

# System of Systems Engineering Pilot Quality Function Deployment Analysis

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### Introduction

- SoS Systems Engineering project addressing LCS ASW Integration & Mission Capability Evolution
- Pilot project conducted by ASW Systems Engineering Team (ASSET) chaired by PEO-IWS5 SE
- Application of ASN/RDA CHSENG Naval SoS SE Guidelines
- Employed Quality Function Deployment (QFD) for SoS capability evaluation

## LCS ASW SoS Pilot Project

- Proliferation of quiet diesel submarines creates a growing ASW challenge
- ASW inherently a "system-of-systems" enterprise:
  - Platforms
  - Sensors
  - Weapons
  - Command, Control & Communications
- Littoral Combat Ship (LCS) a "transformational" concept:
  - Agile platform
  - Reconfigurable mission packages
  - Extensive use of unmanned vehicles & off-board sensors
  - Spiral development
- Pilot project objectives
  - Address needed ASW capability
  - Apply ASN/RDA SoS SE guidelines
    - Including QFD
  - Show "value added" in SoS acquisition

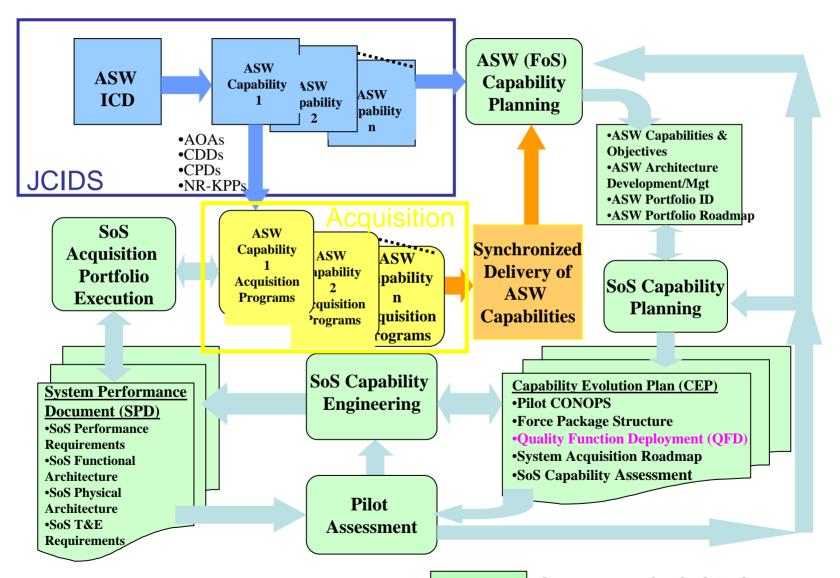


Quiet Diesel Submarine Threat

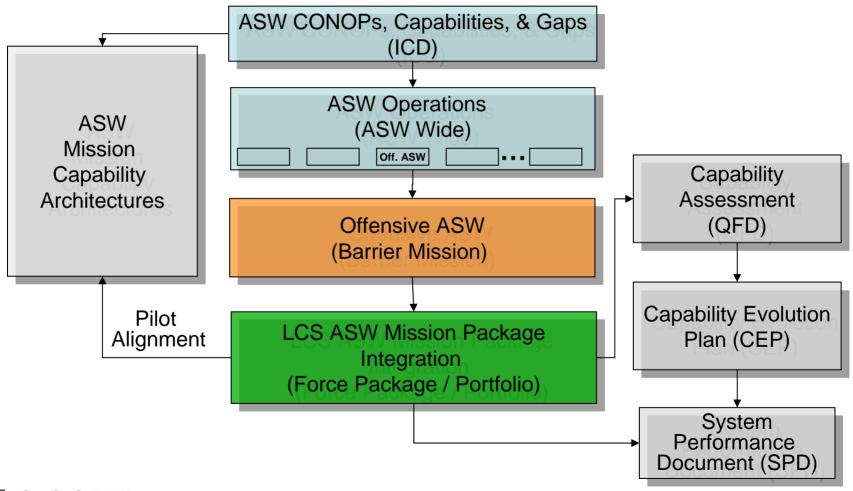


LCS Platform Concepts

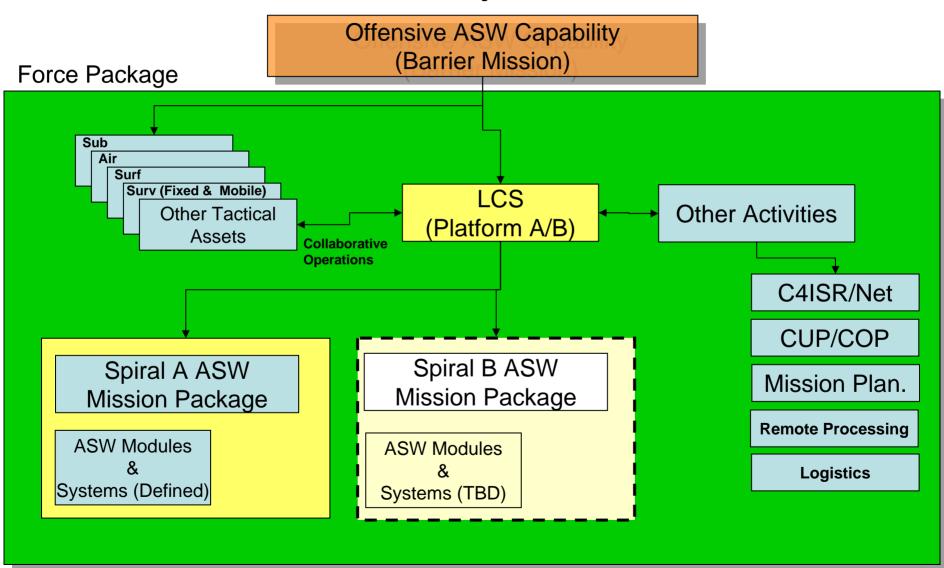
### ASW System of Systems Engineering Process



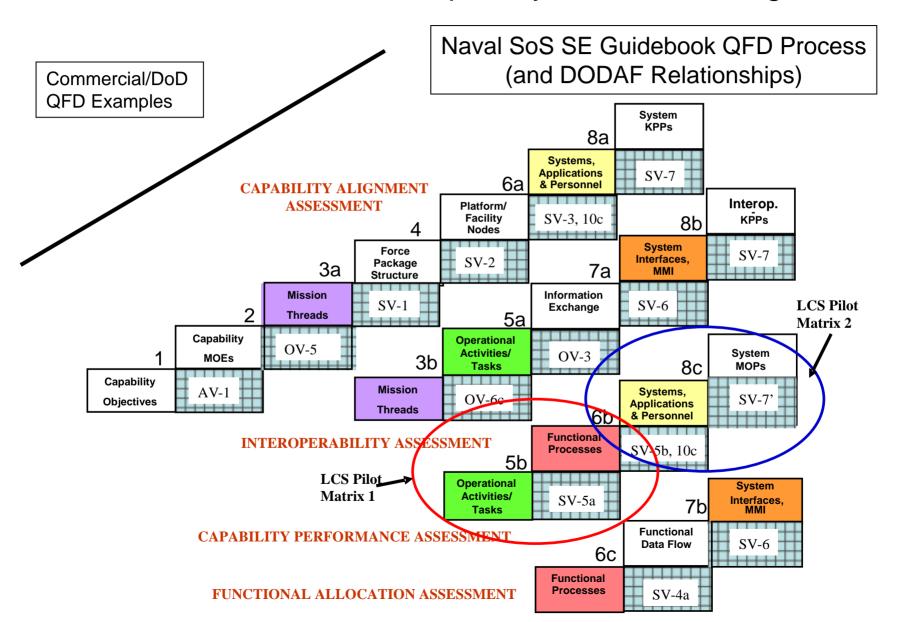
### LCS ASW Mission Context



## LCS Pilot Project Portfolio



### QFD Matrices for Capability-Based Planning



### Pilot QFD Matrices & Workshop

Mission & SoS Systems MCA

Operational & Engineering Metrics (ICD, CDD, Other)



