Robotics and the National Robotics Initiative

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Overview

- Self-introduction
- President's vision
- National Robotics Initiative
- State of the art
- Three specific applications: nuclear, military bases, logistics
- ... and lots of cool videos



My Own Background

• Carnegie Mellon Robotics Institute, 1979 – present: PhD student, post-doc, faculty, Director 2000 - 2004





... and a few robots

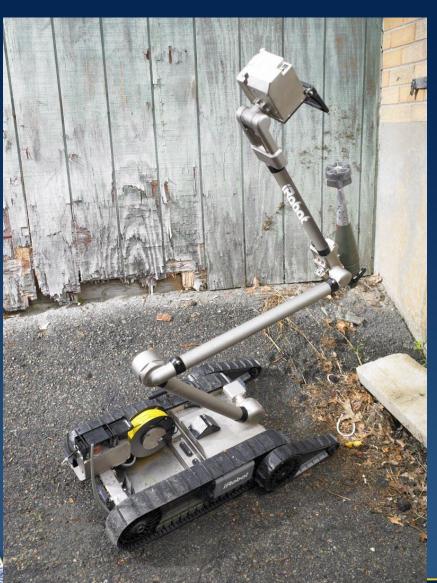


State of the Art

- Over 6 million robots in use.
- Over 5 million:
- Around 10,000:







1,000,000 Assembly Robots











Robot safety, 1961 - 2011





Robots vs Humans

- Robots
- Fast
- Precise
- Tireless
- Huge memory
- Disposable

- Humans
- Reasoning
- Perception
- Adaptable

So why is there a fence between them?

May 21, 2009



A Roadmap for US Robotics From Internet to Robotics

Organized by

Georgia Institute of Technology
University of Southern California
Johns Hopkins University
University of Pennsylvania
University of California, Berkeley
Rensselaer Polytechnic Institute
University of Massachusetts, Amherst
University of Utah
Carnegie Mellon University
Tech Collaborative

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POTUS and Robots





Presidential Priorities for Robots





The President's Mission

• "You might not know this, but one of my responsibilities as Commander-in-Chief is to keep an eye on robots. (Laughter.) And I'm pleased to report that the robots you manufacture here seem peaceful -- (laughter) - at least for now."



Robotics Vision: Machines Who Think

- Building smart machines
 - -"Disappearing robots"
 - -"Co-workers of the future"
- Building embodied intelligence
 - -"Where AI meets the real world"
 - -"Why computer science matters"
- Building smart people
 - -STEM education
 - -K-PhD
- Building smart industry
 - –Making the robot revolution happen in the US
 - -Moving technology out of the labs and into society



National Robotics Initiative (NRI)

The realization of co-robots acting in direct support of individuals and groups

• manufacturing; exploration; discovery; agriculture; security;



The NRI

- Multi-agency SBIR
- DURIP
- Prizes and Competitions
 - -RoboBowl, AFRL, ...
- New applications
- Multi-agency RFP: Co-Robots
 - -680 LOIs for small projects / 445 proposals
 - -67 LOIs for large projects / 261 proposals



NASA







USDA



NIH









NRI Research Areas

Fundamental research in robotics science and technology Controls and dynamical systems

