



# Testing the Test Range without Flights

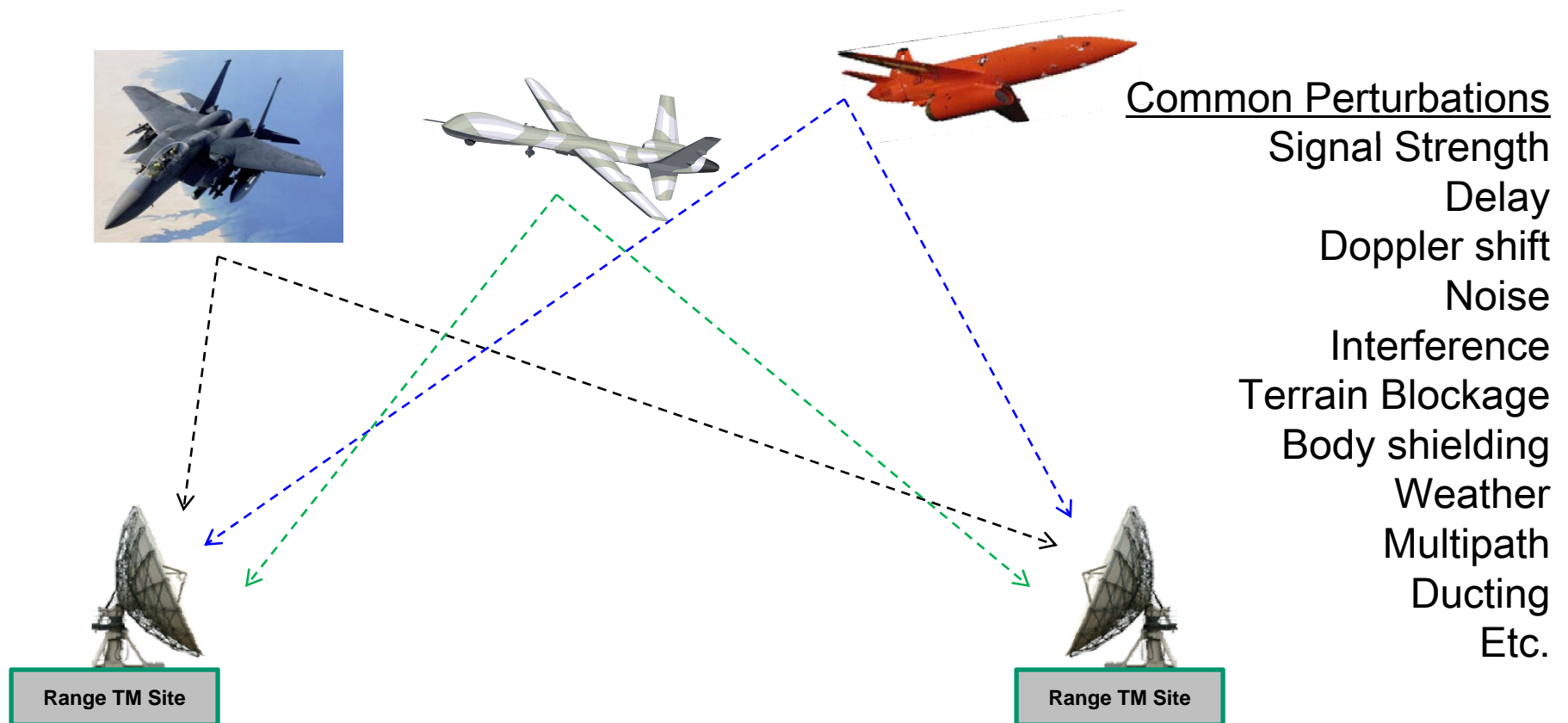
## Progress Update



RT Logic, Steve Williams  
48<sup>th</sup> Annual Targets, UAVs and Range  
Operations Symposium & Exhibition  
20 October, 2010



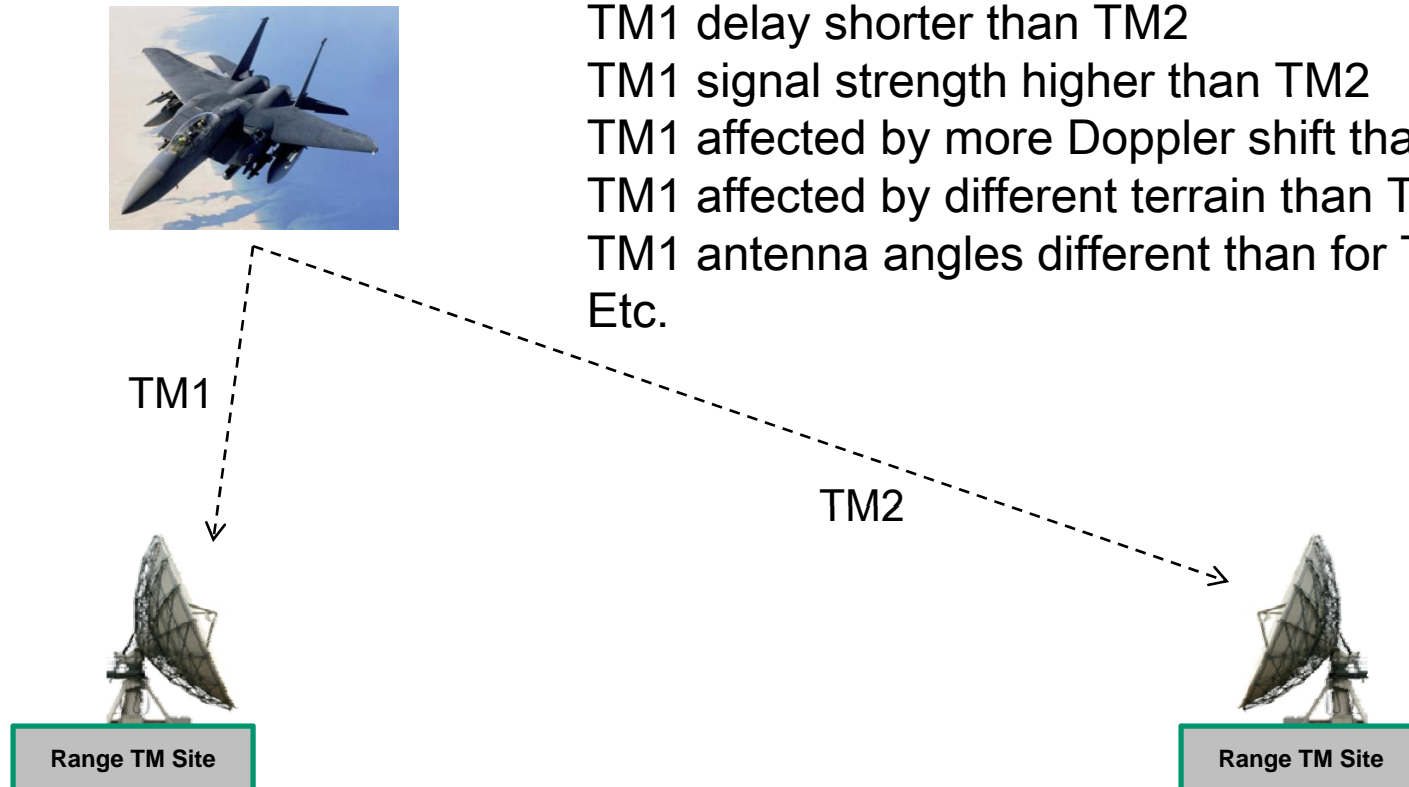
Whenever transmitters and receivers are in motion with respect to each other, RF link perturbations occur.