#### Matrix 1

**Matrix 2** 



SoS Functions & Systems

Operational Priority and
Functional & System
Importance
Importance Score



SoS Capability Metrics

Functional Capability
Assessment

Capability Score

Workshop Day 1

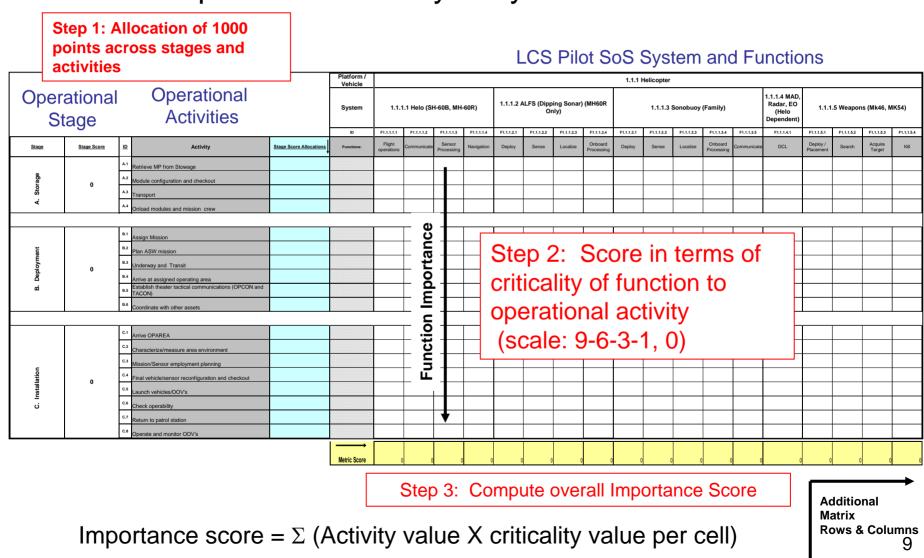
Workshop Day 2

- 2-Day Workshop
- ~30 Subject Matter Experts (SME)
- Divided into four teams
- Operational, technical, engineering expertise

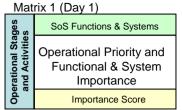


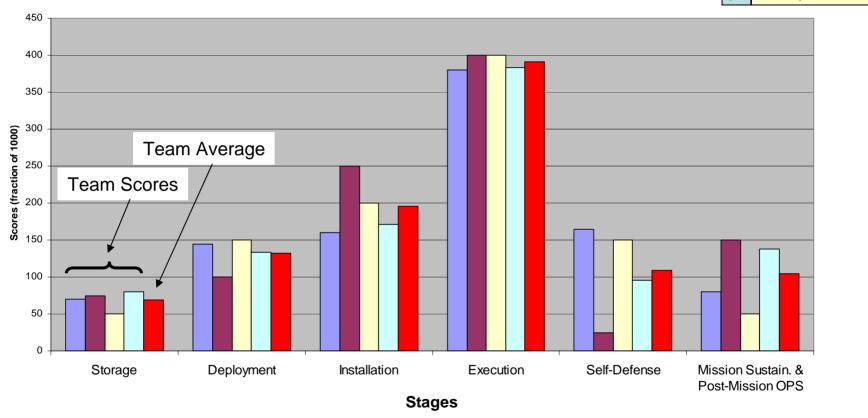


# Matrix 1 (partial) Operational Activity & System Functions



### Stage Score Allocations (Matrix 1)





Team prioritization of operational the six stages (Allocation of 1000 points)