Computational models of human cognition

Application-inspired topics

Platform specific topics

micro- and nano-robotics,

neuro-robotics,

humanoid robotics, and

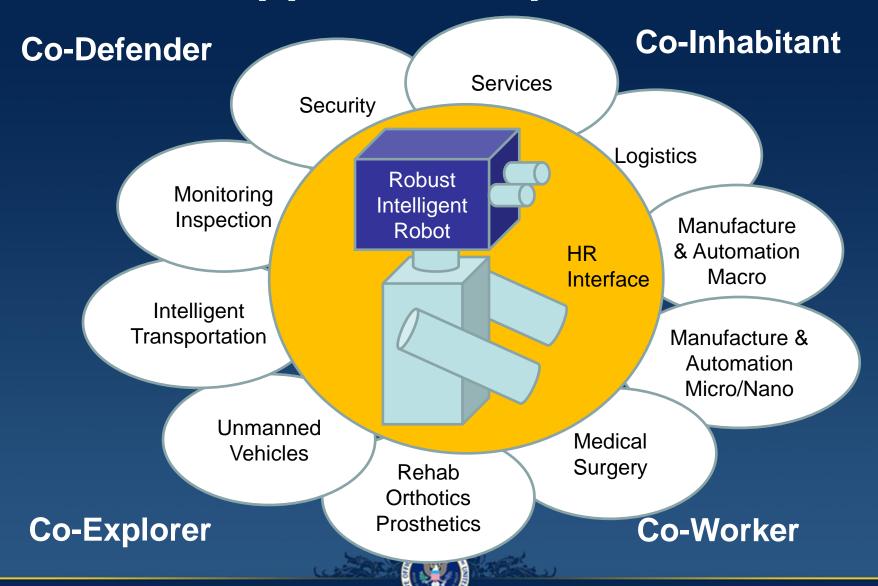
networked multi-robot team

Understanding of the long term social, behavioral and economic implications of co-robots across all areas of human activity

Use of co-robots for STEM learning K-16



NRI: The Application Space



Co-Robots: Task Cooperation





Co-robots: Safety through Control



Three Laws of Robotics

- 1.A robot may not injure a human being or, through inaction, allow a human being to come to harm.
- A robot must obey orders given it by human beings except where such orders would conflict with the First Law.
- 3.A robot must protect its own existence as long as such protection does not conflict with the First or Second Law.