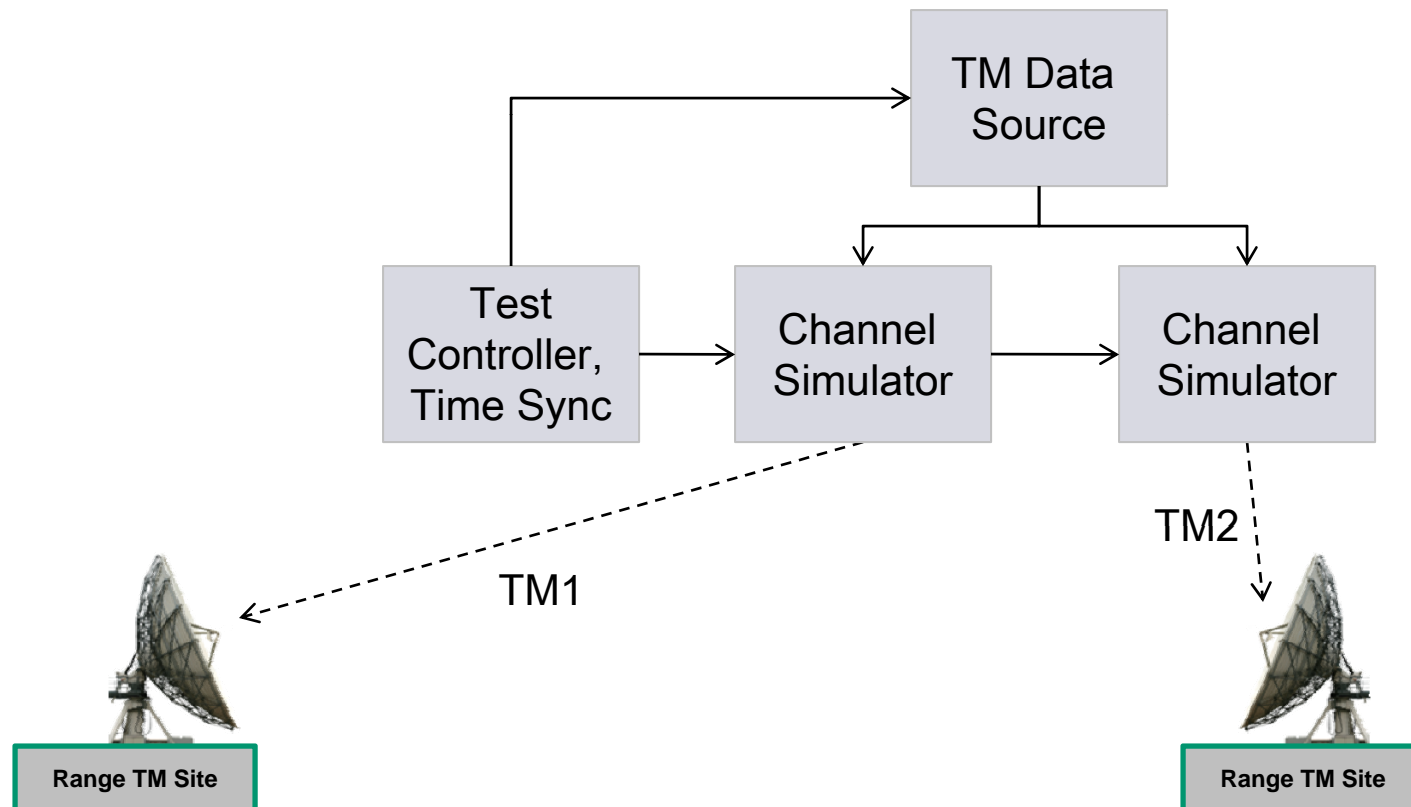
Signals TM1 and TM2 are transmitted from the same transmitter, so the data on each is the same, but the signals can look dramatically different from each other at receiving TM sites.

### Examples

- TM1 delay shorter than TM2
- TM1 signal strength higher than TM2
- TM1 affected by more Doppler shift than TM2
- TM1 affected by different terrain than TM2
- TM1 antenna angles different than for TM2
- Etc.