## Operational Activity Priority – *Execution Stage*Rank Ordered Team Averages

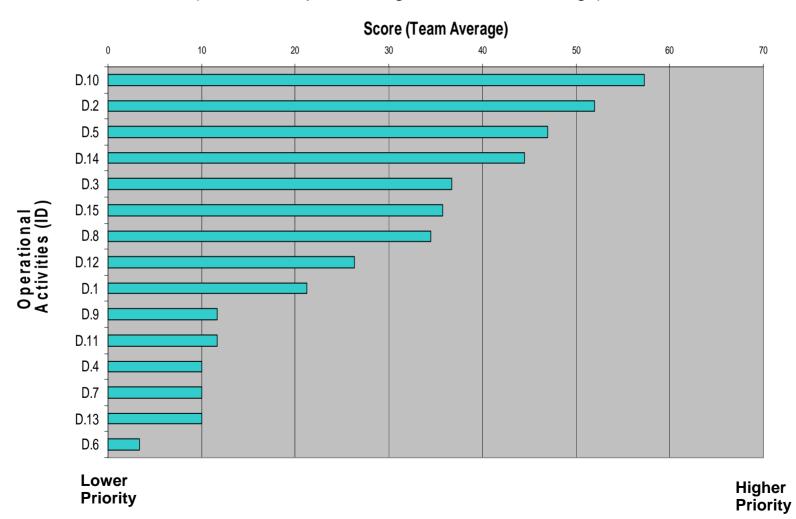
Matrix 1 (Day 1)

Sos Functions & Systems

Operational Priority and
Functional & System
Importance

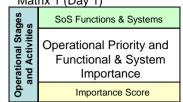
Importance Score

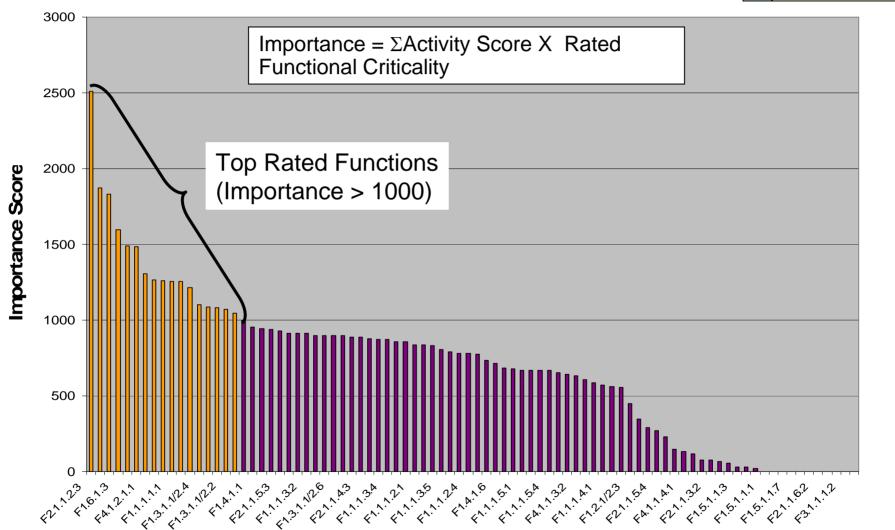
(Allocation of points assigned to Execution Stage)



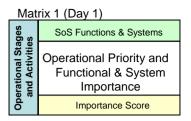
ASW SoS Systems Engineering Pilot – QFD Analysis Matrix 1 (Day 1)

