



System Re-tasking to Achieve Resilience in an SoS

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Outline



Motivation

• Representation of an SoS

• Analytic framework

- Illustrative example
 - -Notional 5-node SoS
 - -Results and discussion
- Summary and Future work



Motivation



• What is resilience?

—"Resilience is the ability of a system or organization to react to and recover from disturbances at an early stage with minimal effect on its dynamic stability"

(Resilience Engineering: Concepts and Precepts (2010))

• Historical approach:

- Improve resilience through over-design
- -Traditional systems engineering practices anticipate and resist disruptions
- -Resilience incorporated through classical reliability methods:
 - Redundancy
 - Preventive maintenance





- Not suitable for SoSs:
 - -Heterogeneity, geographical distribution, interdependencies
 - -Backup systems are costly and impractical

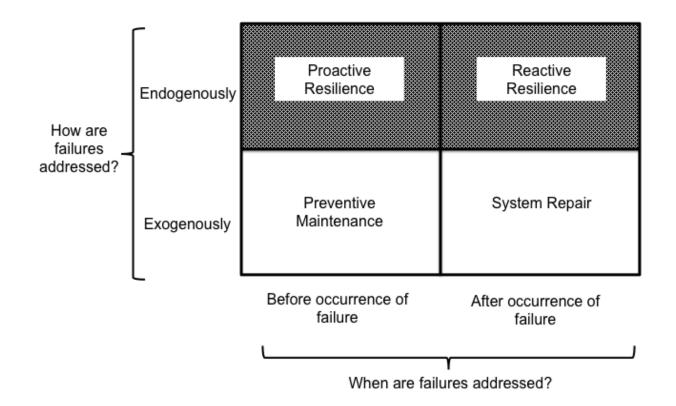
- Stand-in redundancy:
 - Compensate for loss of performance in one constituent system by re-tasking remaining systems
 - As one node experiences degradation, other nodes can alter their operations to compensate for this loss
- Raises interesting questions:
 - -Given a system failure, what is the best configuration to compensate for the loss?
 - —What level of performance can be recovered with new configuration?
 - -What is upstream effect of stand-in redundancy on development costs and risks?





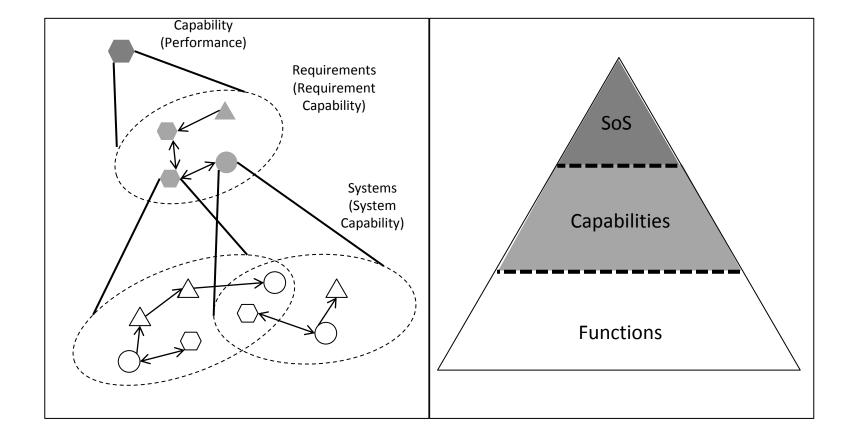
• Impact of stand-in redundancy on resilience of SoS:

- -Reactive Resilience
- -Proactive Resilience











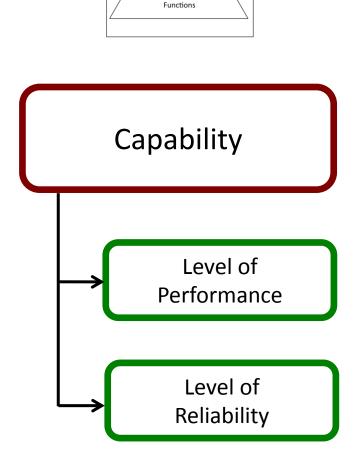
SoS Representation



- Consider metrics at capability level:
 - -Level of Performance (LoP)
 - -Level of Reliability (LoR)

