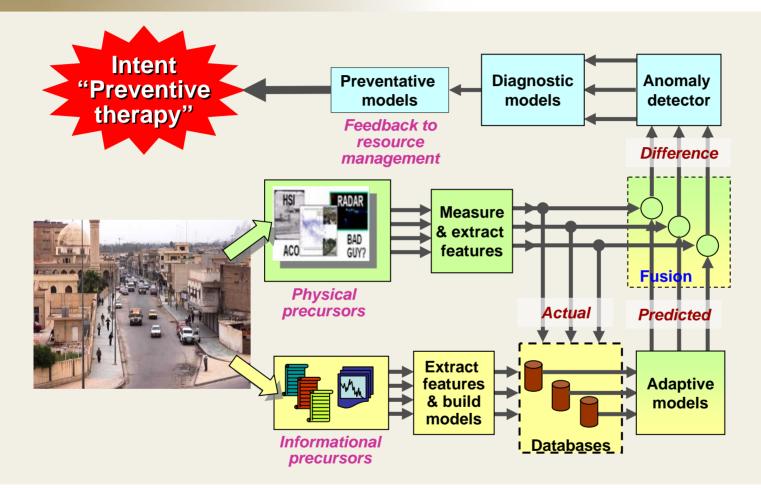
TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED,

**Approved For Public Release** 



# Networked Fusion & Understanding





#### **Characteristics:**

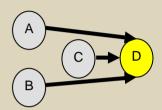
- Scalable
- Expandable
- Adaptive
- Modular

#### **Challenges:**

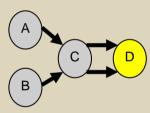
- Network Architecture
- Robust Fusion Engines

- Autonomous Management
- Up-to-date

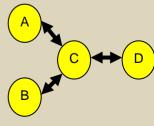
# Data Flow Architecture



Centralized



**Distributed** 



**Decentralized** 



# Shaping the Vision: Operational Scenarios



# Autonomous networked ensembles of multifunctional microsystems for enhanced battlefield situational awareness for the Soldier

### Scenario #1: small unit building search

Autonomous navigation in benign indoor environment with human mission control

# Scenario #2: small unit cave search or demolished building

Autonomous navigation in complex environment with human mission control

## Scenario #3: small unit perimeter defense

Autonomous navigation in complex environment with autonomous mission control