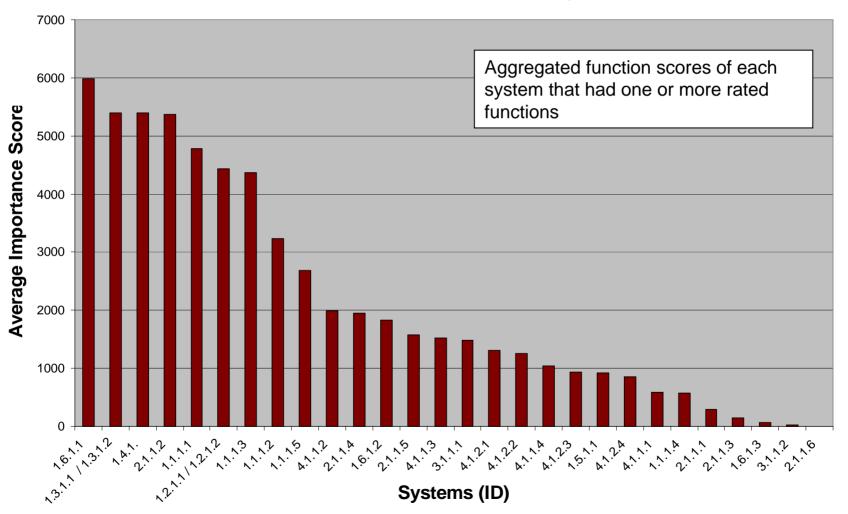
## Function Importance (Execution Stage/Matrix 1) Team Score Averages (Ranked)



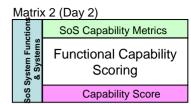


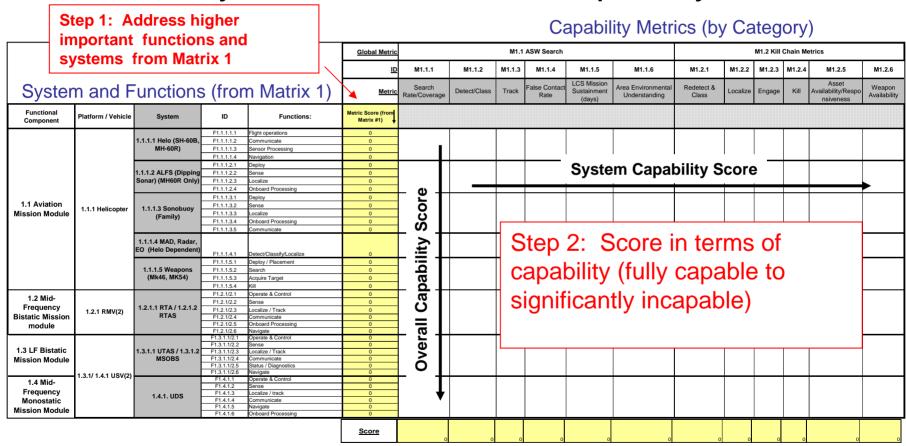
# System Importance (Matrix 1) Execution Stage Ranked Team Averages





# Matrix 2 (partial) System/Functions vs Capability



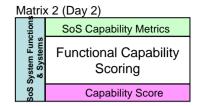


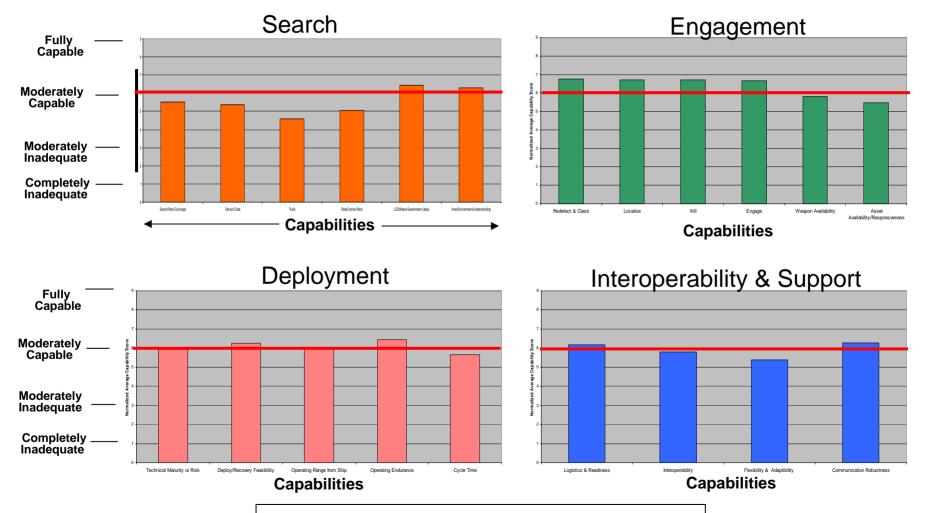
Step 3: Compile overall capability scores