 LoP depends on systems, functions, performance metrics, interdependencies

 LoR depends on reliability of individual systems

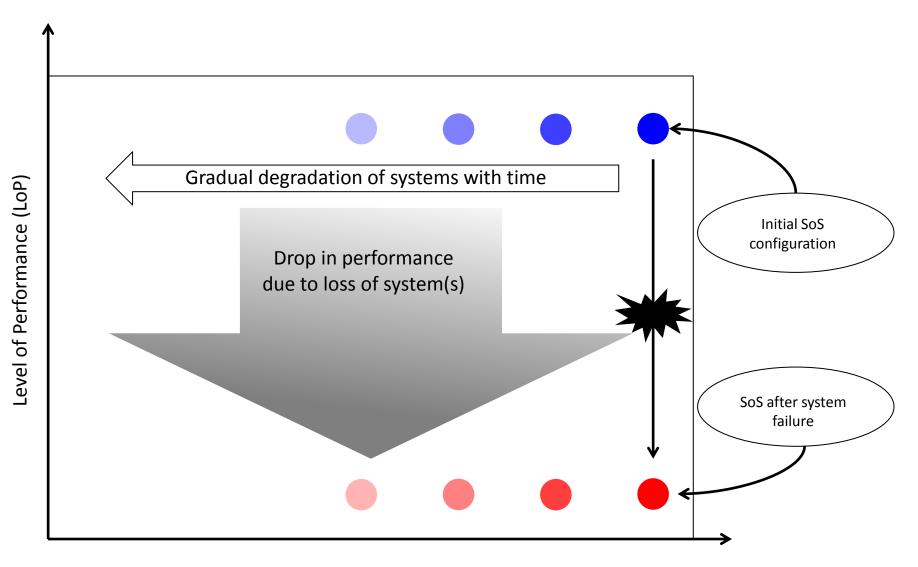


Capabilitie



Analytic framework



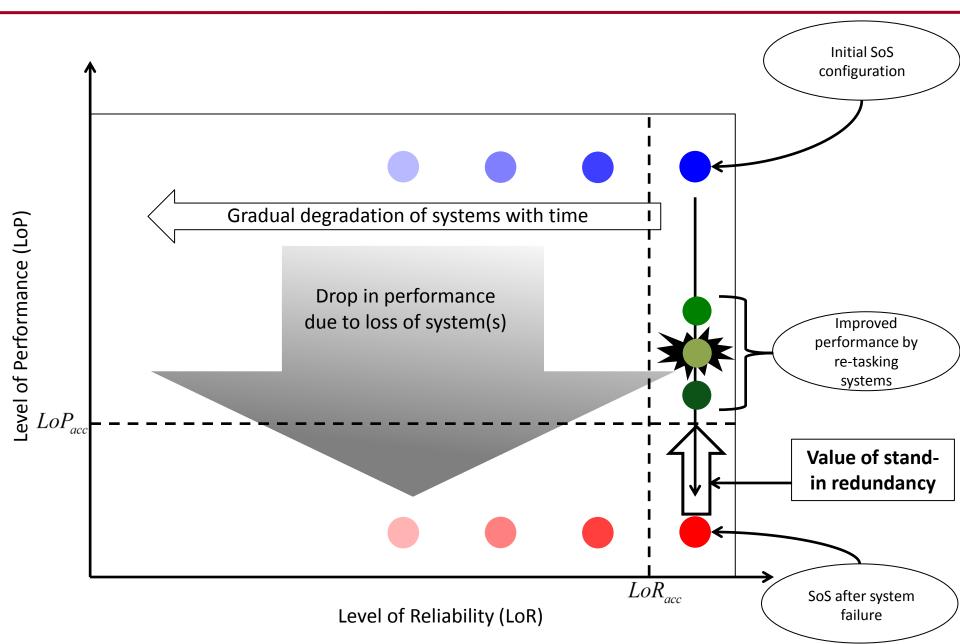




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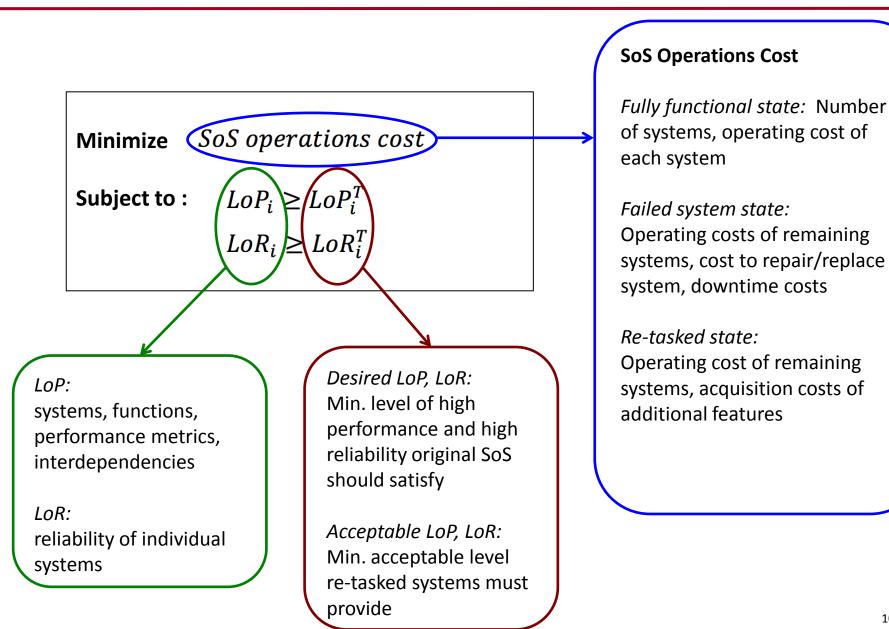






Analytic framework

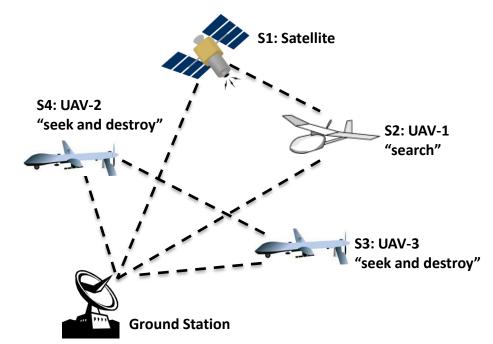






Illustrative example





Features available on each system:

UAV1: High-definition camera UAV2: Basic camera + weapons UAV3: Basic camera + weapons

