



PRODAS GNC Trajectory System Simulation

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NDIA Guns & Missiles

Legacy Software
Simulation

PRODAS GN&C
Prototype Tool

MATLAB/ Simulink
Simulation

Legacy Software Simulation

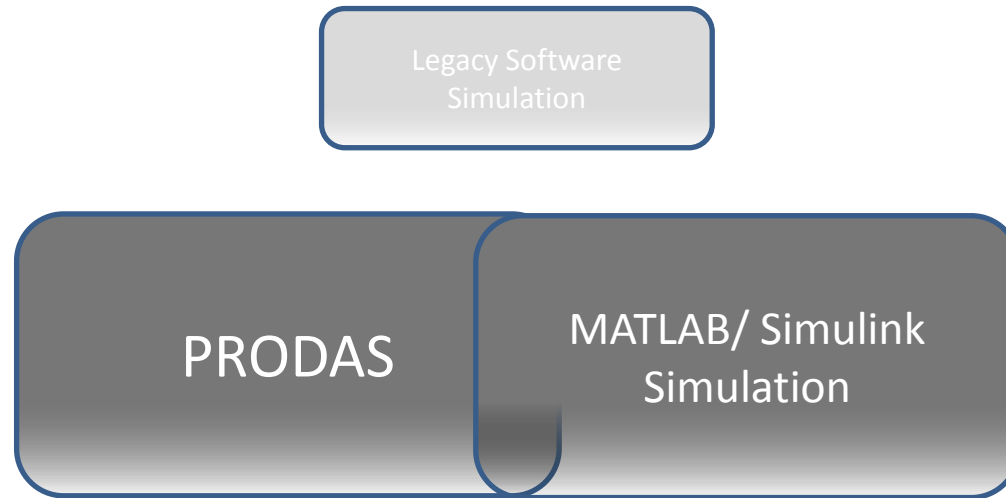
- **Pros**
 - Detail only limited by developer
 - Very fast simulation
- **Cons**
 - Tough to validate
 - Can get very complex

PRODAS GN&C Prototype Tool

- **Pros**
 - Trajectory Engine transparent to User
 - Very fast simulation
 - Simulation Data provided by PRODAS
 - Can be driven by a Macro
 - Validated Trajectory codes
- **Cons**
 - Limited detail

MATLAB/ Simulink Simulation

- **Pros**
 - Almost unlimited details can be included
 - Internal equations and variables visible
 - GN&C can transition easily into Hardware
- **Cons**
 - User must build and validate Trajectory Engine
 - User must provide inputs and build outputs



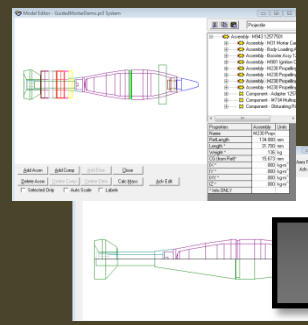
- **Pros**
 - **Validated Trajectory Engine**
 - **Simulation inputs provided by PRODAS**
 - **Unlimited details can be included**
 - **GN&C can transition easily into Hardware**

PRODAS – MATLAB/Simulink Simulation

PRODAS Environment

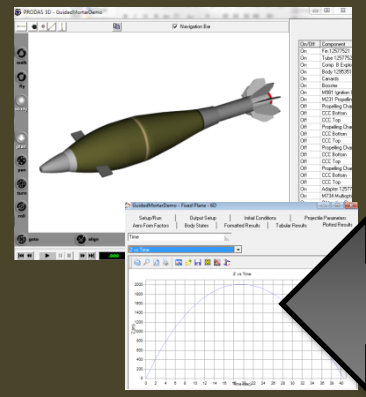
Modeling

- Projectile Modeler
- Aero Prediction
- Mass Properties
- Rocket Motor
- Initial Conditions
- Error Budgets
- MET