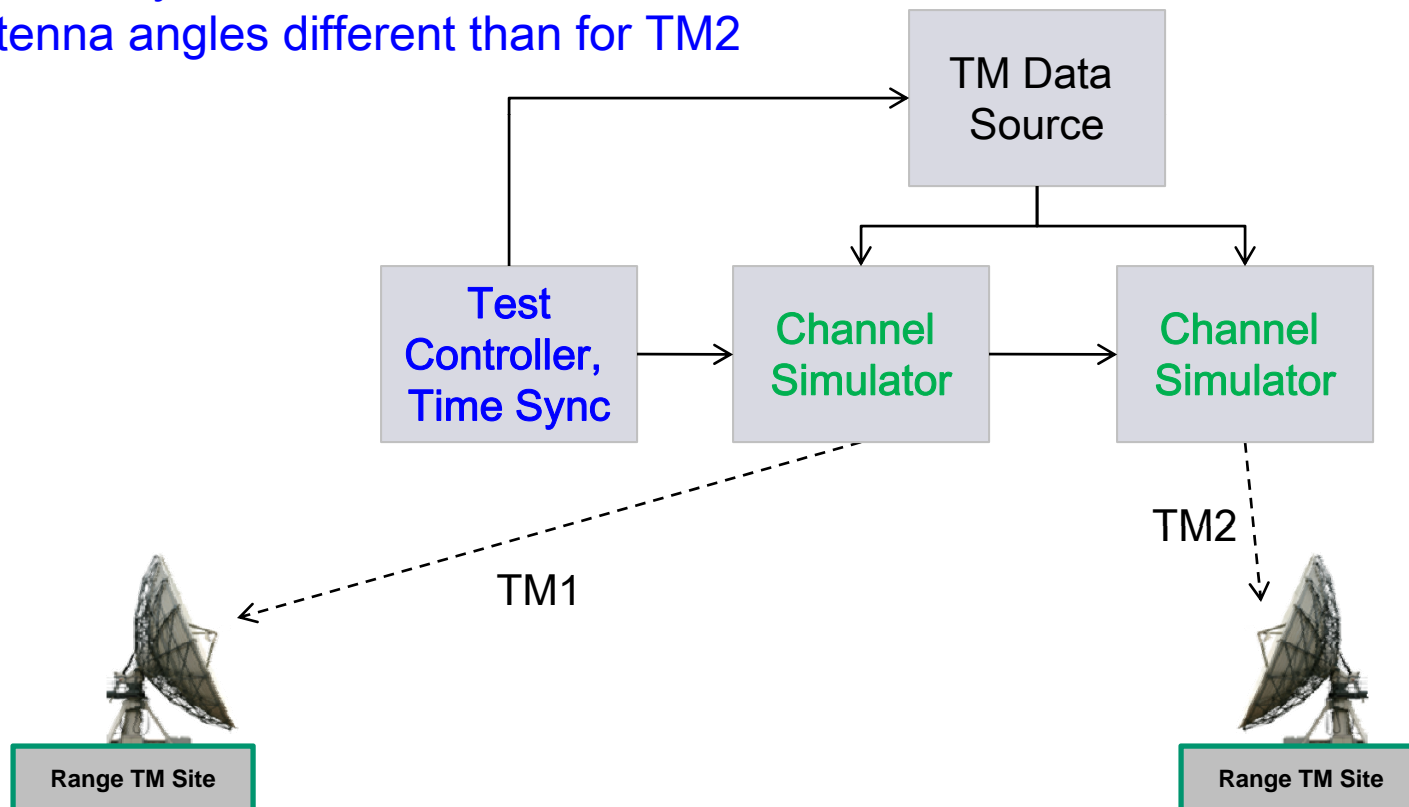


A method for testing the Test Range without flights is to supply signals from a central fixed location to the TM sites that have these same signal characteristics.



## Examples

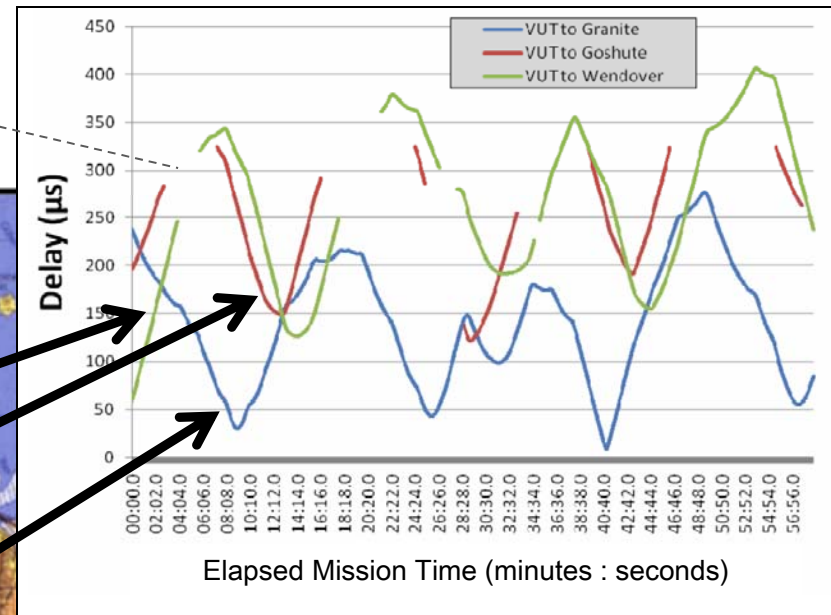
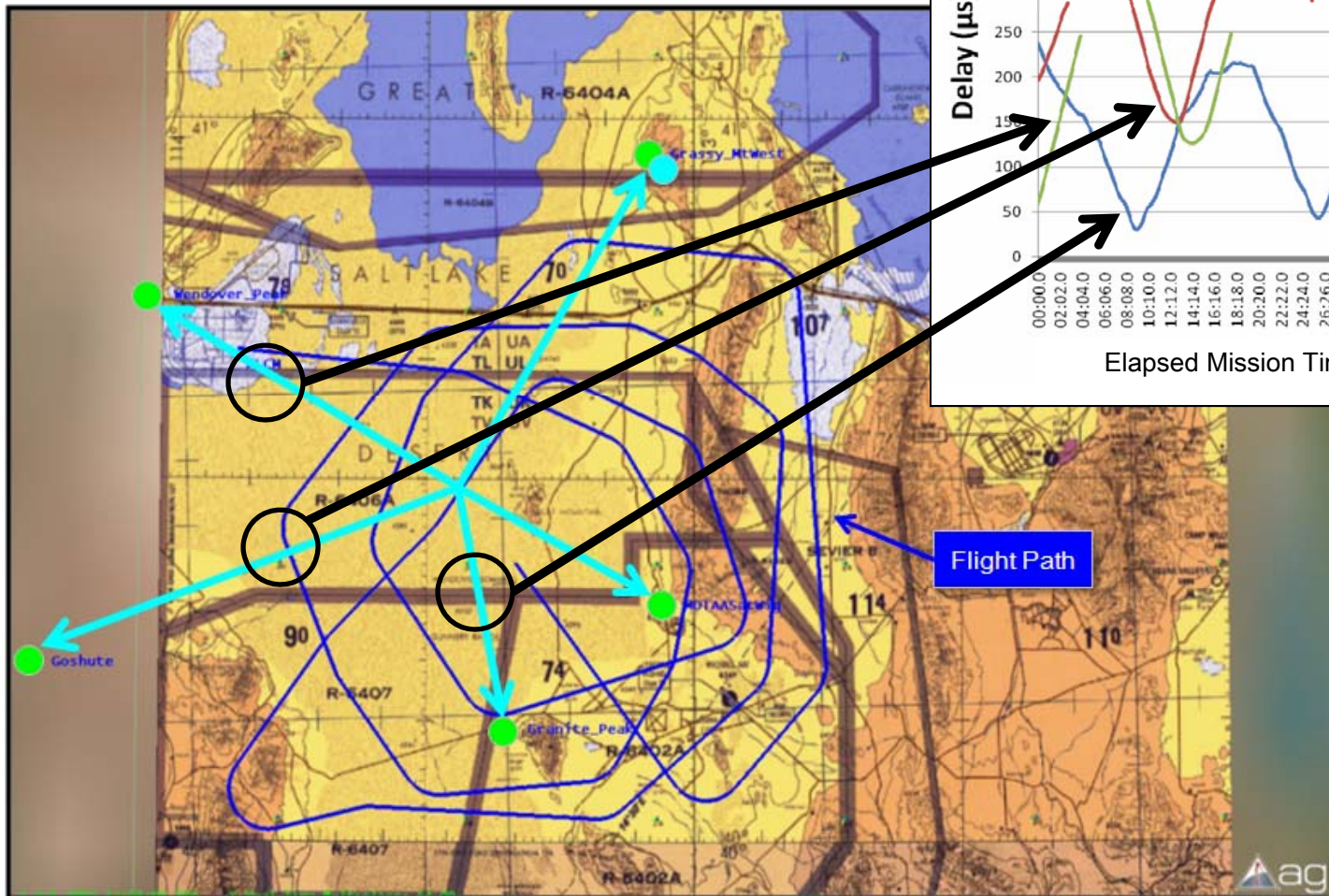
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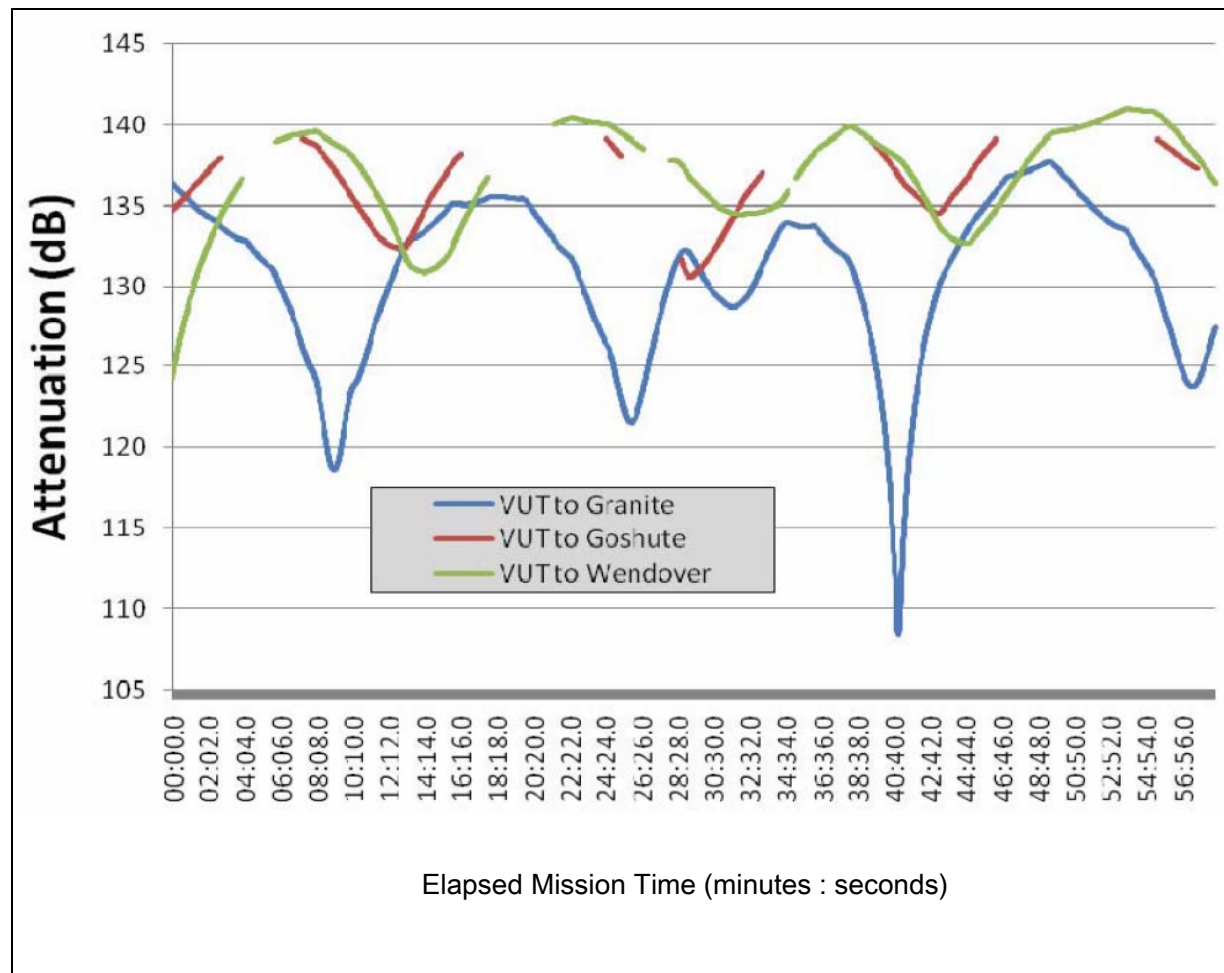
# Signal Delay Variance Through Flight

