# **UCS** Architecture

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**GRCCE February 2016** 

## **UCS** Architecture

#### **UAS Control Segment (UCS) Architecture**

- OUSD(AT&L) ADM for DoD UAS Groups 2-5, February 2009.
- OUSD(AT&L) funded development through April 2015.
- Public Release of R3.4

Emerging as DoD information architecture for controlling Robotic and Autonomous Systems (RAS) in all domains

- Currently managed by SAE AS-4 (Unmanned Systems). Portfolio now includes both JAUS and UCS Architecture.
- Extended by Navy for surface and subsurface RAS (UCS-M).
- NAMC extension for small UAS, ground vehicles, and unattended sensors (soldier/marine common controller).





## Why is UCS different?

### **Conceptual Interoperability** - how things relate

UCS provides a comprehensive **Conceptual Data Model (CDM)** of the resources in the RAS domain and their objectives, missions/tasks, data products, and environment. *All information architectures must interact with the same real-world objects*. *This is how SoS integration becomes possible*.

### **Pragmatic Interoperability** – accessing capabilities

UCS defines a **Service Oriented Architecture (SOA)**, which exposes RAS the capabilities via message exchanges. *Exchanged messages project to the CDM and therefore are conceptually related. The SOA ties these messages to real-world effects/actions* 

### Semantic Interoperability - messages/data

UCS provides an extensive Logical Data Model (LDM), which defines how the state values in message exchanges (e.g. vehicle position) are to be interpreted within a particular system. The LDM provides a machine-readable definition of state information and any required conversions between systems.



## UCS roadmap under SAE

Plan for AS6512 Rev A, end FY17