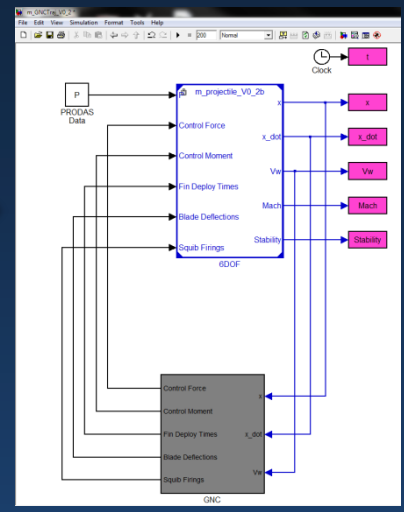


Visualization

- 3D Animations
- Extensive Plotting



MATLAB/Simulink Environment



Development

- Leverage All MATLAB/Simulink Toolboxes and Blocksets
- Focused Effort on GNC Design

Simulation

- Validated 6+DOF Trajectory Engine
- Seamless Data Interface and Execution Between PRODAS and MATLAB

Product Tests

Hardware-In-the-Loop (HIL)

- Use the same simulation to drive the HIL fixture



Embedded Code Generation

- Automatically generate flight code from the Simulink model



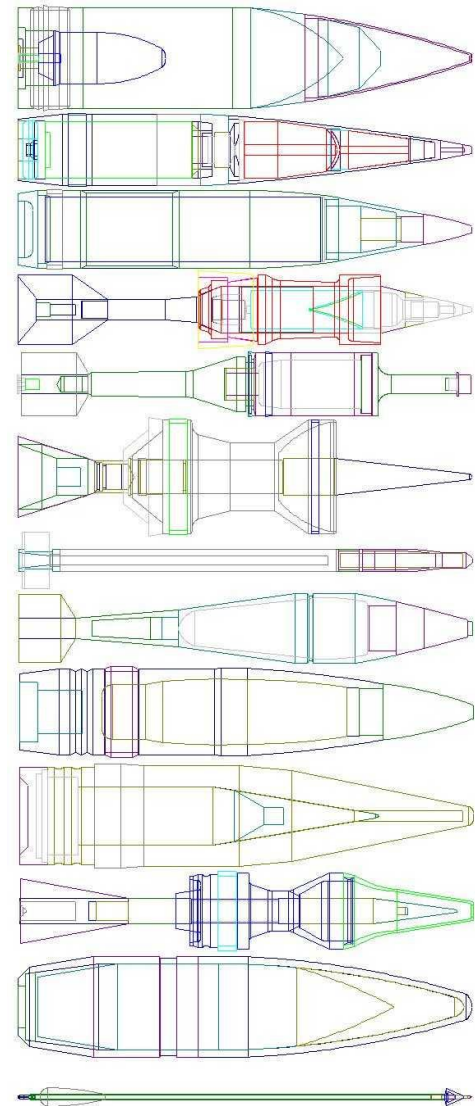
Fire Control

- Simulation software is the basis of fire control software



PRODAS

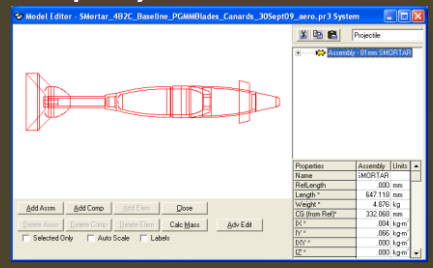
- Industry standard projectile design and analysis environment
- 65+ integrated analysis modules
 - System simulation
 - Aerodynamic prediction and stability
 - Trajectory simulation and flight Dynamics
 - Guidance, navigation, and control
 - In-bore balloting and interior ballistics simulation
 - Aero-ballistic test data reduction
 - Software development kit
- Over 500 Users at Government and prime contractors
- In use in over 25 countries



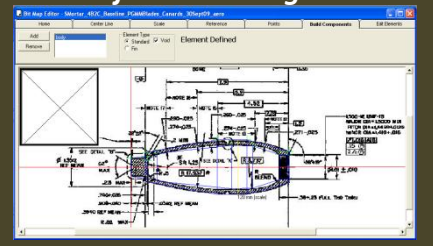
Guided Projectile Development with PRODAS