Gaps are terrain, link budget, and/or body shielding drop-outs



RF signals are received at each TM site at slightly different times due to the dynamic distance between the flight platform and the TM site location.

# Attenuation (Loss) Variance Through Flight



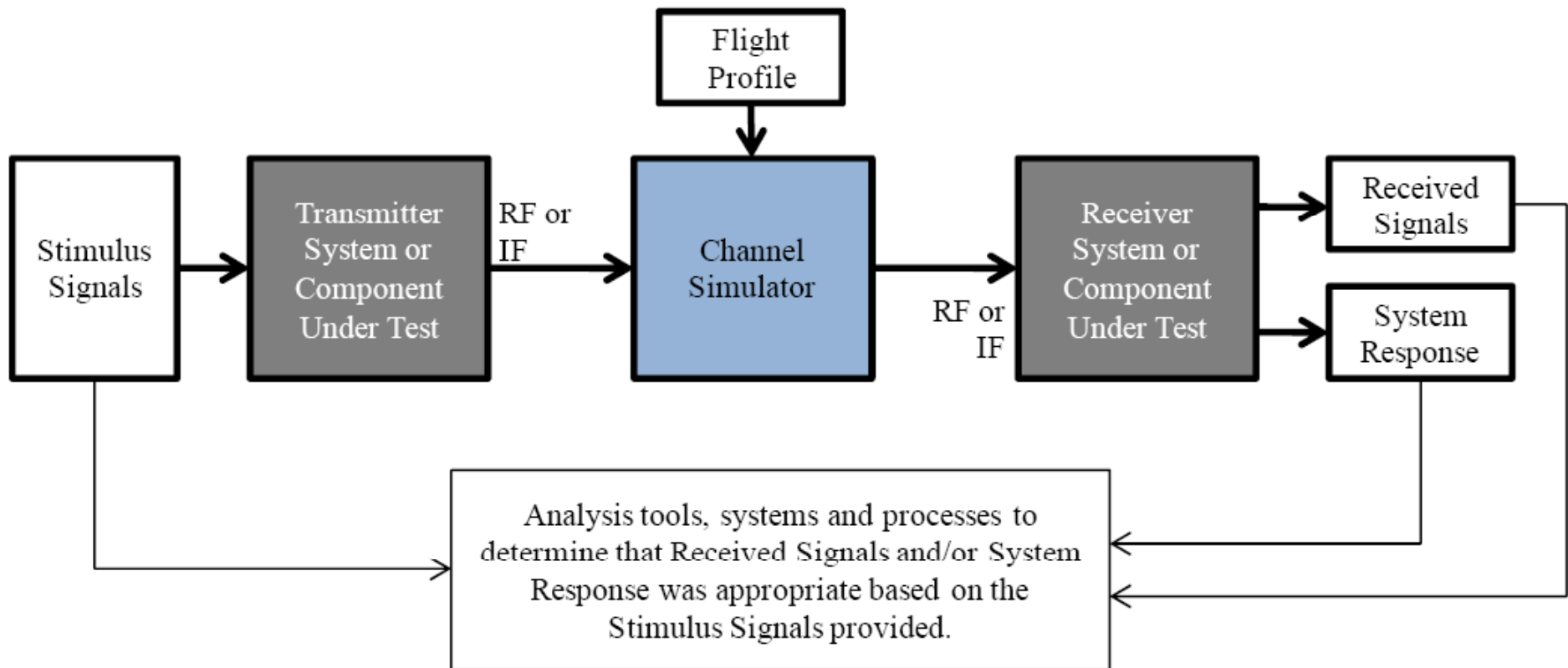
RF signals are received with differing power levels at each TM site at due to the dynamic distance between the flight platform and the TM site location.

