

## Verification of Autonomous Systems

# Alessandro Pinto United Technologies Research Center, Berkeley, CA

This document does not contain any export controlled technical data.

## **Outline**

- Introduction
- Verification and autonomous systems
- Thesis: Verify what the system knows and understands rather than what the system does
- Our contribution in the DARPA ALIAS program

## United Technologies Business Units

#### **Otis**

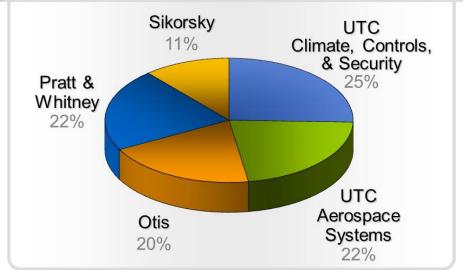


UTC Climate, Controls & Security



2014 Sales: \$65.1 billion

Segments: 45% Commercial & Industrial, 55% Aerospace



Pratt & Whitney



#### **UTC Aerospace Systems**



## **Applications**

#### **UTRC** interest

#### Autonomous rotorcraft

## SARA Pilot CBS FLYING SOLO CBS FLYING SOLO MONTH WITH HOMOLOGY COAD MINACE CO PLOTS MONTH OF MONOCOOP COAD MINACE CO PLOTS

Field Operator

CES RYNGSOLD

WINDSOLD CARDINAL COARD

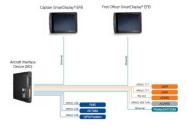


## ISR missions



#### **UTAS EFB**





Source: utasaerospacesystems.com

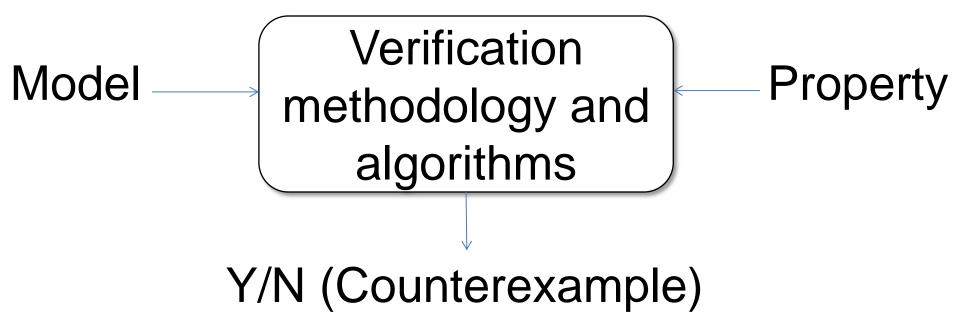
#### **Intelligent Buildings**



Source : ccs.utc.com

## Verification

General definition



## Verification

The known case

Model

-Simulink

-Code

-...

Verification methodology and algorithm

- Model checking
- Testing

- . . .

## **Property**

- -Requirements
- -Common sense

- . . .

Y/N (Counterexample)

## Verification

#### Autonomous systems

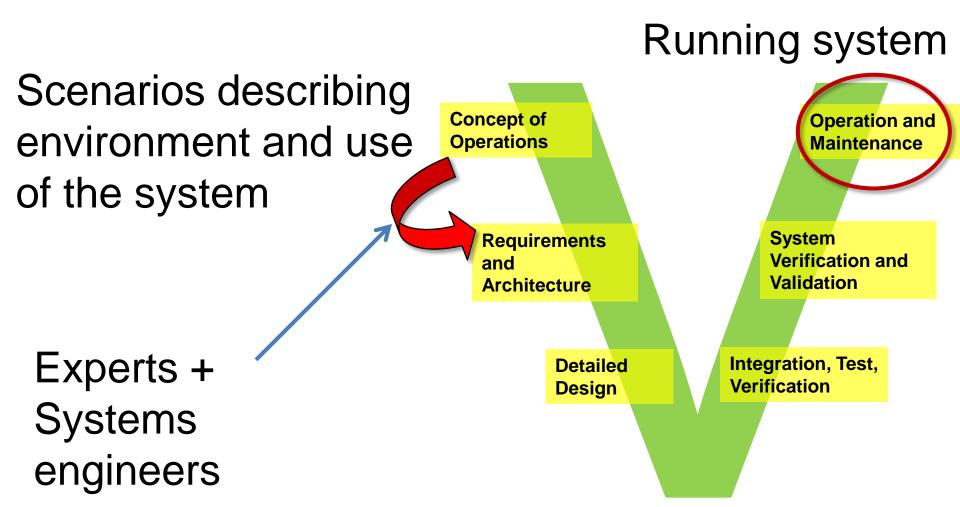
Model? (Environment?, Perceptions?, Decision Making?) Verification methodology and algorithm? (can't be define until we know Model and Property)