Build a Model

Simple Symmetric Model Editor

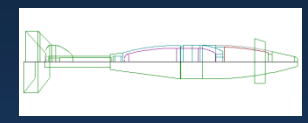


Projectile Tracing Tool

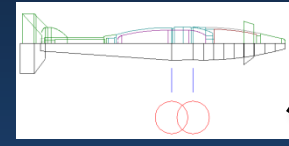


Estimate Aerodynamics

Arrow Tech Finner/Spinner



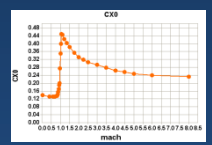
NSWC AP



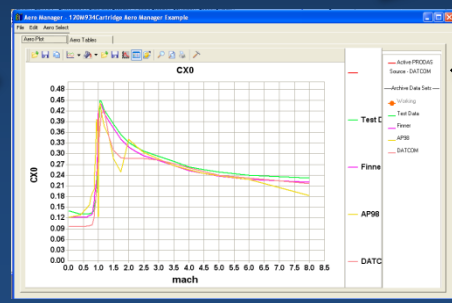
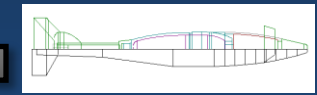
Nielsen Engr. MISL3



Test Data



Missile DATCOM



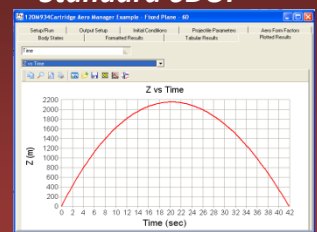
PRODAS Aero Manager

Macro Language

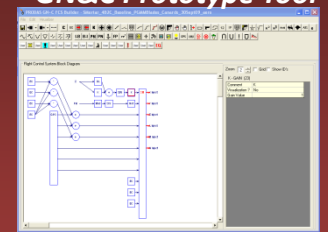
Software Development Kit

Fly It

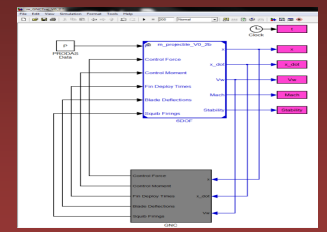
Standard 6DOF