Isaac Asimov - The Caves Of Steel, p. 177-179, 1942



Co-Robots: Go where people can't



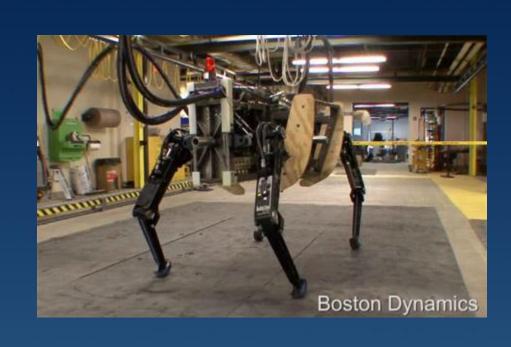


Co-robots: carry the load



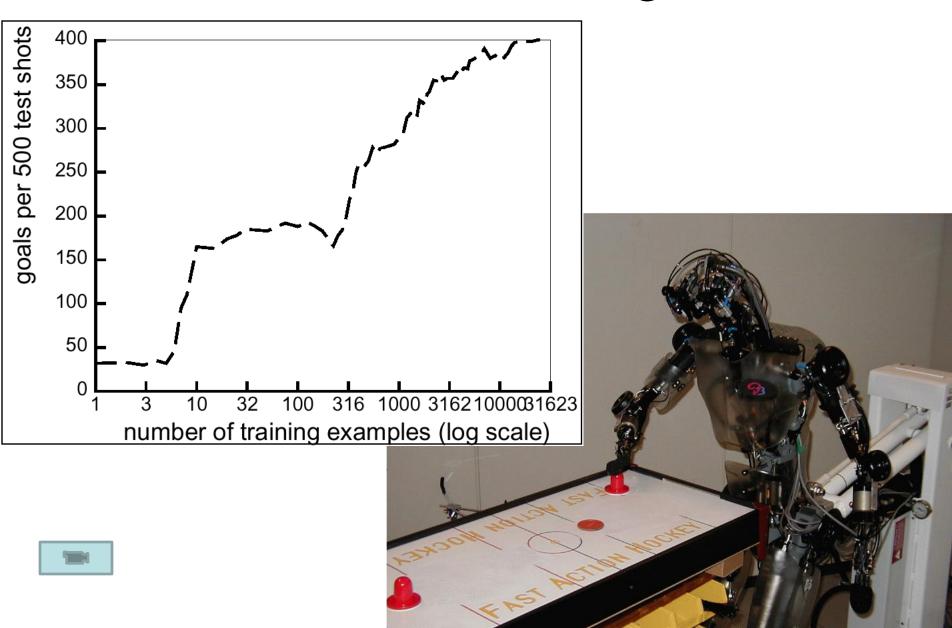


The Evolution of Dogs

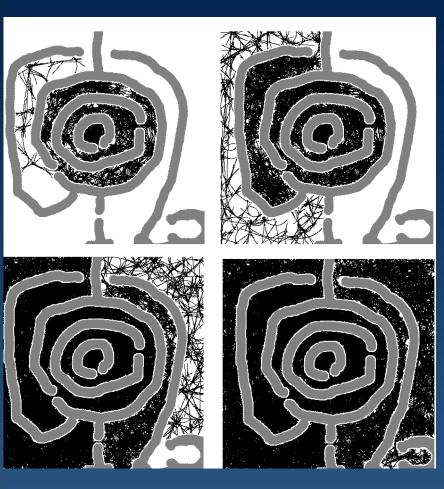


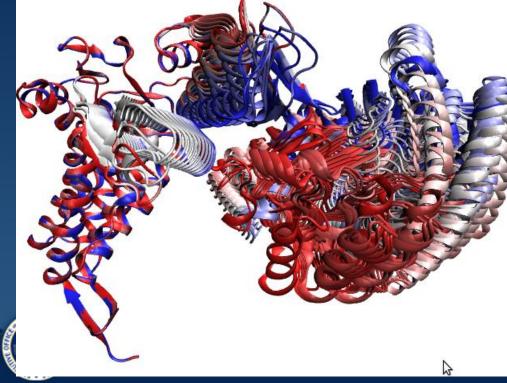


Robot Learning

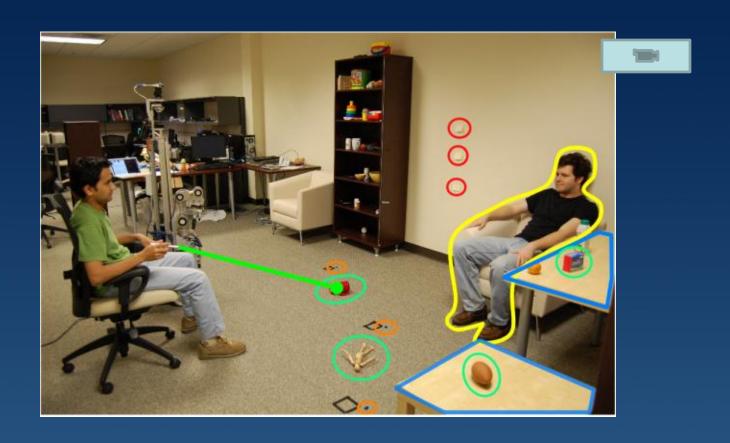


Tangent: Robots and Proteins





Co-robots: Robot-Ready House; House-Ready Robot





... and Really Really cute design: RoboBowl

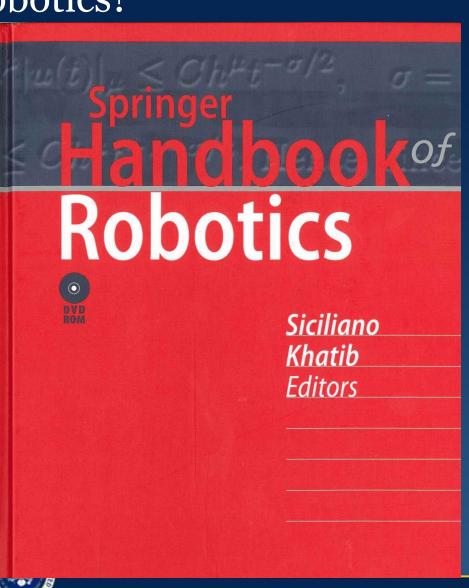


- 5-part competition
- Business plans
- Round 1, Health Care Robotics
- Winner: Interbots



How International is Robotics?

Australia	7
Belgium	2
Canada	7
Finland	1
France	13
Germany	10
Italy	20
Japan	14
Korea	4
Norway	1
Portugal	1
Spain	1
Sweden	2
Switzerland	5
Taiwan	2
Turkey	1
UK	3
US	67