Property?
(Not designed to do one thing)

Y/N (Counterexample)

## Traditional System Design

From CONOPS to Operations

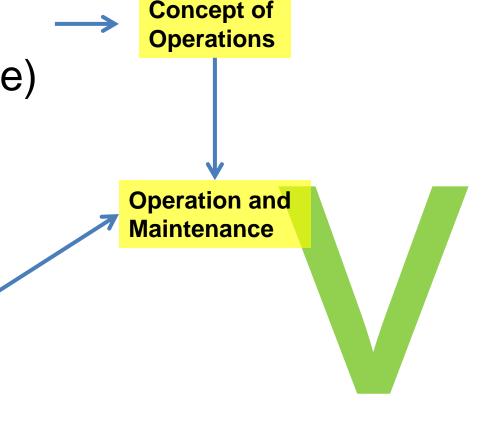


## Autonomous Systems

Operations on CONOPS

Mission objectives, constraints, relevant facts (function of time)

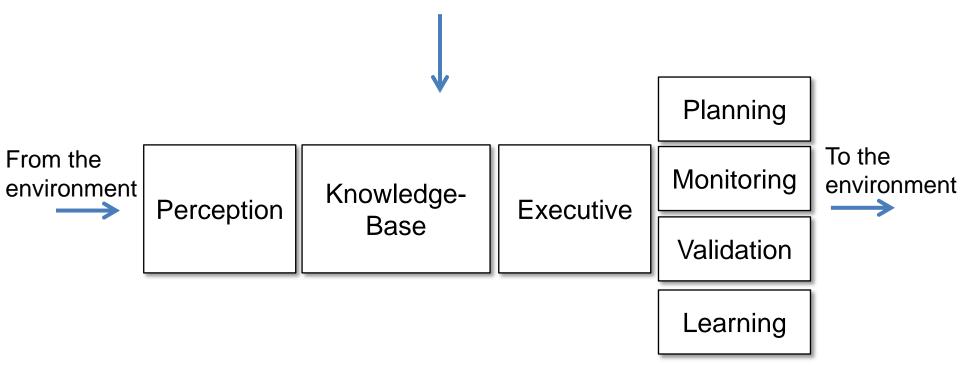
Needs to know/understand the subject matter



## Knowledge-Based Systems

#### Archetype

Mission objectives, constraints, relevant facts (function of time)





#### Knowledge Capturing and Verification

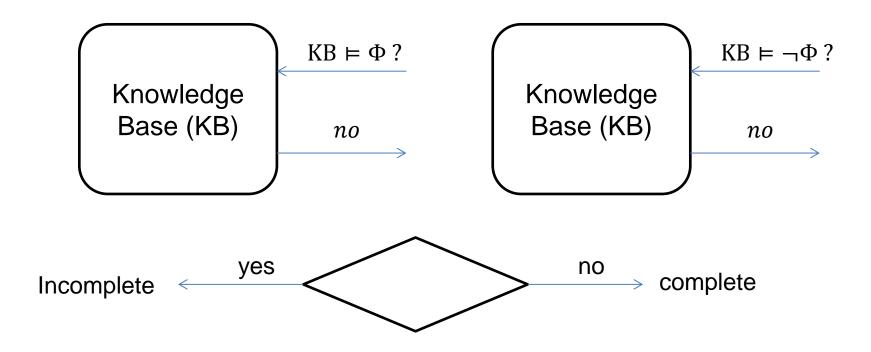
Presented by Alessandro Pinto
United Technologies Research Center, Berkeley, CA

This research was funded by the Defense Advanced Research Projects Agency (DARPA) Aircrew Labor In-Cockpit Automation System (ALIAS) program. The views, opinions and/or findings expressed are those of the author(s) and should not be interpreted as the official views or policies of the Department of Defense or the U.S. Government.