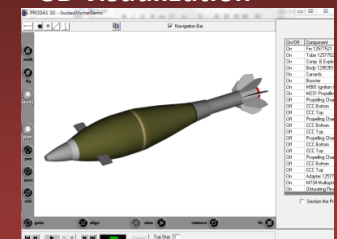
GN&C Prototype Tool



GN&C MATLAB

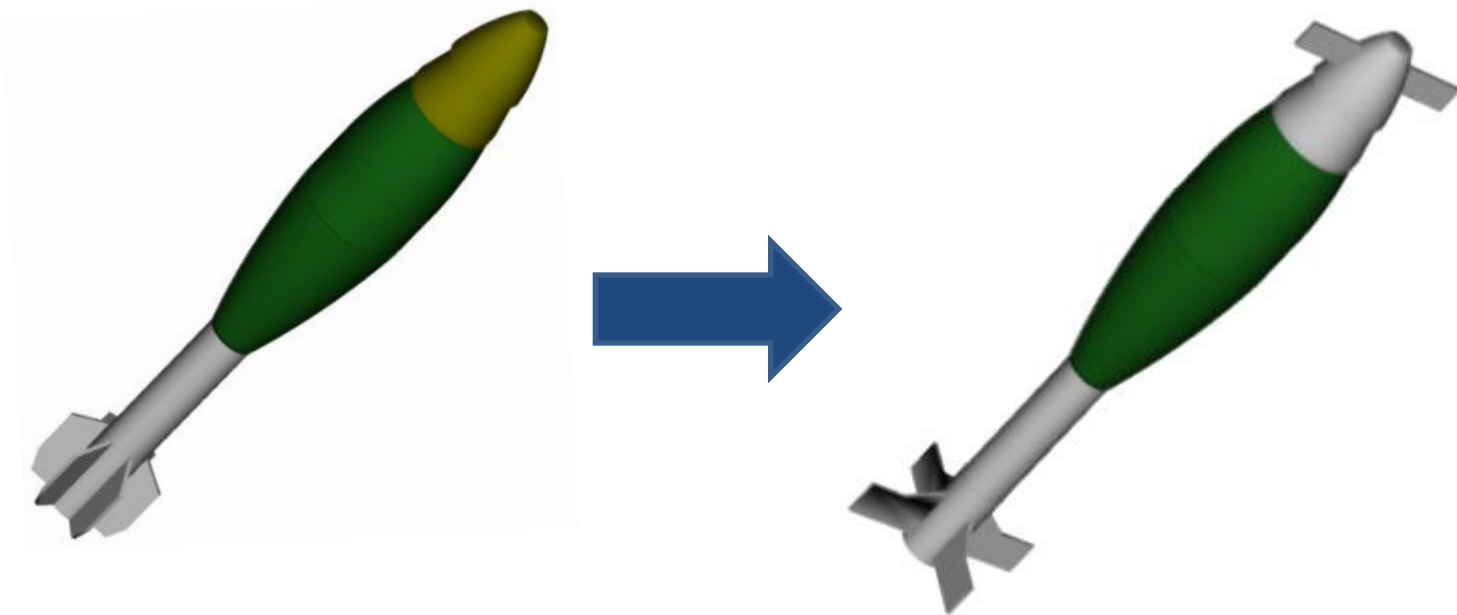


3D visualization



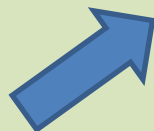
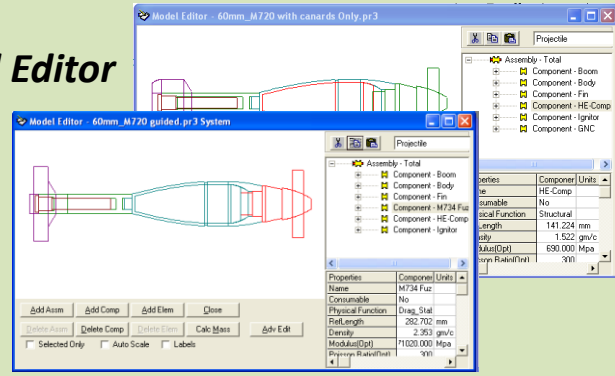
How Does It Work?

- Illustrate with a simple transformation
- Add nose and tail kit to a 60mm Mortar



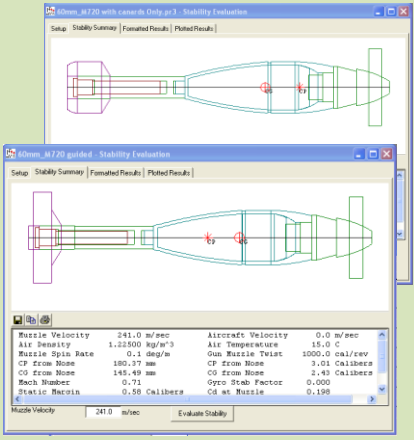
Design the Air Vehicle

Model Editor

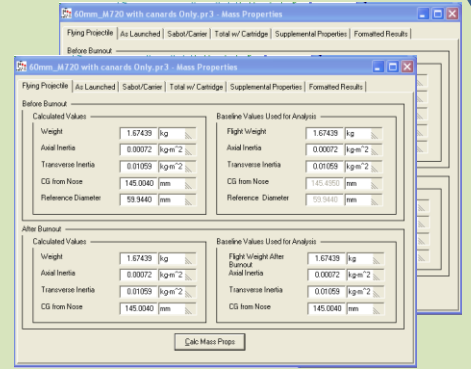


- Design the air vehicle:
 - Add control surfaces
 - Update mass properties
 - Estimate Aerodynamics
 - Evaluate Stability
 - Repeat as Necessary