Other dynamic attenuation factors include antenna patterns, body shielding, foliage, frequency selection, etc.

- Testing possibilities
  - TM Site as a whole
  - TM Site RF hardware elements
  - TM Site signal processing hardware elements
  - TM Site firmware, software, algorithms or processes
  - Entire Test Range, including BSS, Range Control Center Displays and final data creation/processing
- Training possibilities
  - TM Site Operators } Nominal conditions
  - Range Operators } Worst-case conditions
- Up-front range capability proof to customer
- Range mission readiness proof to range personnel and customer



- Theory is sound
- And, Channel Simulators do exist
  - But usually used in the lab for testing flight/ground hardware, SW, FW, etc.
  - Flight/Ground systems: Satellites, UAVs, Targets, Aircraft, Missiles, etc.



- Channel Simulators haven't been used in this manner in the past. Will they be useful for Range Testing?
  - With high power amplifiers and antennas
  - With complex flight profiles and flight/ground antenna models
- Needed to find a Test Range and a flight capability that was interested in helping validate the concept.
  - UTTR, Summer, 2009
    - Use of a Channel Simulator to pre-distort signals and transmit at RF to a TM site to validate received signal quality and Doppler, delay, loss and noise expectations.
  - Pax River and Airtec, Sept 28-29, 2010
    - Expanded test of entire concept...

- Test Process utilized at Pax River
  - 1. Perform Test Flight
    - Transmitting simple, known, unclassified BER TM
    - Close range and long range → signal fading, BER
    - High speed, close passes → Doppler shift
    - Various turn maneuvers → body shielding
    - Horizon → terrain masking
    - Record as-transmitted TM and TSPI on aircraft (truth data)
      - Also captured at Pax TM sites
    - Record TM & and signal characteristics at two TM sites
      - St. Mary's Airport
      - On Pax River

2. Process flight TSPI data to create Channel Simulator control model that mirrored the actual flight.

- Latitude, Longitude, Altitude, Yaw, Pitch and Roll
  - Incorporate previously constructed
    - Aircraft body model
    - Aircraft antenna/transmitter model
    - TM site antenna/receiver model
- } RF Model

3. Use Channel Simulators to transmit to 2 TM sites.

- Input signal = BER TM pattern as recorded on aircraft during flight
- Use TSPI and RF model constructed in #2 above
- Record TM & signal characteristics at two TM sites

4. Compare TM & signal characteristics from actual flight (step #1) and the simulated (step #3) flight.



Airtec Beach A-100 King Air

On board equipment rack  
GPS / IRIG Time  
BER / TM Data Generator  
S-Band Transmitter







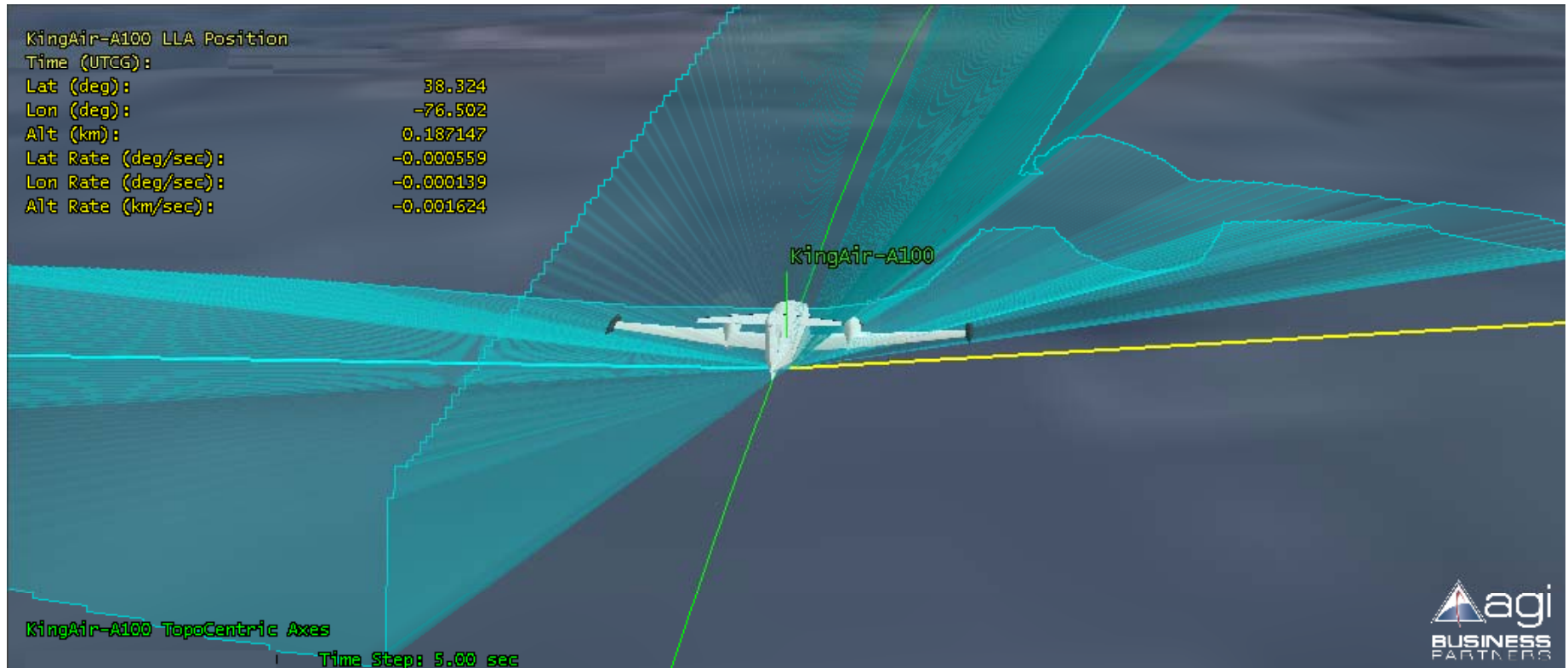
Novatel ARDS Pod  
For acquiring  
recording and  
transmitting TSPI  
data