## Completeness

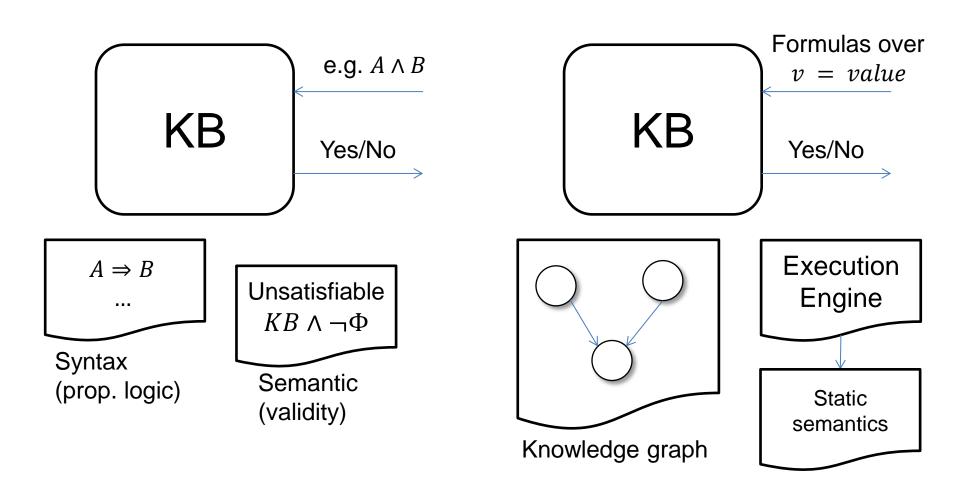
#### General definition

Is there a query  $\Phi$  such that:



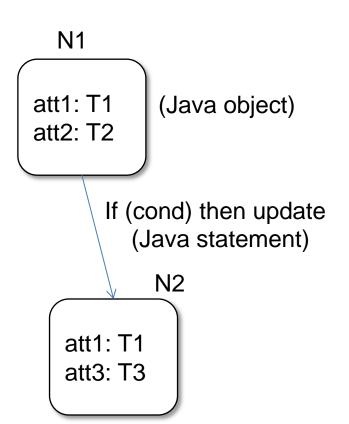
## Completeness

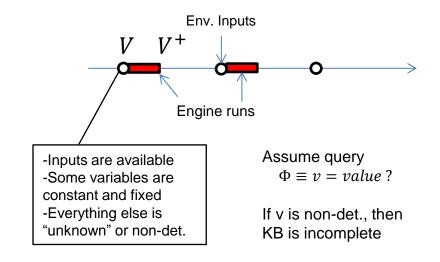
#### Examples of knowledge bases



## Completeness of Knowledge Graphs

Syntax, semantics, and structural rules





#### Rules:

- No cycles
- No leaf nodes
- Nodes with common child update different variables
- All variables are updated by some node
- All variables are read