Score =  $\Sigma$  (system function score X adequacy rating value per cell)

Additional Matrix Rows & Columns

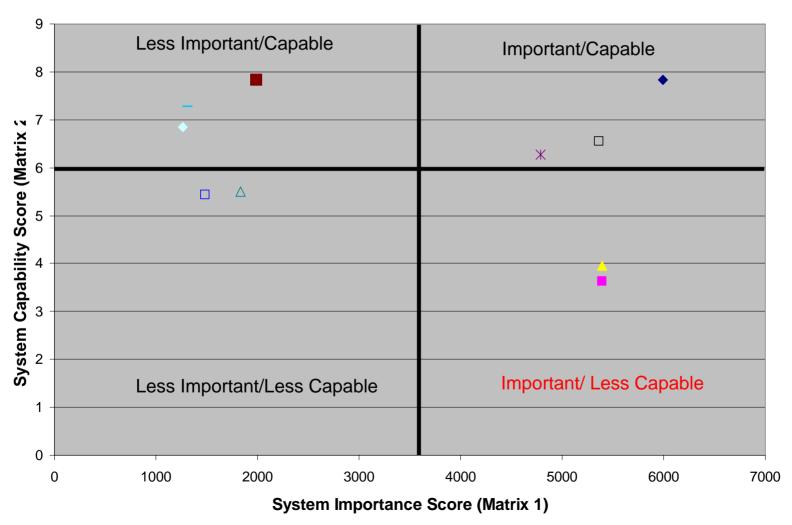
# Capability Scores (Execution Stage)





Score < 6 considered a Capability "gap"

# System Capability vs. Importance (Results of Matrix 1 & 2)



### **QFD Workshop Comments**

- Carefully constructed matrices critical to success
- Manageable matrix size (dimensions)
- A two-day workshop was insufficient
- Dividing participants into four smaller working groups worked well.
- Need clear Concept of Operations and mission threads (ideally an approved set of architectures)
- Description and performance information regarding the systems being rated needed on site
- An experienced QFD workshop facilitator if not facility recommended

### Summary

- LCS ASW Integration Pilot project has been a good example of SoS SE process
  - Portfolio of systems
  - Application of the ASN/RDA SoS SE Guidelines
- The QFD process was adapted from the SoS SE Guide and other QFD applications and was effective in identifying functional priorities and capability gaps across a complex SoS portfolio.
- QFD matrices must be customized to assess the operational, functional, and physical aspects of the Force Package.
- The matrices map to or expand upon the DOD Architecture Framework and thereby are a further use of the architecture products
- The process followed is considered useful, applicable, and adaptable to other SoS capability evolution scenarios.

### Backups

#### LCS Operational Stages and Activities (Matrix 1)

#### **Activity Activity Activity** Defense Conduct area search Module configuration and Self-Threat /Weapons DCL Storage Detect and classify checkout contacts Transport Resolve possible false Evade Onload modules and contacts mission crew Report detections to San and ASWC Post-Refurbish and Redeploy Plan ASW mission Localize, track and OOV's Underway and Transit monitor threat LCS proceeds to sensor **Deployment:** య Arrive at assigned submarines station **Mission Sustainment** S operating area Target reported to sqn Mission OP Final recovery of OOV's and ASWC Conducts turnover with Establish theater tactical Prosecution assets relieving LCS communications (OPCON proceed to target Onboard stowage and TACON) Prosecution assets Coordinate with redetects, classifies and Transit to port (or ship other assets Execution localizes target replenishment sight) Prosecution assets Off-load request and receives Refurbishment Characterize/measure attack authorization Stowage area environment Prosection assets Mission/Sensor launches weapon employment planning Final vehicle/sensor Attack assessment reconfiguration and Reattack if required Installation checkout Prosecution assets return to LCs or patrol Launch station vehicles/OOV's Handoff/receive Check operability targets with other Return to patrol station Operate and monitor assets