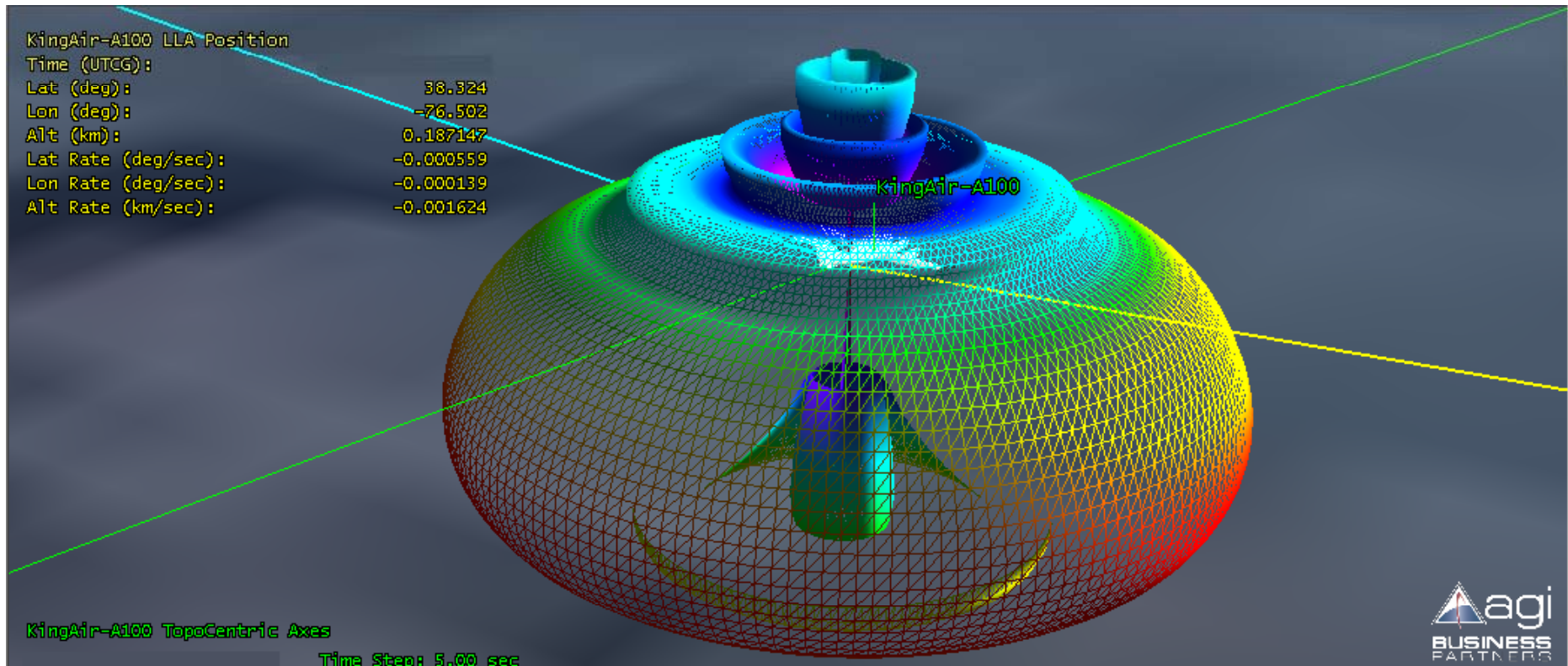
S-Band Antenna  
This was used  
for transmitting  
our test BER TM.

A separate  
antenna was  
used for  
transmitting from  
the ARDS pod.



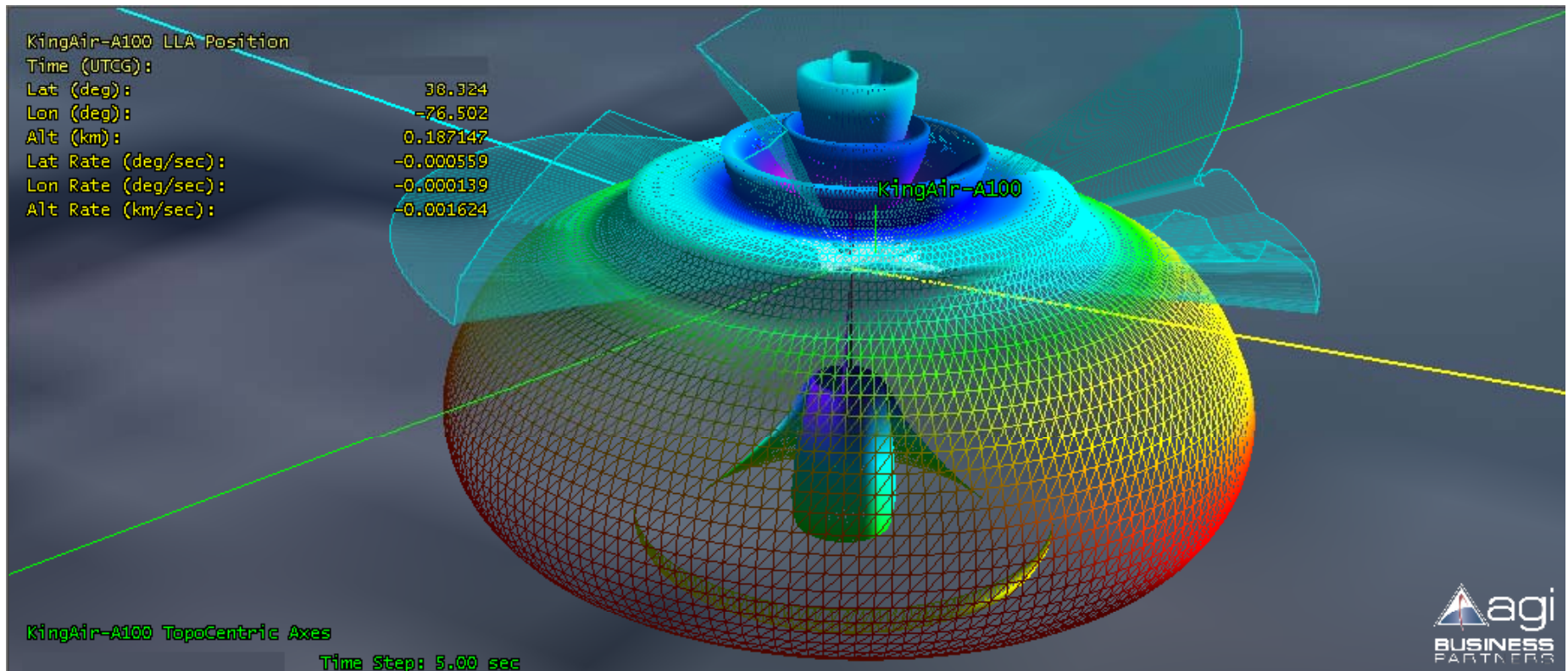
## Antenna Body Shielding Mask

Based on mounting location of antenna. Modeled in AGI  
STK, which is used for Channel Simulator control.



Antenna Radiation Pattern  
Based on antenna characteristics.





