# Agenda



- WPML Background / Overview
- Program Highlights
  - •2.75-inch Rocket Tests in Tank
  - •Subscale Tests in Va Tech Water Tunnel
  - •5-inch Rocket Tests at NSWC Crane Lake Glendora
    - •Restrained
    - •Flyout
- Future Plans

#### **Concentric Canister Launcher (CCL)**

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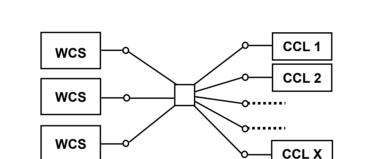
Self-Contained Gas Management

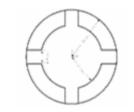
> Distributed Electronic Architecture

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Canister is an All-Up Launcher

#### CCL is a "Plug-n-Play" Launch System, Electronically & Mechanically

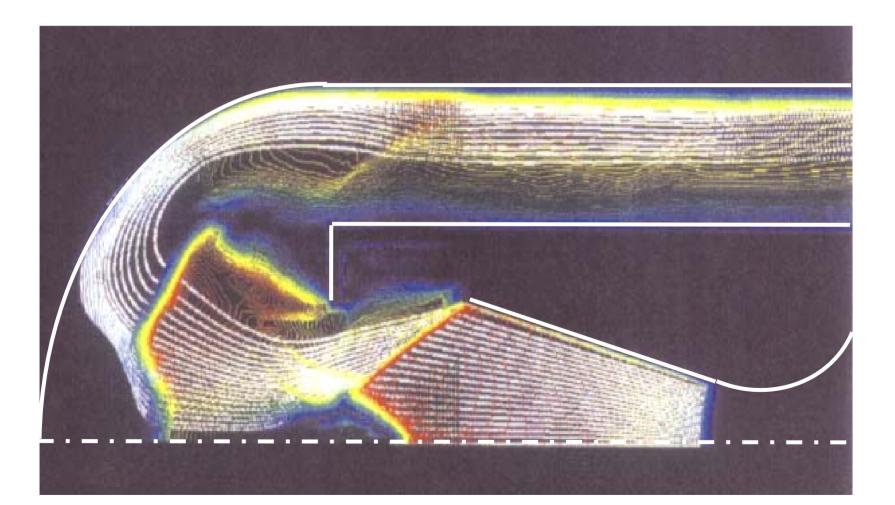






#### CFD Computer Result for Flow of Rocket Exhaust through a CCL





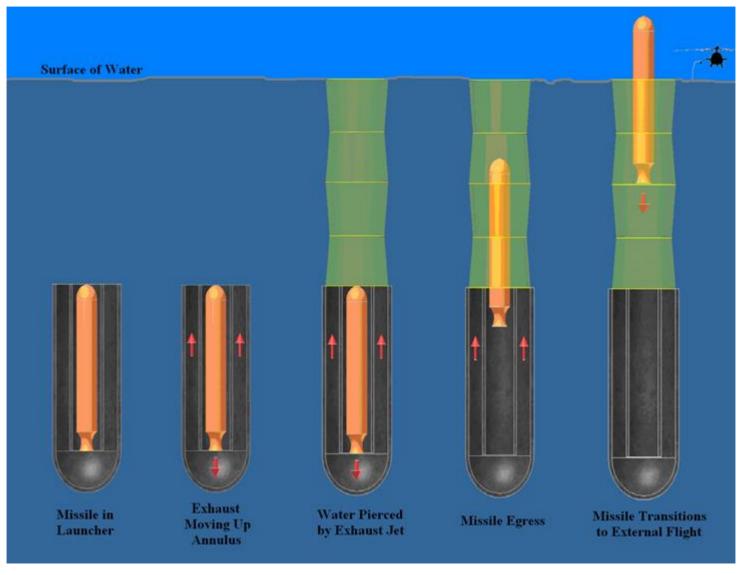
#### **CCL Surface Launch**





#### Water Piercing Missile Launcher Concept





#### **Benefits of WPML Concept**

- Precludes need to pressurize missile for underwater launch
- Any existing service missile can be used without modification