Maintain tactical Picture

OOV's

<sup>\*</sup>Ref: LCS ASW Mission Package Overview, PMS 420

### LCS ASW SoS Pilot System and Functions (Matrix 1 & 2)

#### 1. OOV/Sensors

	1.1.1 Helicopter																
1.1.1.1 Helo (SH-60B, MH-60R)			-60R)	1.1.1.2 ALFS (Dipping Sonar) (MH60R Only)			1.1.1.3 Sonobuoy (Family)					1.1.1.4 MAD, Radar, EO (Helo Dependent)	1.1.1.5 Weapons (Mk46, MK54)				
F1.1.1.1.1	F1.1.1.1.2	F1.1.1.1.3	F1.1.1.1.4	F1.1.1.2.1	F1.1.1.2.2	F1.1.1.2.3	F1.1.1.2.4	F1.1.1.3.1	F1.1.1.3.2	F1.1.1.3.3	F1.1.1.3.4	F1.1.1.3.5	F1.1.1.4.1	F1.1.1.5.1	F1.1.1.5.2	F1.1.1.5.3	F1.1.1.5.4
Flight operations	Communicate	Sensor Processing	Navigation	Deploy	Sense	Localize	Onboard Processing	Deploy	Sense	Localize	Onboard Processing	Communicate	DCL	Deploy / Placement	Search	Acquire Target	Kill

	1.2 Mid-Fre	quency Bi	static Miss	sion modul	e		1.3 L	_F Bistatio	Mission Mo	dule		1.4 Mid-Frequency Monostatic Mission Module				1.5 UAV Mission Module					1.6 Mission Package Support										
		1.2.1	RMV(2)			1.3.1/1.4.1 USV(2) 1.5.1 VTUAV							1.6.1 MPSE/COMMS/Storage																		
	1.2	1.2.1.1 RTA / 1.2.1.2 RTAS 1.3.1.1 UTAS / 1.3.1.2 MSOBS 1.4.1. UDS 1.5.1.1 VTUAV P				.5.1.1 VTUAV Payload				1.6.1.1 MPCE				1.6.1.2 OOV COMMS	1.6.1.3 Storage																
F1.2.1/2.1	F1.2.1/2.2	F1.2.1/2.3	F1.2.1/2.4	F1.2.1/2.5	F1.2.1/2.6	F1.3.1.1/2.1	F1.3.1.1/2.2	F1.3.1.1/2.3	F1.3.1.1/2.4	F1.3.1.1/2.5	F1.3.1.1/2.6	F1.4.1.1	F1.4.1.2	F1.4.1.3	F1.4.1.4	F1.4.1.5	F1.4.1.6	F1.5.1.1.1	F1.5.1.1.2	F1.5.1.1.3	F1.5.1.1.4	F1.5.1.1.5	F1.5.1.1.6	F1.5.1.1.7	F1.6.1.1	F1.6.1.2	F1.6.1.3	F1.6.1.4	F1.6.1.5	F1.6.1.2.1	F1.6.1.3.1
Operate & Control	Sense	Localize / Track	Communicate	Onboard Processing	Navigate	Operate & Control	Sense	Localize / Track	Communicate	Status / Diagnostics	Navigate	Operate & Control	Sense	Localize / track	Communicate	Navigate	Onboard Processing	Operate & Control	Communicate/ Relay	Sense	Classify	Localize	Attack?	BDA	Data Fusion & Contact Management	CAUSS	Display	Mission Planning	Sonar Operations	Control & Data Links	Weapons, HAZMAT, CPG