Antenna Radiation Pattern and Body Shielding Mask  
Based on antenna characteristics and mounting location.

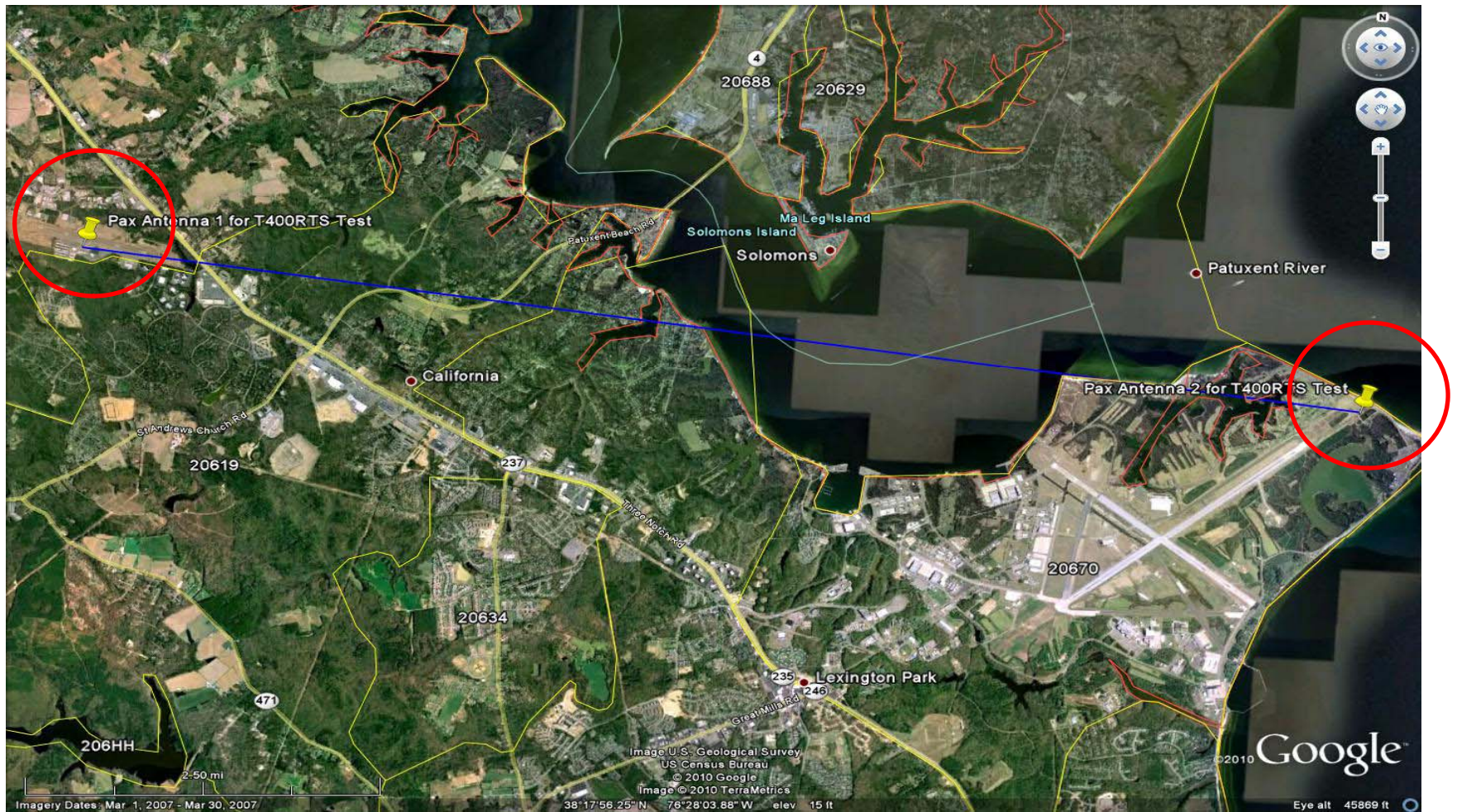


TM Sites  
This was the  
mobile site used  
at St. Mary's  
Airport

Very similar  
system used at  
Pax River site.



