



Implementation of Clustering Analysis in Engineered Resilient Systems Tools for Enhanced Trade Space Exploration of Military Ground Vehicles

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Background and Motivation



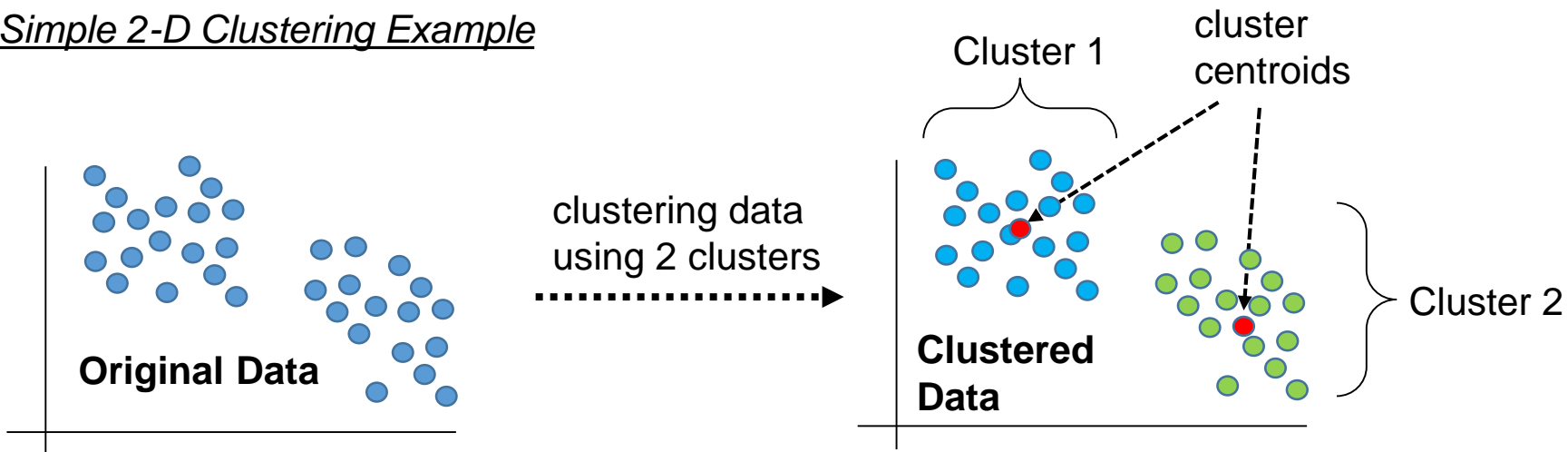
- Performing multidisciplinary design optimization of a military ground vehicle is extremely challenging
- One challenge is related to analyzing large, highly dimensional vehicle design datasets
- Analysis questions to answer regarding these datasets:
 - Do my highest-ranked designs reside in multiple regions of the trade space?
 - How many promising regions are there?
 - Does each region represent variations on a single design concept or multiple design concepts?
 - How can I best characterize the unique features of each design concept?



Clustering

- Simply put, clustering is the process of assigning data points to groups based on how closely their values are to a common group centroid
- A way to group data that is highly dimensional
- Different algorithms available
- Machine learning technique

Simple 2-D Clustering Example





Clustering for Trade Space Design Populations



- Reduce large, highly dimensional datasets to more manageable, digestible sizes. This can make it easier to draw conclusions
- Automated way of quantifying and qualifying design differences - **characterizing**; may help answer the question of : “How different are the top ranked vehicle designs?”
- Clusters could be used to provide promising vehicle design groups, and therefore promising characteristics, to be taken to the next stage of vehicle development