	2. Host Platform																		
2.1.1.1 Crew	'				IS Handling stems	2.1.1.4	2.1.1.4 Mission Package Support Equipment					2.1.1.5 Command & Control				2.1.1.6 Ship Defense			
F2.1.1.1.1	F2.1.1.2.1	F2.1.1.2.2	F2.1.1.2.3	F2.1.1.2.4	F2.1.1.3.1	F2.1.1.3.2	F2.1.1.4.1	F2.1.1.4.2	F2.1.1.4.3	F2.1.1.4.4	F2.1.1.4.5	F2.1.1.5.1	F2.1.1.5.2	F2.1.1.5.3	F2.1.1.5.4	F2.1.1.6.1	F2.1.1.6.2	F2.1.1.6.3	F2.1.1.6.4
Ship Operations	Ship-Ship	Ship-to-Shore	Ship to Off- Board Systems	Ship to Force ASW Assets	MM Deploy Crew	Deploy/Recover MM	MP Control	Data Processing	Display	Mission Planning	Test MP	Mission Planning	Env. Data Gathering	Coordination	Common Processing	Weapon DCL	Counter	Evade	Mission recovery

3.1	3.1 Maintenance and Storage										
3.1.1 MP Shore/IMA/Depot											
3.1.1	.1 MP Shore	e/IMA	3.1.1.2 Depot & OEM								
F3.1.1.1.1	F3.1.1.1.1 F3.1.1.1.2 F3.1.1.1.3										
Train MP personnel	Store & Maintain Equip	Transport MP Equipment	Accept & Refurb Equip								

	4. Theater Assets													
		4.	4.1.2 Other Assets											
4.1.1.1 Network (GIG/Forc eNet)		2 ASW nand & ntrol		Common ture	4.1.1.4	Mission P	ianning	4.1.2.1 P8- A P3-C	4.1.2.2 Force Helo's	4.1.2.3 Other ASW Assets	4.1.2.4 Theater ISR			
F41.1.1.1	F4.1.1.2.1	F4.1.1.2.2	F4.1.1.3.1	F4.1.1.3.2	F4.1.1.4.1	F4.1.1.4.2	F4.1.1.4.3	F4.1.2.1.1	F4.1.2.2.1	F4.1.2.3.1	F4.1.2.4.1			
Communicati ons	ASWC	TASW	Common Tactical Picture	Common Operational Picture	Area assignment	Sensor employment	Mutual Interfeerence	Cooperative ASW	Cooperative ASW	Cooperative ASW	Cueing			

# Capability Performance Metrics (Matrix #2)

		M1.1	<b>ASW Searc</b>	h	M1.2 Kill Chain Metrics							
M1.1.1	M1.1.2	M1.1.3	M1.1.4	M1.1.5	M1.1.6	M1.2.1	M1.2.2	M1.2.3	M1.2.4	M1.2.5	M1.2.6	
Search Rate/Coverage	Detect/Class	Track	False Contact Rate	LCS Mission Sustainment (days)	Area Environmental Understanding	Redetect & Class	Localize	Engage	Kill	Asset Availability/Respo nsiveness	Weapon Availability	

	M2 Syste	em Employr	ment Metrics	M3 SOS Metrics						
M2.1	M2.2	M2.3	M2.4	M2.5	M3.1	M3.2	M3.3	M3.4		
Deploy/Recovery Feasibility	Operating Endurance	Cycle Time	Operating Range from Ship	Technical Maturity or Risk	Communication Robustness	Interoperability	Flexibility & Adaptibility	Logistics & Readiness		

10<sup>th</sup> Annual Systems Engineering Conference Session - T&E in Systems Engineering ASW SoS Systems Engineering Pilot – QFD Analysis