**ESSM** 

**ATACMS** 



PAM





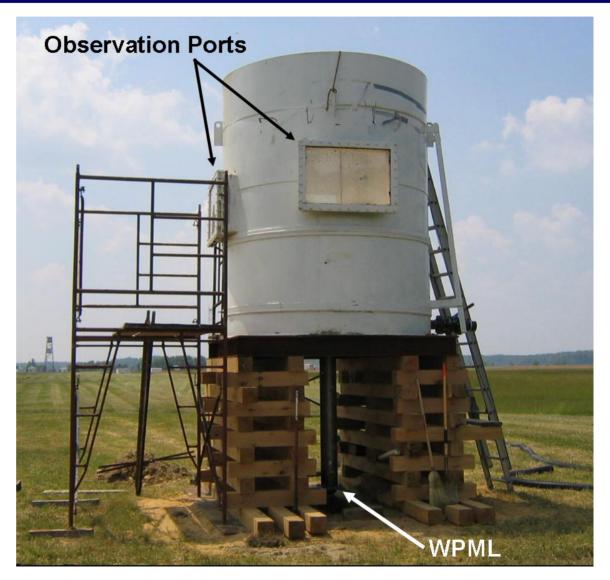


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#### 2.75-inch Rocket Motor Tests

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- CCLs with 7, 8, and 9" outer diameter
- MK66 (2.75") rocket motor as the gas source





#### 2.75-inch Restrained Rocket Motor Test



# 2.75-inch Fly-out Experiment



- Modified 5" Navy Hi-Frag Projectile
- Mk66 Provides Thrust





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#### 2.75-inch Rocket Motor Flyout Test

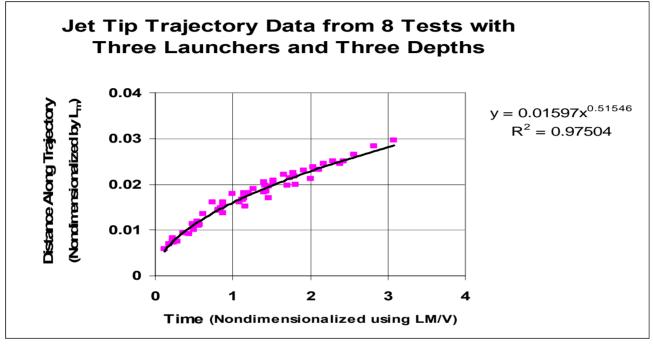




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## Empirical Model for Predicting Jet Tip Trajectory





#### Formula for trajectory from graph:

 $y = 0.01597 x^{0.5146}$ 

Let Z be a coordinate along the axis of the launcher starting at the exit plane and ending at the surface of the water, y (on the graphs above) = Z/Lm

y (on the graphs above) = Z/Lm

Let t be the time in seconds

x (on the graphs above) = t/(Lm/V)

Substitute this into the equation for the trajectory on the graphs:

 $Z/L_m = 0.01597 x^{0.5146} = 0.01597 (tV/Lm)^{.5146}$ 

Solve for Z:

Z=.01597L<sub>m</sub>(tV/Lm)<sup>.5146</sup>

#### Final Formula for a Jet Tip Trajectory



$$Z = 0.01597 L_m \left(\frac{tV}{L_m}\right)^{.5146}$$

Z = Jet tip height above the CCL exit

 $L_m = (\text{Specific momentum flux})^{3/4} / (\text{Specific buoyancy flux})^{1/2}$ , where

Specific momentum flux = Exhaust Area of CCL x Velocity<sup>2</sup>, and

Specific buoyancy flux = g (Volume Flux) (Density of Water-Density of Exhaust)/

(Density of Water), and

Volume Flux = Velocity x Exhaust Area

t = Time in Seconds

V = Exit Velocity

# Agenda



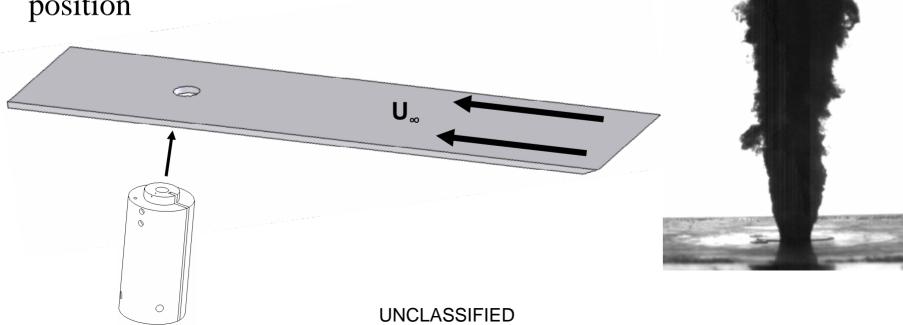
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## Va Tech Water Tunnel Cross Flow Setup