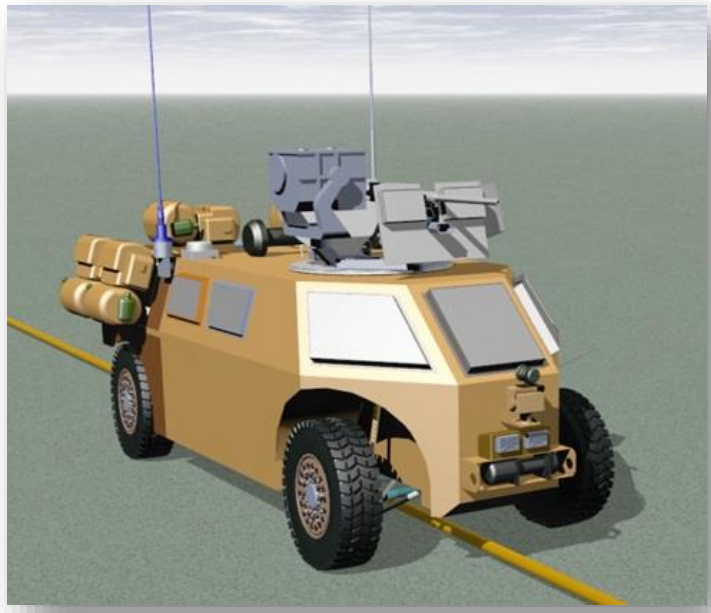


ERS LRV Trade Space Exploration Project



Objectives

- Learn, evaluate, and provide feedback to developers of **CREATE-GV** and **ERS Tools**
- Apply these tools to the **LRV notional concept vehicle** to perform **trade space exploration**
- Develop new trade space exploration methods for ground vehicles



CREATE-GV: Computational Research and Engineering Acquisition Tools and Environments – Ground Vehicles

ERS: Engineered Resilient Systems

LRV: Light Reconnaissance Vehicle



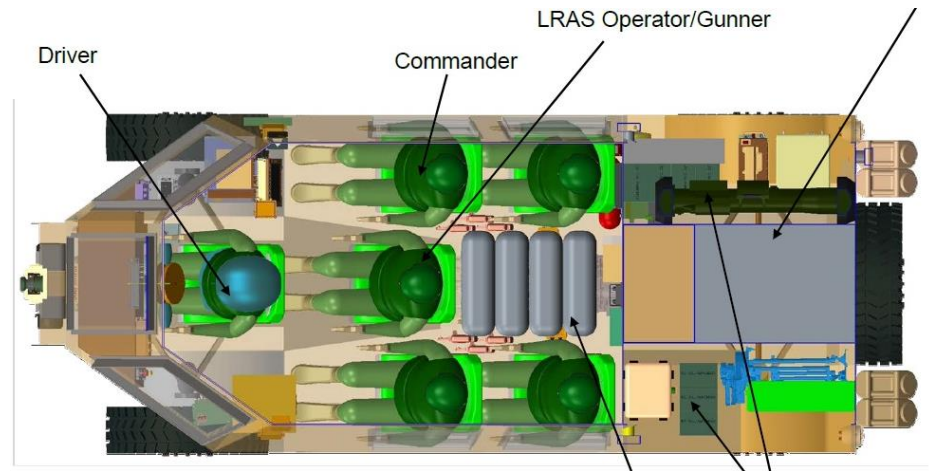


LRV – A Notional Concept for a New-Start Vehicle



Notional concept was initially developed based on these requirements:

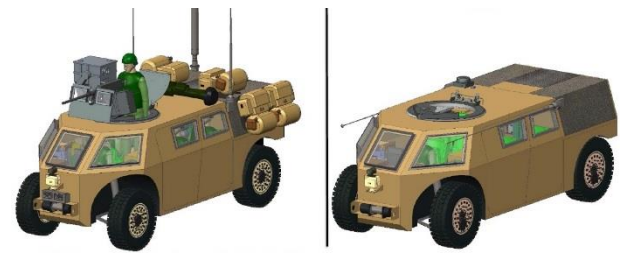
- Crew of 6
- Power for 96-hour mission
- Silent watch, silent move
- Advanced reconnaissance & surveillance equipment package
- CH-47 internal transport and sling-load transport



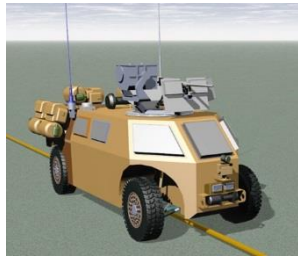


Trade Space Exploration Process

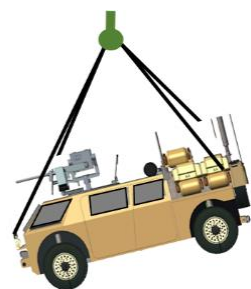
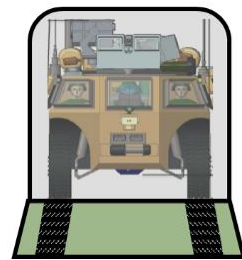
Reviewed initial **concept** & **requirements**