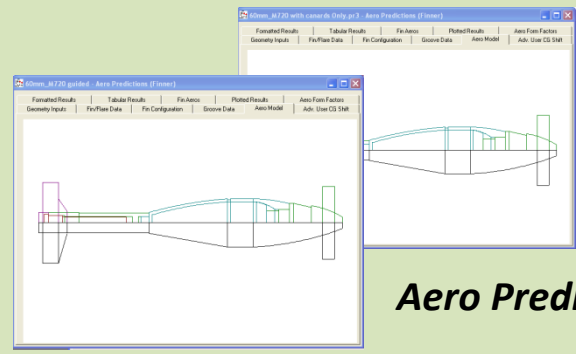
Stability Evaluation



Mass Properties



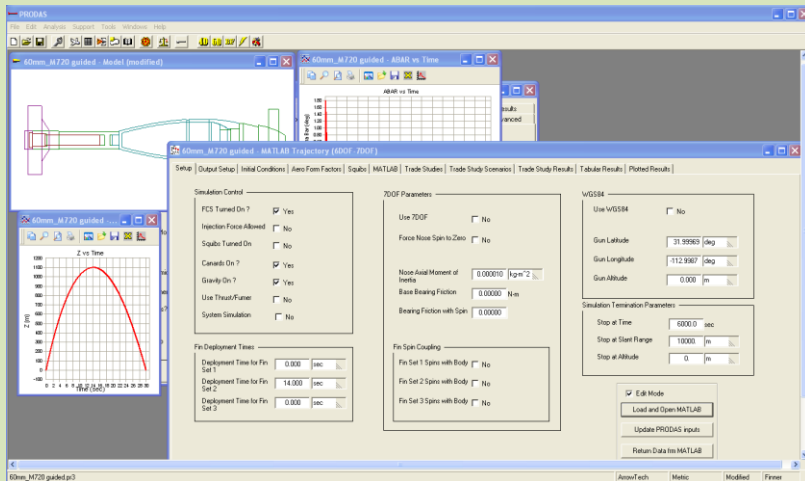
Aero Prediction



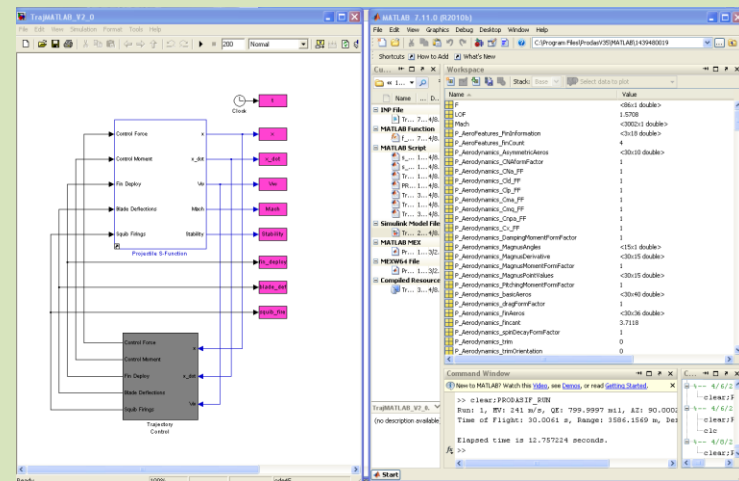
PRODAS

Build a Simple Open Loop Controller

- Open Loop Controller to:
 - Deploy canards at apogee
 - Extend Range
 - Dither with roll angle