- WPML is flush mounted onto flat plate
- Control of key variables
  - Launcher exit velocity
  - Launch depth
  - Cross flow speed
- Shadowgraph images to record interface position

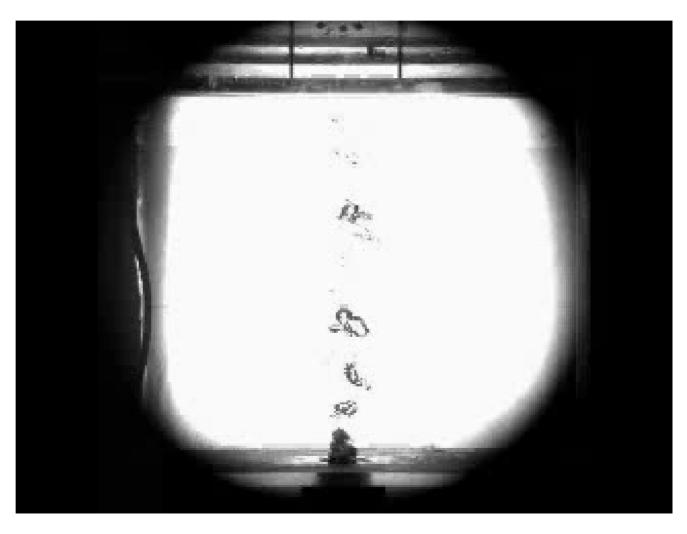




#### UNCLASSIFIED Va Tech Water Tunnel Tests



- Mach # 2.0
- Cross Flow 0 knots
- Time to Pierce - 43ms
- Average Jet Velocity – 31 fps





#### UNCLASSIFIED Va Tech Water Tunnel Tests



- Mach # 2.0
- Cross Flow -1.36 knots
- Time to Pierce - 48ms
- Average Jet Velocity – 28 fps

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## Restrained Rocket Motor Test Series Objective



Objective: Determine the water piercing capability of two different 5-inch diameter rocket motors through restrained firing tests at depths from 10-40 feet

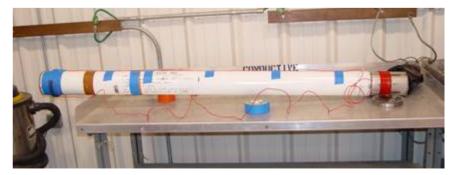
# **Results will be used to update CFD models and scaling laws**

#### **5-Inch Rocket Motors**



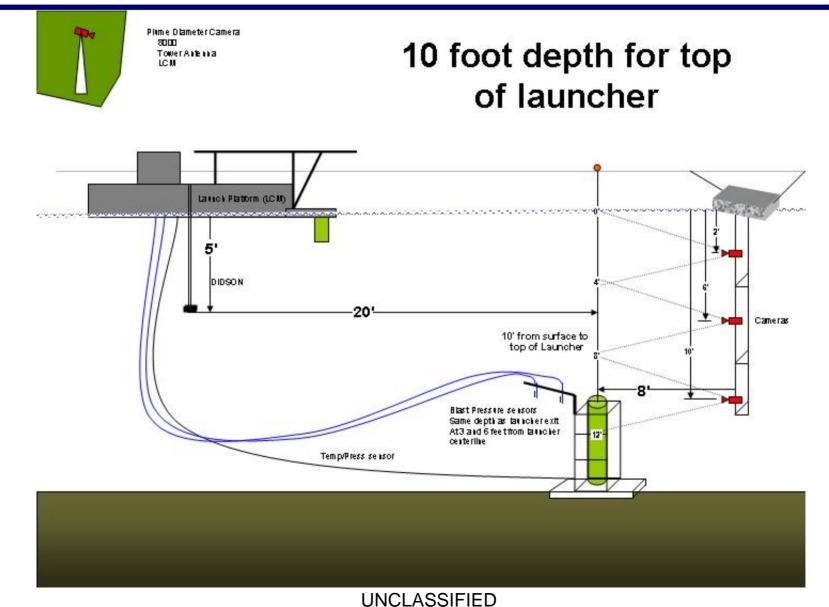
Rocket Motor	Average Thrust (lbf)	Average Pressure (psi)	Burn Time (Seconds)	Nozzle Throat Area (square in)	Avg. Mass Flow Rate (lbm/s)
JATO	2595	1634	1.35	1.09	12.65
ZUNI	5659	1430	1.53	2.92	24.95