Performed **analysis** to build trade space



Revisited **concept** & varied **requirements**



Performed **analysis** to expand trade space



Generated new design set = new **concept**

*Iterative
Concept-
Analysis
Loop*

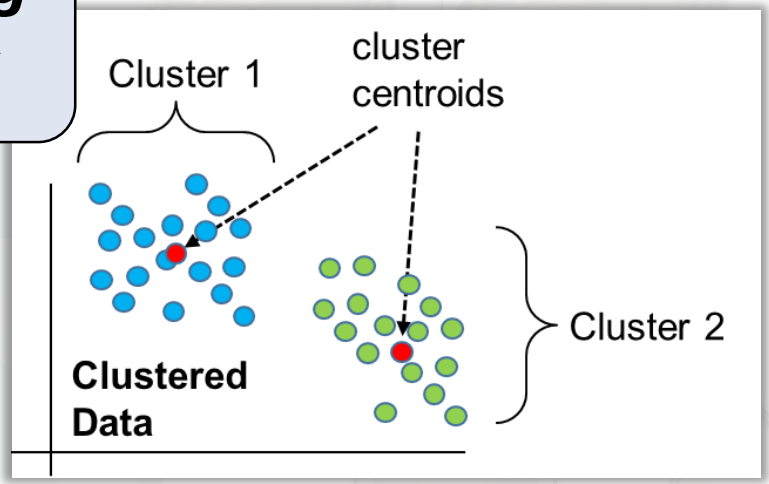


Trade Space Exploration Process

Reviewed initial concept & requirements

Clustering Analysis

Performed analysis to build trade space



Revisited concept & varied requirements

Iterative Concept-Analysis Loop

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Trade Space Construction in ERS TradeBuilder

- CREATE-GV**
- 1 On-Road Speed
 - 2 Off-Road Speed
 - 3 Max Sandy Grade
 - 4 Off-Road No-Go %
 - 5 Soft-soil mobility

ERS TradeBuilder

- 1 Surveillance
- 2 Crew
- 3 Stability
- 4 Silhouette
- 5 Power density
- 6 Survivability
- 7 Transportability
- 8 Lethality

Performance Metrics imported from result files

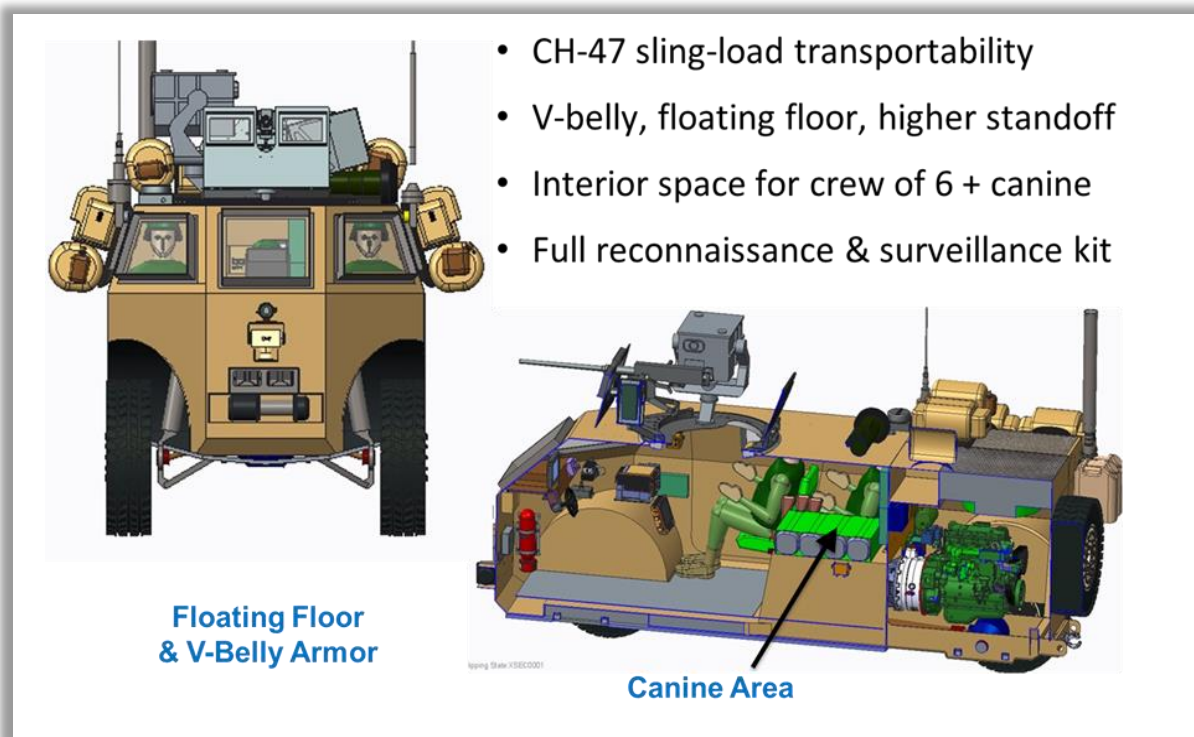
Performance Metrics evaluated in ERS TradeBuilder