PRODIGE MATLAB Interface

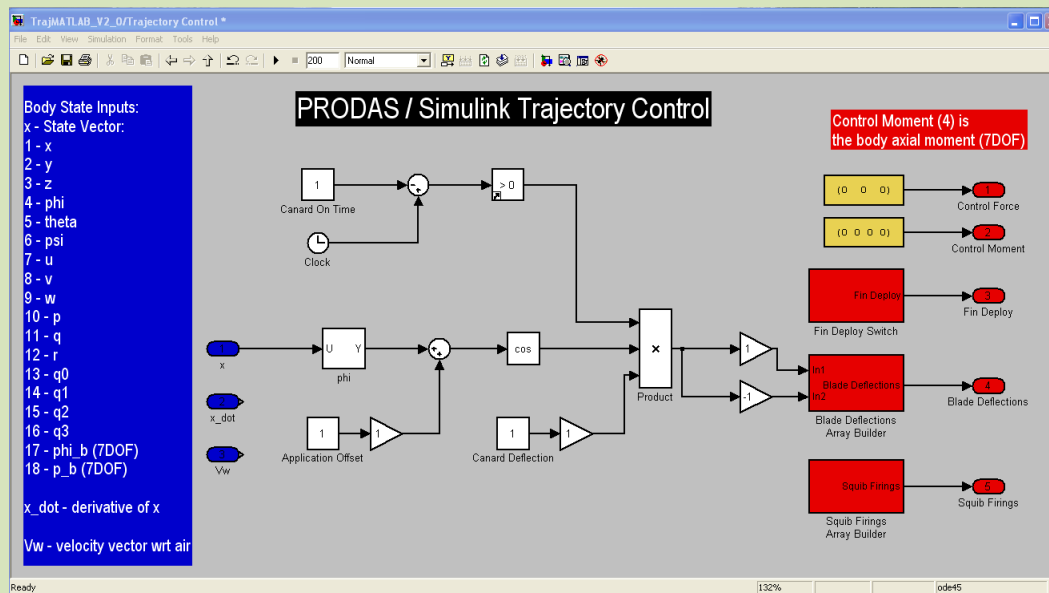


MATLAB/Simulink

PRODIGE

Simple Open Loop Controller

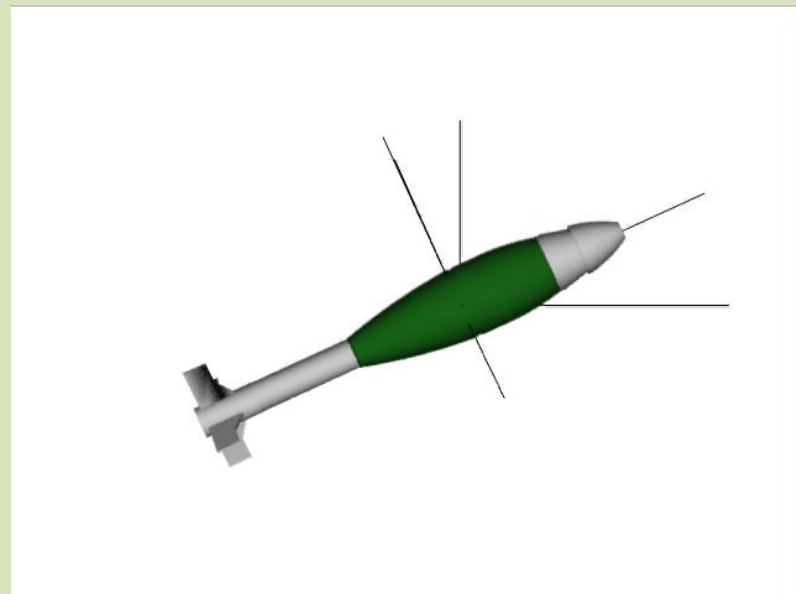
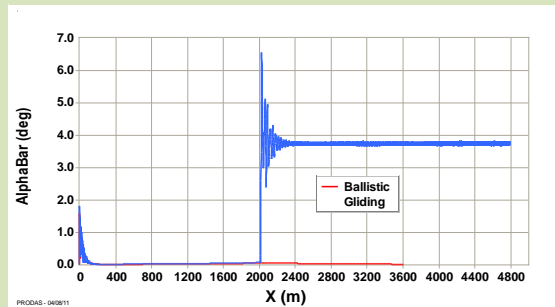
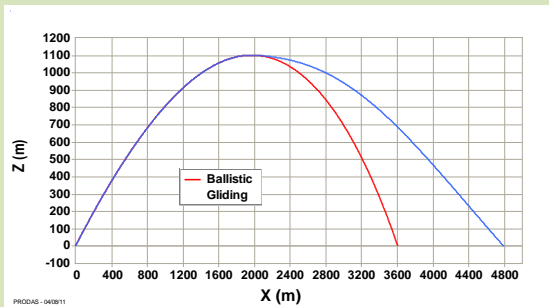
- Validated trajectory engine
- Automatic interface to aeros and IC's
- Design the GNC in Simulink
 - Use any Block Set
 - Inputs - Body states
 - Output - canard angle
- Model contained in PR3 file



PRODAS

Run Simulation Review Results

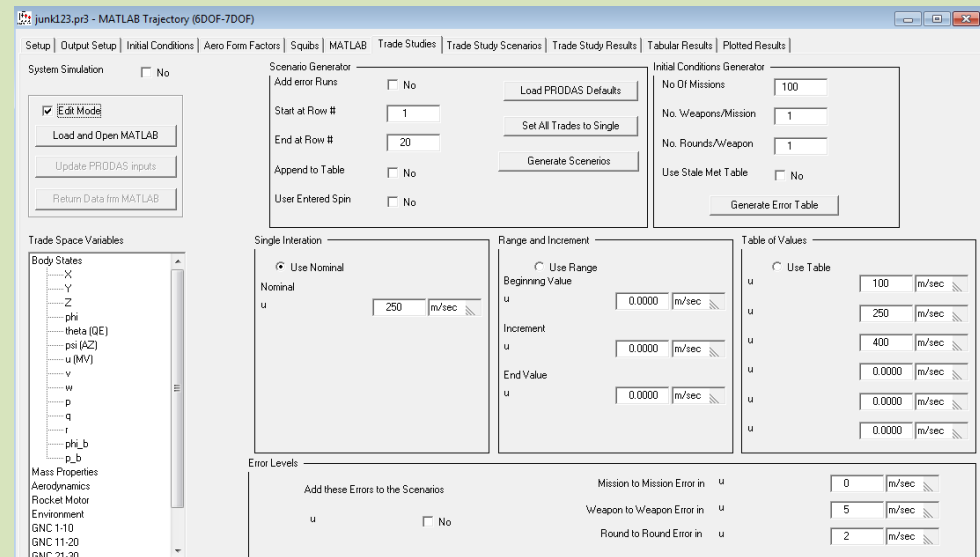
- Use MATLAB plot functions or
- Use built in PRODAS plots and visualizations
- Cross plot against other codes