#### **Typical Test Setup**





#### **5-Inch Rocket Motor Launchers**

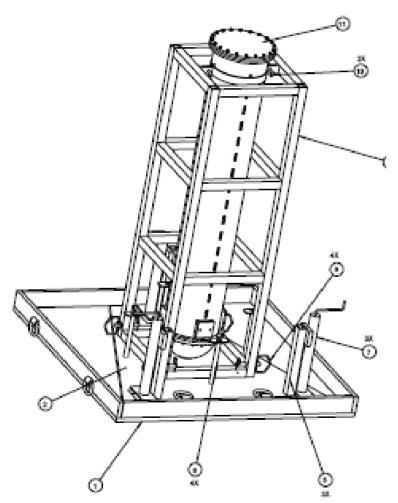




#### Test Hardware Readiness Supporting Test Fixtures



#### **Launcher Cage Platform**





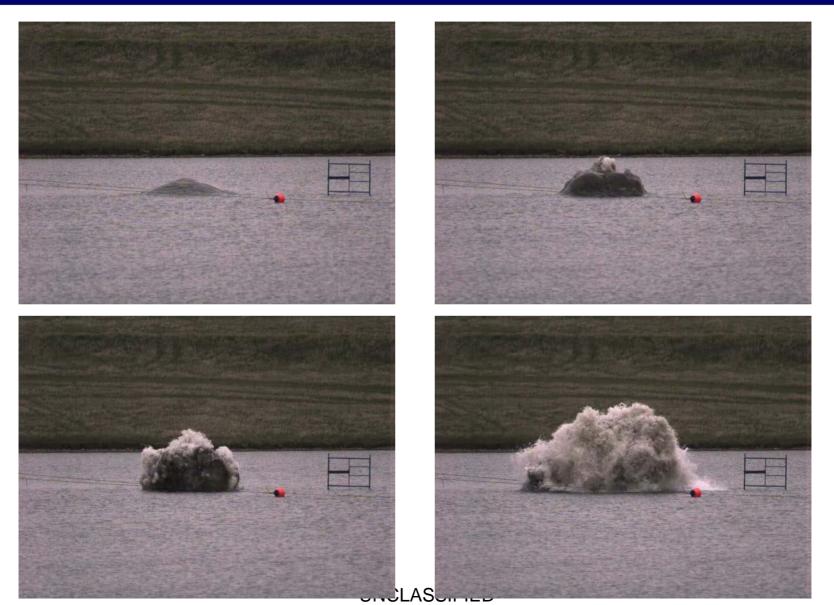
#### **5-inch Rocket Tests Conducted**



Test #	Rocket Motor	Depth (ft)	Pierce? (Y/N)
1	JATO	10	Y
2	JATO	20	Y
3	Zuni	20	Y
4	JATO	27	Y
5	Zuni	32	Y
6	JATO	42	N
7	Zuni	40	Y?
8	JATO w/ Plug Nozzle	40	N
9	Zuni	40	Y
10	Zuni w/ Plug Nozzle	40	Y

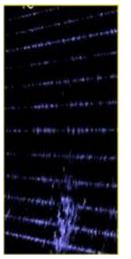
#### Test Results – Zuni at 32 feet Above Water Camera – High Speed



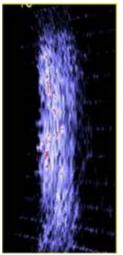


## Test Results – Zuni at 32 feet DIDSON Acoustic Camera

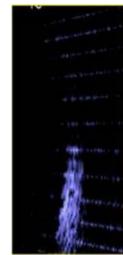




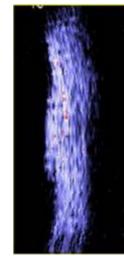
T=0.1667



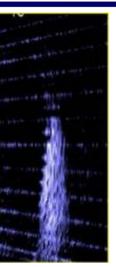
T=1.000



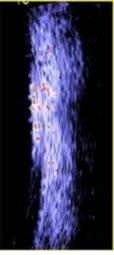
T=0.333



T=1.167

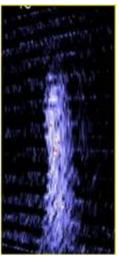


T=0.500

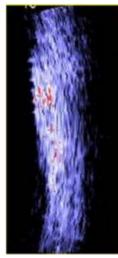


T=1.333

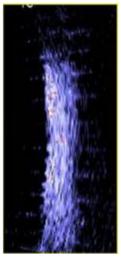
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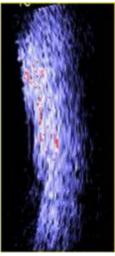
T=0.667