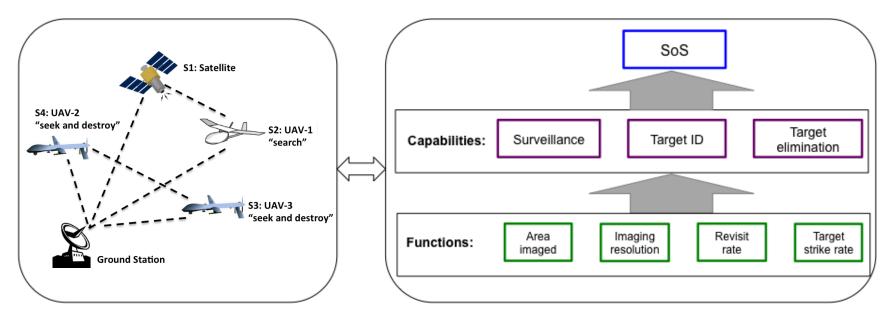
Capability	Description Systems Needed	
C1	Surveillance	S1
C2	Target identification	S1, S2
C3	Target elimination	S3, S4



Illustrative example



• Representation of SoS:





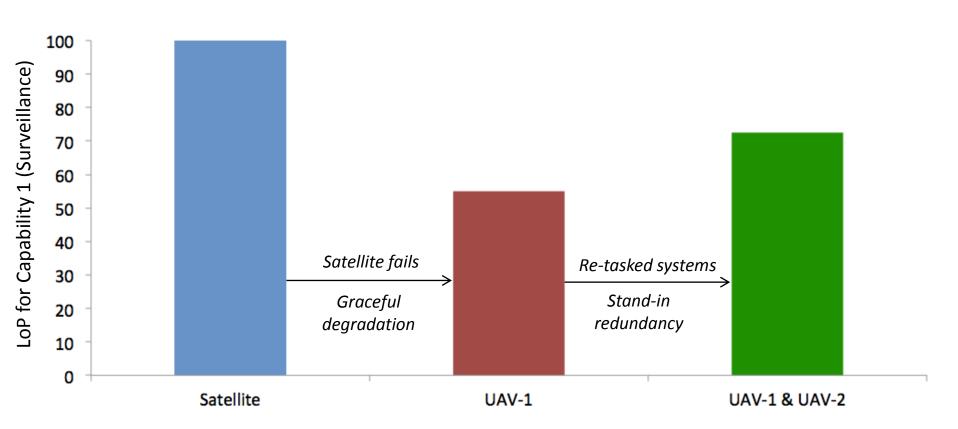


Systems and functions

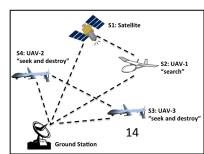
Systems	Individual system functions/features			
	Area imaged	Imaging resolution	Revisit rate	Target strike- rate
Satellite	~	~	✓	-
UAV-1 "search"	✓ ↑	✓ ★	✓	-
UAV-2 "seek and destroy"	* 1	 * 1 	✓	 ✓
UAV-3 "seek and destroy"	~	✓ ♠	✓	~