Ultimate in Human-Friendly Robots







Application 1: Nuclear Disasters





Quince





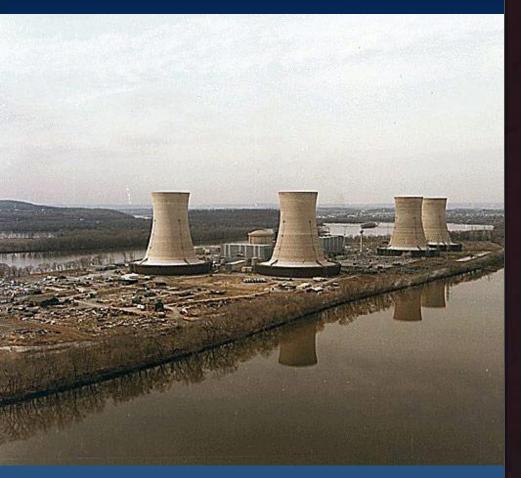
Qinetiq Bobcat





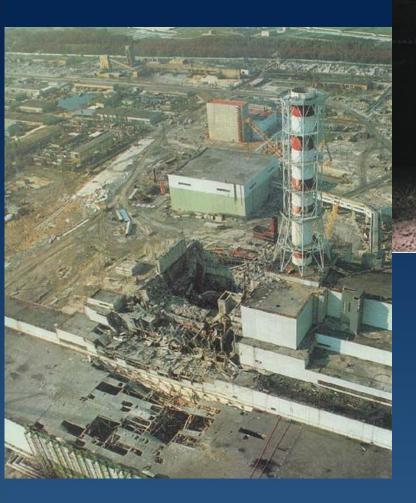


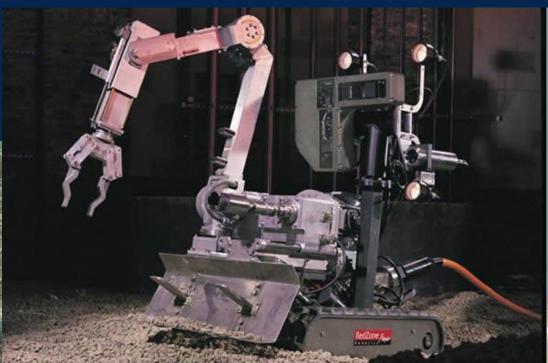














French and German Rad-Nuke Robots



INTRA:
Group of Robotics INTervention on Accidents (INTRA)







Robots for Nuclear Disaster Response

- Who's in charge?
- Who has the capability?

- DNDO
- NNSA
- NE
- FEMA
- DOJ / FBI
- AMCOM
- DTRA
- iRobot
- Qinetiq
- Sandia
- INL
- SPAWAR



Nuclear Response Robots

- Rad-harden some camera sleds
- Generate roadmap for disaster response
 - -Mobility
 - -Communications
 - -Manipulation
 - -User interfaces
 - -Air, land, underwater
 - -Commonality across CBRN, IED, civil platforms and interfaces
- Solve the robotics problem



Robots on Military Bases

• Let's get robots running on military bases

• LtG Lynch

• What can robots do today?



Carry Stuff





... Lots of stuff





Operate your warehouse – Kiva version





Seegrid Version





Collect your garbage DustCart Robot in Peccioli





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Education

standards.

Proven cost savings and consistent cleaning that meet the demands of cleaning schools and universities. Educational environment operating software. The robots' long-range sensors offer a perfect solution for cleaning gymnasiums and cafeterias. Reporting and accountability allow school districts and educational facilities to maintain the highest santation.

The Intellibot robot takes care of your floor cleaning needs every night, freeing up your labor staff to concentrate on high-maintenance zones like restrooms and cafeterias.

Our current clients include:

Mesa Public Schools, Mesa, AZ Upper Merion School District, Upper Merion, PA Neshaminy School District, Langhorne, PA United States Military Academy, Westpoint, NY University of California, Long Beach, CA Onslow County School District, Jacksonville, NG

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... affordably





Application 3

- Robotics and logistics
 - -Lots already happening
 - -Lots left to do
 - -<your ideas go here>



Research Areas

- Touch sensors
- Advanced power sources
- Soft actuation
- Safety skins
- Object recognition
- Intention inference
- Multi-robot cooperation

- Multi-level human interfaces
- Advanced architectures
- House of the future
- Internet interfaces for robotics
- Underwater, surface, air, space, ...



So where are we?

- Lots of open problems:
 - -Object recognition
 - -Human intention inference
 - -Mobility and power and comms and
- Lots of successes:
 - -Ready for deployment
- The Robot Revolution is underway
- ... and they're peaceful: Co-robots