T=1.500



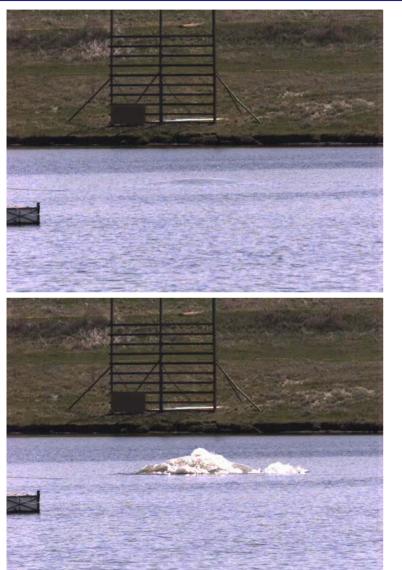
T=0.8333

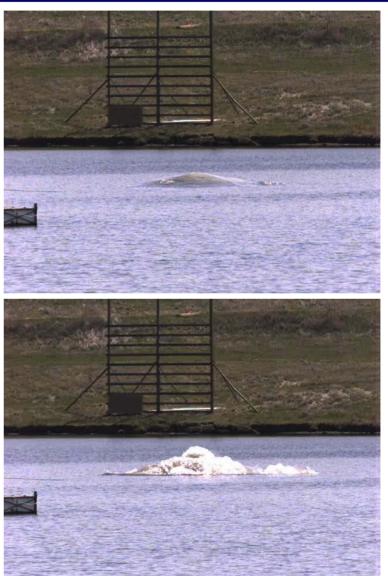


T=1.667

## **Test Results – JATO at 42 feet Above Water Camera – High Speed**

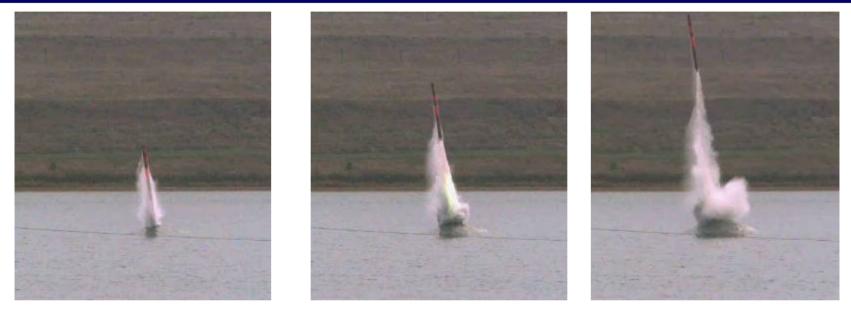






#### **Static Flyout Test – 9/25/07 20 foot depth – JATO Motor**









#### Static Flyout Test – 9/25/07 20 foot depth – JATO Motor

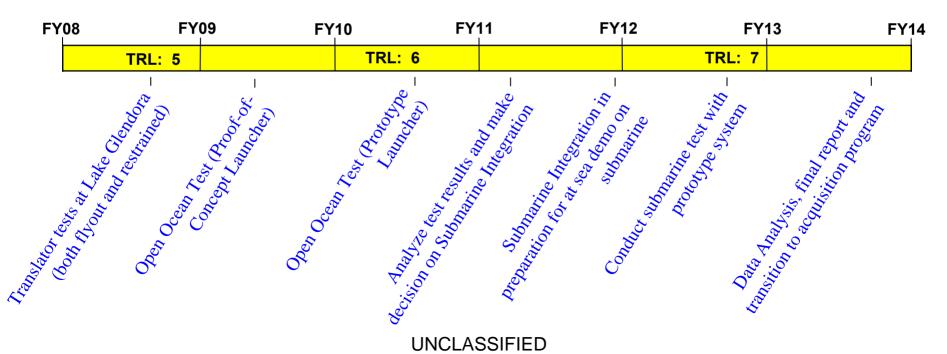




#### **Future Program Plan**



- FY08 Translator Tests at NSWC Crane
- FY09, FY10 Open Ocean Fly Out Tests w/Target
- FY11 Data Analysis, Decision on Submarine Integration
- FY12,13 Submarine Test with Prototype System
- FY14 Data Analysis, Transition to Acquisition Program







# Tests and analysis have shown that the WPML concept is valid

# Continuing to Execute Program Plan FY08 Translator Tests at Lake Glendora FY10 Relevant Environment Test (Underwater Rail at San Clemente Island)

## **Questions?**