Analyze dependencies

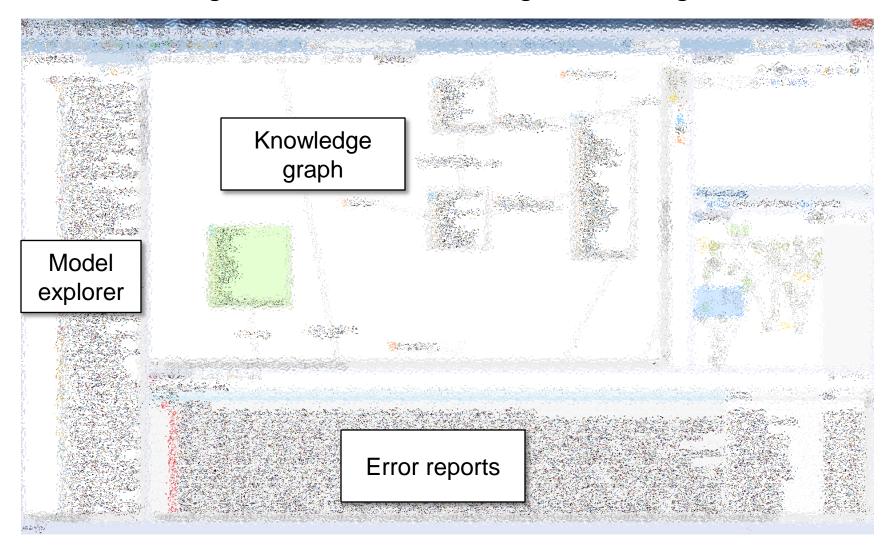
Build abstract graph

Check rules

Generate report

## Completeness of Knowledge Graphs

Integration in the knowledge modeling tool

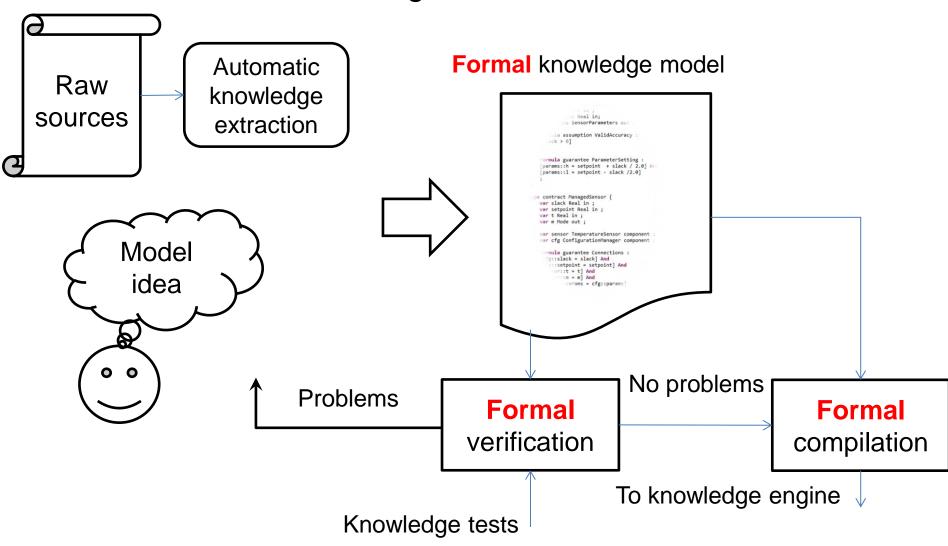


### Lessons learned

- Knowledge graphs easy to understand by software engineers
- Not as powerful as declarative knowledge
- Verification is hard on generic code leading to spurious error reports (conservative abstraction)
- If fast, verification can be integrated in the knowledge modeling process
- Verification needs to be precise: avoid confusing users and loosing trust

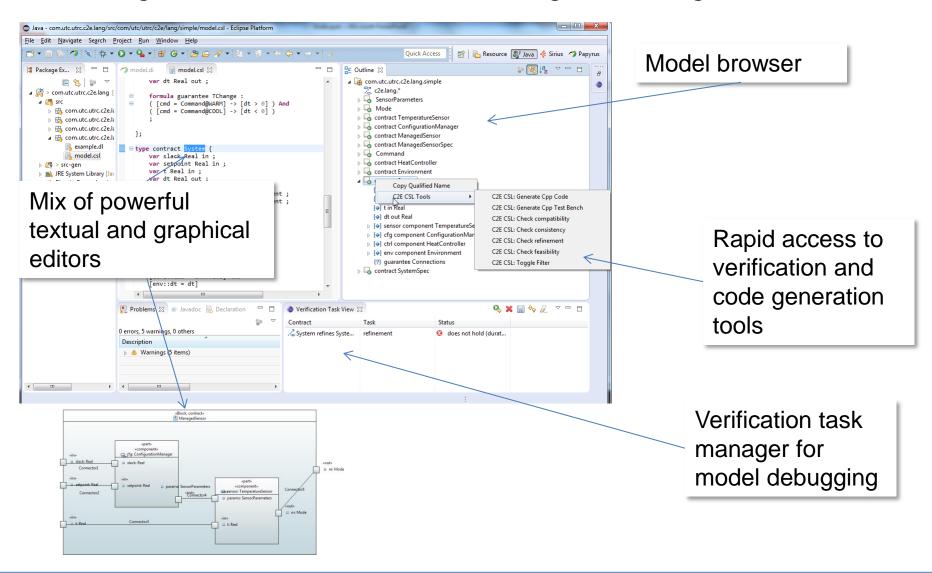
## **Process**

From knowledge sources to execution



### **Tools**

An integrated environment for knowledge modeling and verification



## Conclusions

- Autonomous systems solve new class of problems
- A new design and verification method is needed for autonomous systems
- Verification should focus on what these systems know and understand