- Modifications/enhancements in SoS:
 - -Features on satellite cannot be changed
 - -Easier to retrofit UAVs with higher performance devices
 - -(UAVs can also be reprogrammed for higher revisit rates)





Systems that contribute to Capability 1 (Surveillance)



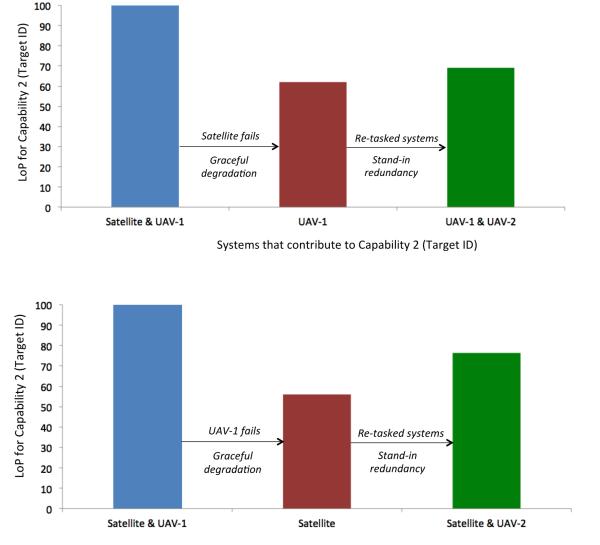
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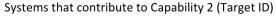
AERONAUTICS

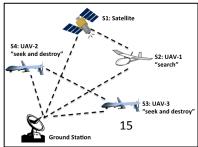
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Results: Target identification (C2)







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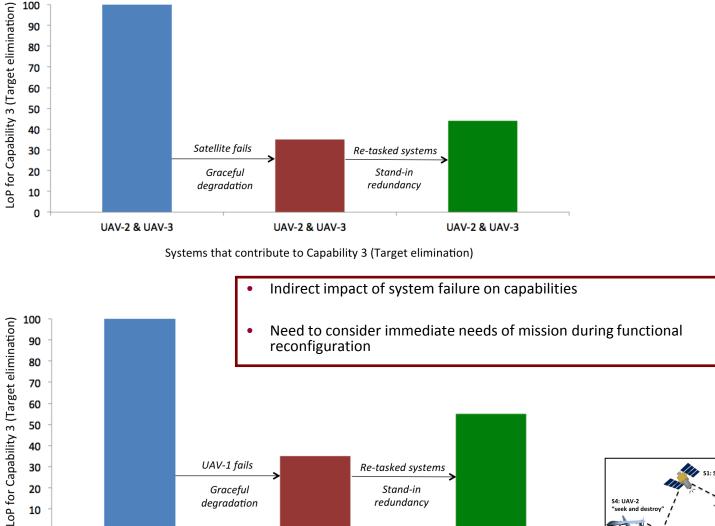
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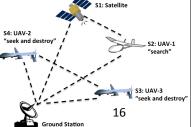


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UAV-2 & UAV-3

Results: Target elimination (C3)





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Systems that contribute to Capability 3 (Target elimination)

UAV-2 & UAV-3

UAV-2 & UAV-3



Discussion



- Using stand-in redundancy, systems can:
 - -Contribute to SoS-level capabilities in ideal case, and
 - "Stand-in" for failed functions during failures

- Limit to level of stand-in redundancy that can be incorporated —Appropriate resource allocation
- Need to consider balance between *resilience*, *costs*, and *adaptability* of the SoS
 - -For example, multi-modal transportation networks are designed for long lifetimes with gradual modifications and/or upgrades





• Large scale SoSs evolve with time along with changing environment

 This approach indicates incremental enhancements/modifications to existing systems can provide inherent resilience

 Approach can help decision-makers quantitatively assess resilience of different SoS architectures

- Future work:
 - Expand static model to dynamic model (resilience under uncertainty)
 - -Track system degradation with time (proactive resilience)
 - -Consider multi-system failures