- TM Site locations for test flight





- Test Flight, Pax River, 28 Sept, 2010

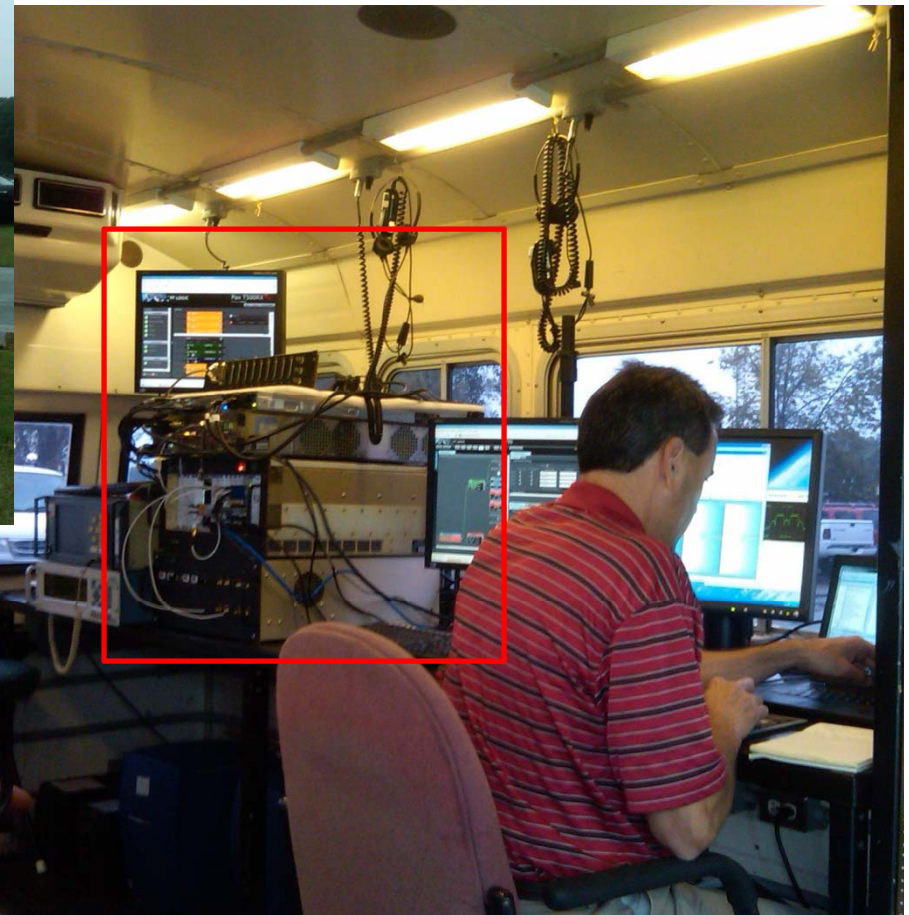


- Flight Simulation, Pax River, 29 Sept, 2010

Primary Channel  
Simulation Equipment



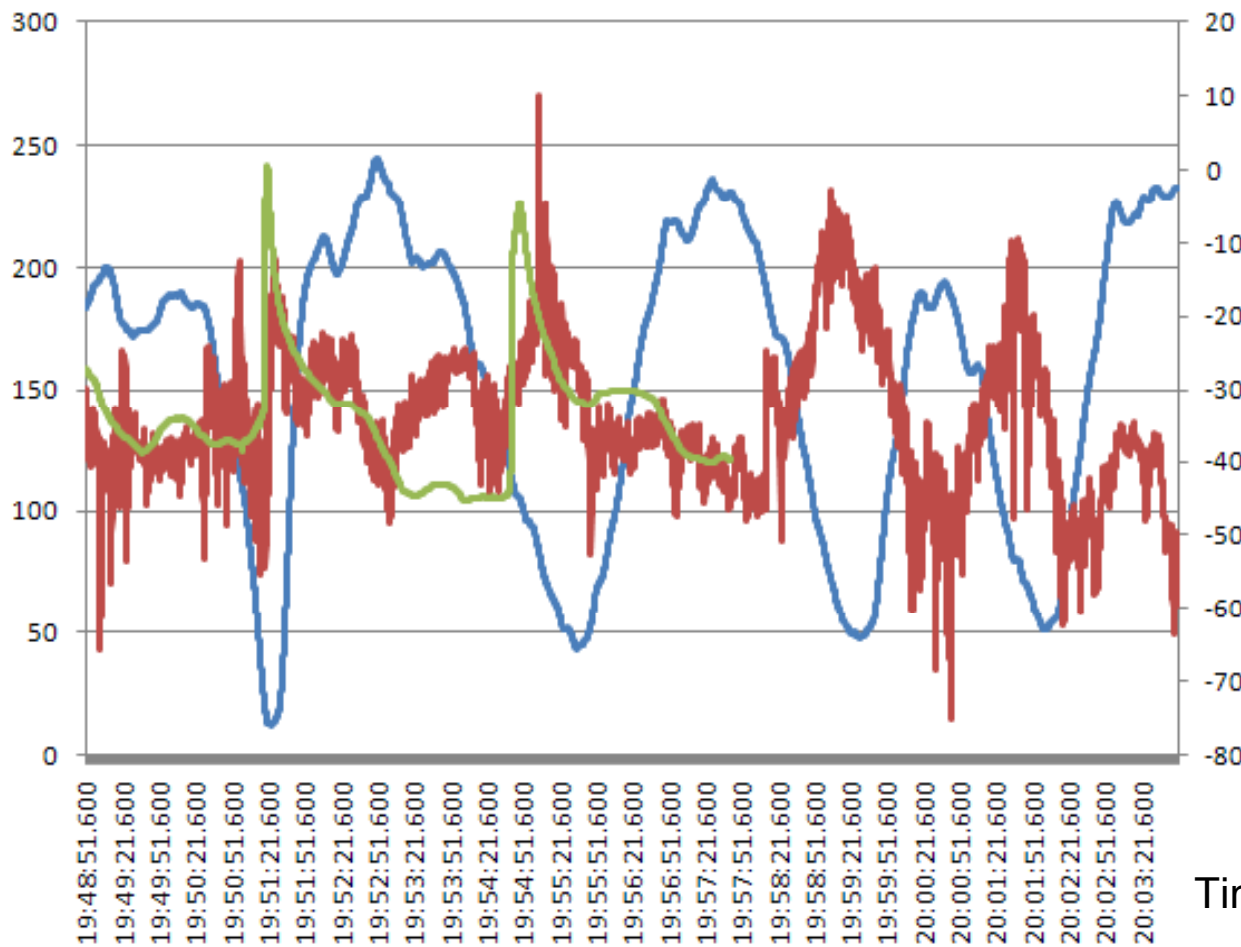
Telemetry Van  
Channel Simulators,  
Amplifiers and control  
elements.  
Two S-Band cone  
antennas pointed at 2  
TM sites.



- Very Preliminary Sample Data

Altitude (meters)

Scaled Relative Power (dBm)

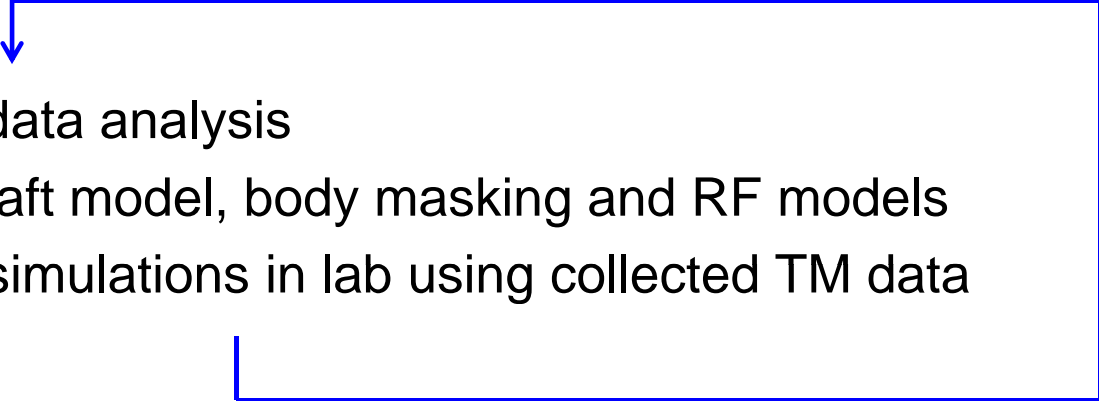


Without :  
 -Antenna models  
 -Body shielding  
 -Antenna pointing error factoring  
 -Time alignment  
 -Etc...

— Novatel Height  
 — StMary's LS35 RSSI\_1  
 — Calculated Recv Power ←

Time (first ~15 minutes)

- Near term next steps

- 
- Continued data analysis
  - Refine aircraft model, body masking and RF models
  - Rerun test simulations in lab using collected TM data
- 
- In-depth review of final results with Pax River
  - Develop and implement recommendations
    - Another test flight
    - Retransmit to Pax TM sites
    - Channel Simulator functionality modifications (e.g. multipath)
    - Etc.



- Summary
  - Verification efforts continue, but...
  - Channel Simulators can be used to verify Test Range operation as a whole, or in part, and can be dual-purposed for Test Range operations training.
  - Such testing/training is faster, more economical and more complete than testing/training with actual flights, since the limits of scenario development are virtually boundless.
- Acknowledgement
  - RT Logic would like to express it's sincere gratitude to Mr. Bob Myers and his NAVAIR team at Pax River for their enthusiastic support and valued assistance in conducting these tests.
- For further information and/or a copy of the final report
  - Steve Williams, RT Logic, 719-884-6269, [swilliams@rtlogic.com](mailto:swilliams@rtlogic.com).
  - Booth #315, NDIA Targets, UAVs and Range Operations Symposium.