Design Variables

	<i>Design Variables</i>				<i>Performance Metrics imported from result files</i>					<i>Performance Metrics evaluated in ERS TradeBuilder</i>					
	#	H	L	W	...										
<i>Designs</i>	1	H ₁	L ₁	W ₁											
	2	H ₂	L ₂	W ₂											
	3	H ₃	L ₃	W ₃											
	4	H ₄	L ₄	W ₄											
	⋮														



- Common features from highest-ranked designs:



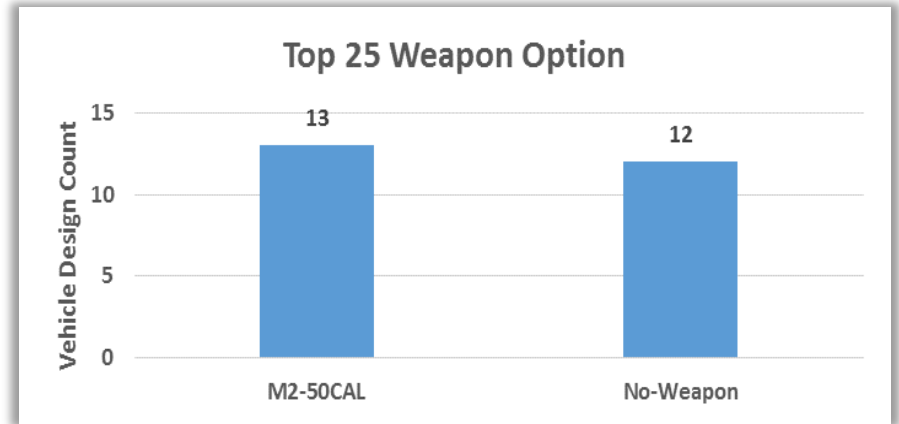
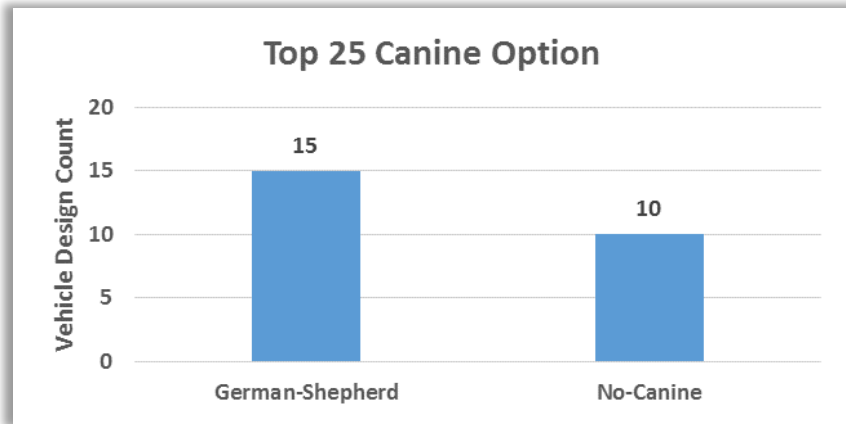
These are general features typically seen in the top 25 ranked vehicles, **though not all of the top 25 designs had the same features**