PRODAS

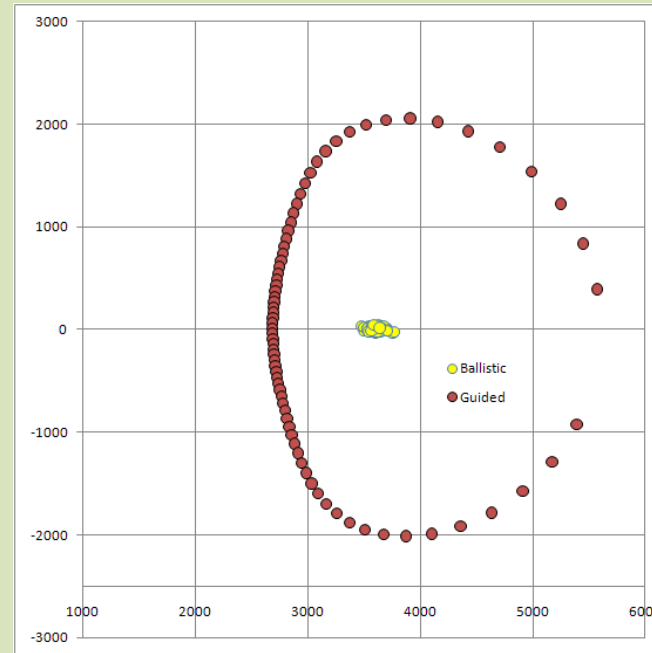
Trade Studies and Error Budget

- Setup trade study scenarios varying:
 - Body states
 - Mass properties
 - Aerodynamics
 - Rocket Motor
 - Environment (MET)
 - 50 custom GNC parameters
- Add system errors to any variable
 - Mission-to-mission
 - Weapon-to-weapon
 - Round-to-round



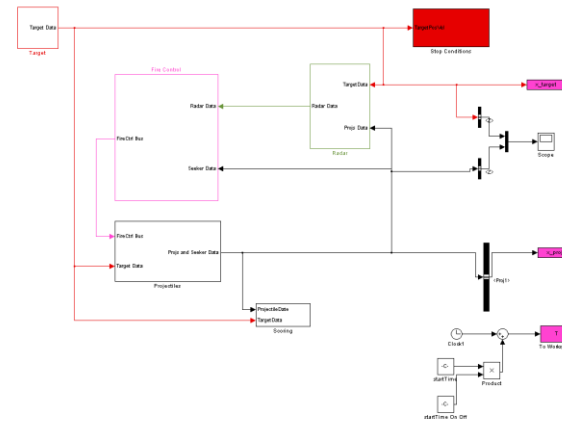
System Error Budget

- Example entered errors for:
 - Muzzle Velocity
 - Mass
 - Winds
 - Temperature
 - Quadrant Elevation
- Monte Carlo Runs
 - Ballistic to validate errors
 - Open loop guidance to check control authority



Where To Go From Here

- Close Loop GNC
- Sensor Models
- Use 6DOF and GNC model for HIL
- Generate code for embedded processor



This then becomes the system simulation for the program

Conclusion

- The PRODAS tool set has been enhanced with the inclusion of the MATLAB/Simlink Trajectory Code
- Now PRODAS can be your tool from concept to final production.
- For more information on the PRODAS MATLAB/Simulink Trajectory Engine contact:
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