

#### **Generic Sensor Model**

Stanley N. Hack, D.Sc. Keith Josef, Ph.D. Philip Nation Vinay Shah Paul Juckiewicz Yena Park Jeri Anne Moses Bradly Pietras Walter Osadciw

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LOCKHEED MARTIN

MS-2 Radar Systems Syracuse, New York

The Generic Sensor Model (GSM) is a collection of core software components (classes) used as the foundation for developing radar simulation models.





- Model Description
- Operating Modes
  - o Stand-Alone
  - o System-of-Systems
- Model Components
- Model Flow
- Model Flexibility
  - o Extensibility
  - o Changeable Components
  - o System Adjustable Parameters
- Analyses



The Generic Sensor Model (GSM) is a collection of core software components (classes) used as the foundation for developing radar simulation models.

#### <u>MODEL UTILITY</u>

- Scenario Testing
- Algorithm Testing and Comparison
- Interoperability Evaluation
- Mission Planning

The Generic Sensor Model (GSM) is a collection of core software components (classes) used as the foundation for developing radar simulation models.

#### FEATURES

- Event Driven
- Parameter Based
- Scalable
- Modular
- Extensible Uses Object Oriented Design (C++ based)
- Can Incorporate Tactical Software
- Can be Incorporated into system-of-systems environment (High Level Architecture (HLA) interface)
- Fidelity configurable from low to high
- Unclassified

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The Generic Sensor Model (GSM) is a collection of core software components (classes) used as the foundation for developing radar simulation models. <u>COMPONENTS</u>

- HLA Interface
- Beam Scheduling
- Ray Trace Beam Propagation
- Detection Processing
- Tracking
- Cueing
- Communications
- Data Logging
- Dynamic Environment (Atmosphere, Weather, clutter)
- Terrain maps (DTED)



#### **OPERATING MODES**

#### **Stand-Alone Mode**

- All inputs via XML and data files
- All outputs to log files
- Operates on a single Windows<sup>™</sup>-based platform

#### System-of-Systems Mode

- HLA federated configuration
- Operates in Lockheed Martin's Integrated Missile Defense Testbed (IMDT)



Integrated Missile Defense Testbed (IMDT™)

# IMDT Addresses All Phases of BMDS Mission

- 1. Plan the Battle
- 2. Fight the Battle
- 3. Assess the Battle

- Integrated Defense Planner (IDP)
- IMDT Federation
- Post-Simulation Analyses

IMDT Provides Accurate BMD Planning, Performance And Evaluation Support



Integrated Missile Defense Testbed (IMDT™)

**IMDT Federation** 

- Distributed high-fidelity system-of-systems modeling and simulation testbed for BMD
- HLA and the GV-Net<sup>™</sup> allow distribution of the simulation models to their developers' (subject matter experts') locations
- Includes sensor, weapon systems, communications, and C2BMC high-fidelity models. System controller, analysis suite, and visualization.



#### **IMDT™ Distributed Network**



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#### IMDT Video







#### **Generic Sensor Model Flow**















- Physics-Based Components
  - o Beam scheduling
  - o Beam propagating
  - o Signal calculations
  - o Tracking
- Effects-Based Components
  - o Measured state
  - o Single-scan correlation
  - o Multi-scan correlation



#### **Generic Sensor Model Components**





# **Generic Sensor Model Components**

# Flexibility and Extensibility

#### • Beam Scheduler

- 0 Phase / Rotate
- o Phase / Phase
- o Phase / Phase / Rotate
- o Track Filter

#### • Kalman Filter

- o Interacting Multi-Model (IMM)
- o Non-Linear Ballistic Model
- Model Extensions
  - o External Cue
  - o *IFF*





# **Generic Sensor Model Parameter Examples**

- Sensor
  - o Transmitter power, duty cycle, ...
  - o Antenna size, element count, ...
- Waveforms
  - o **Selection**
  - o Beam Parameters frequency, bandwidth, ...
- Tracker Characteristics
  - o Initial Conditions weights, ...
  - o **Operating Parameters time constants, ...**
- Threats
  - o **Number**
  - o **Characteristics**
  - o **Trajectories**



#### **Generic Sensor Model Analyses**

- Component Performance Analyses
  - 0 Detections SNR, P<sub>D</sub>, ...
  - o Tracker initiate track, drop track, ...
- Algorithm Analyses
  - o Baseline updates
  - o Extended functionality
- Mission Planning
  - o Assumption verification
  - o Parameter development
- Scenario Analyses
  - o Targets number, location, type, ...
  - 0 Assets number, location, type, ...
  - o Communications latency, availability, ...



#### **Generic Sensor Model Analysis Examples**

- Stand-Alone Operating Mode
  - Performance assessment
    - Track initiation
    - Coverage
    - Detection probability
  - Enhanced/Modified Capability evaluation
    - Tracking
- System-of-Systems Operating Mode
  - Interoperability

# Stand-Alone Mode Performance Example



- Individual missiles launched throughout the region of interest
- Missiles impact one of two cities (white, pink)
- Radar at a specified location





# Stand-Alone Mode Performance Example Video



#### NOTE: All data are notional.



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# Stand-Alone Mode Enhanced Capability Example

- N Monte-Carlo runs using Tracker 1
- N Monte-Carlo runs using Tracker 2
- Evaluate
  - Probability of track initiation
  - Track initiation time
  - Track duration
  - Track drop time
  - Track quality
  - ...



NOTE: All data are notional.

#### **Interoperability Video**

#### NOTE: All data are notional.





#### <u>Summary</u>

- Generic Sensor Model (GSM) provides a flexible, extensible framework for instantiating sensor models
  - o **Object-Oriented design**
  - o Parametrically driven
  - o Stand-Alone mode
  - o Federated mode
- Integrated Missile Defense Testbed (IMDT) provides a distributed system-of-systems environment
  - o High-Level Architecture (HLA)
  - o Global Vision Network (GV-Net<sup>™</sup>)
  - o Addresses all phases of the BMD mission
    - Plan the Battle
    - Fight the Battle
    - Assess the Battle

#### Lockheed Martin MS2, Syracuse, NY