Trade Space Vehicle Design Characterization



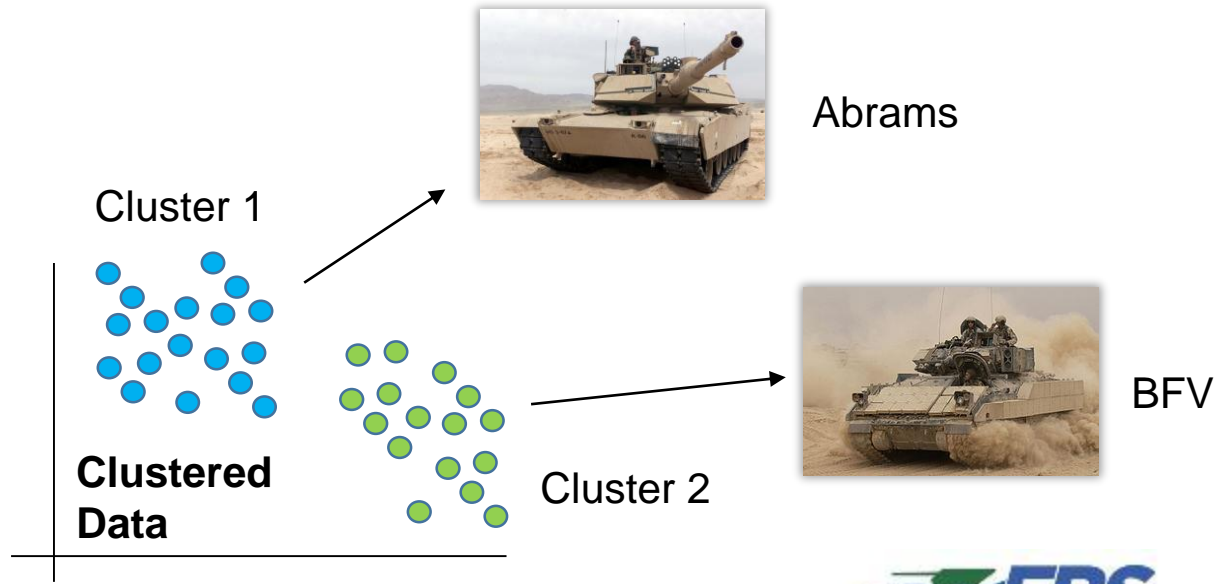
- Two areas where differences are seen in the top 25 designs :



- Characterizing the top ranking designs as a whole may not lead to as useful conclusions regarding which features a single vehicle design should have
- We could be **unintentionally characterizing multiple vehicle designs, multiple variants**, a potential outcome when performing multi-objective design optimization

- Early in the concept development phase, the trade space is large, with a design space that could be spanning regions consisting of two or more completely different vehicle designs
- ... and this is not apparent
- We want to understand if potential regions exist early on in the analysis process to understand what unique concepts we may have

Potential example outcome of early concept, highly dimensional, multi-object design optimization

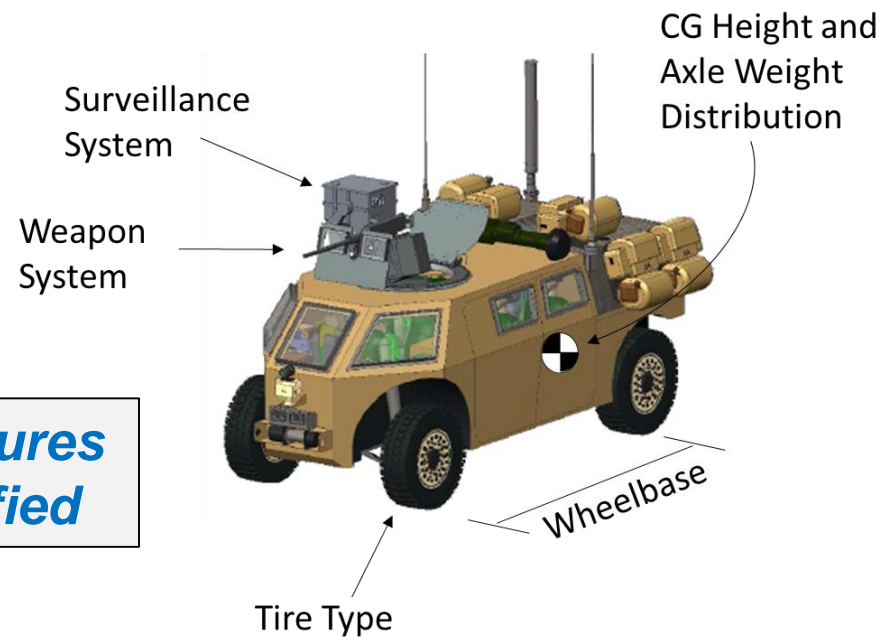




Clustering Analysis - Setup

- **K-means clustering** algorithm used within R (“Hartigan-Wong” version)
- **Chose to generate 10 clusters** based on the “within sum of squares (WSS)” count selection method
- Design variables and characteristics chosen for features:

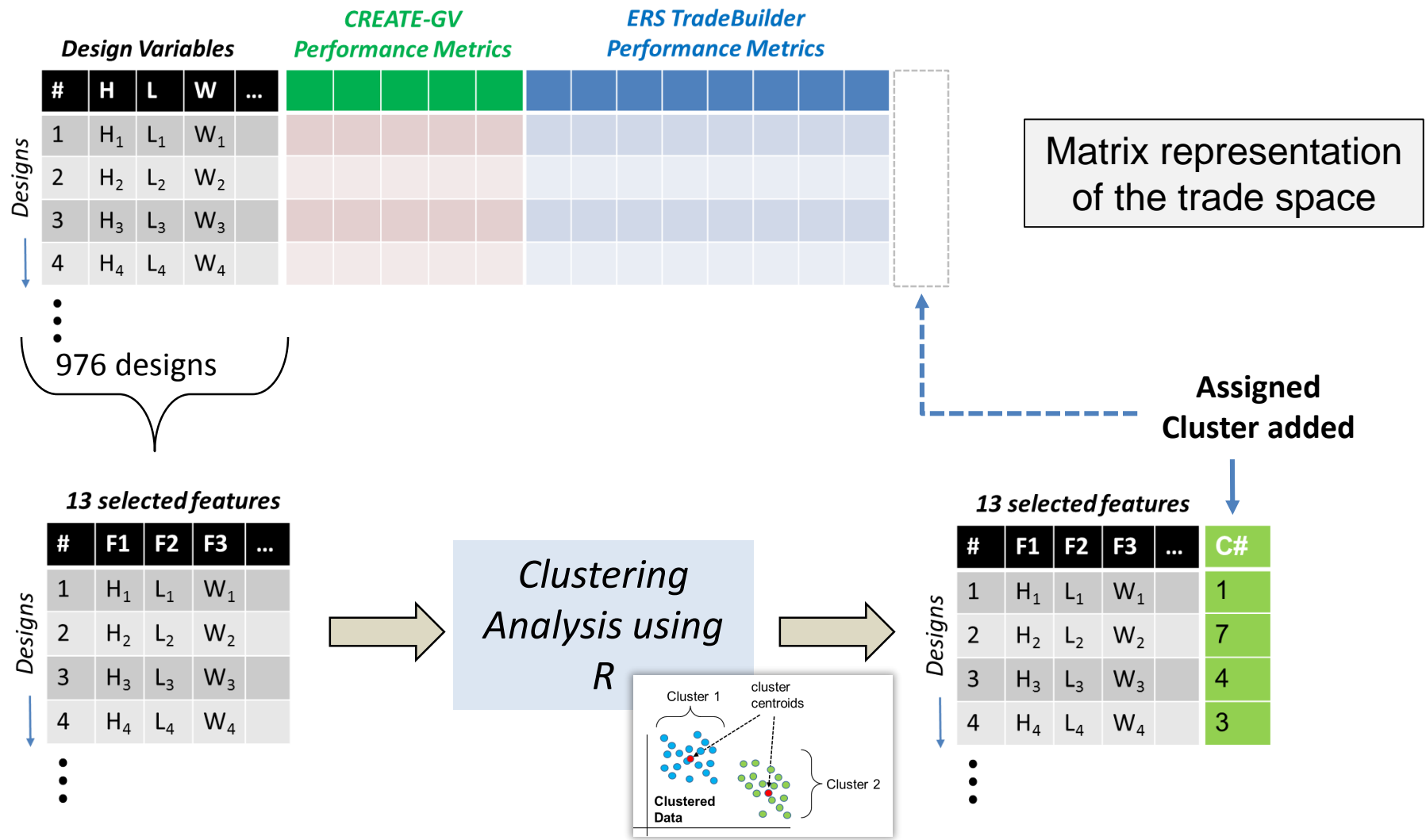
13 features specified



- Suspension characteristics (damping ratio and ride frequency) for the front and rear axles
- Canine
- Crew size
- Armor weight



Clustering Analysis - Setup

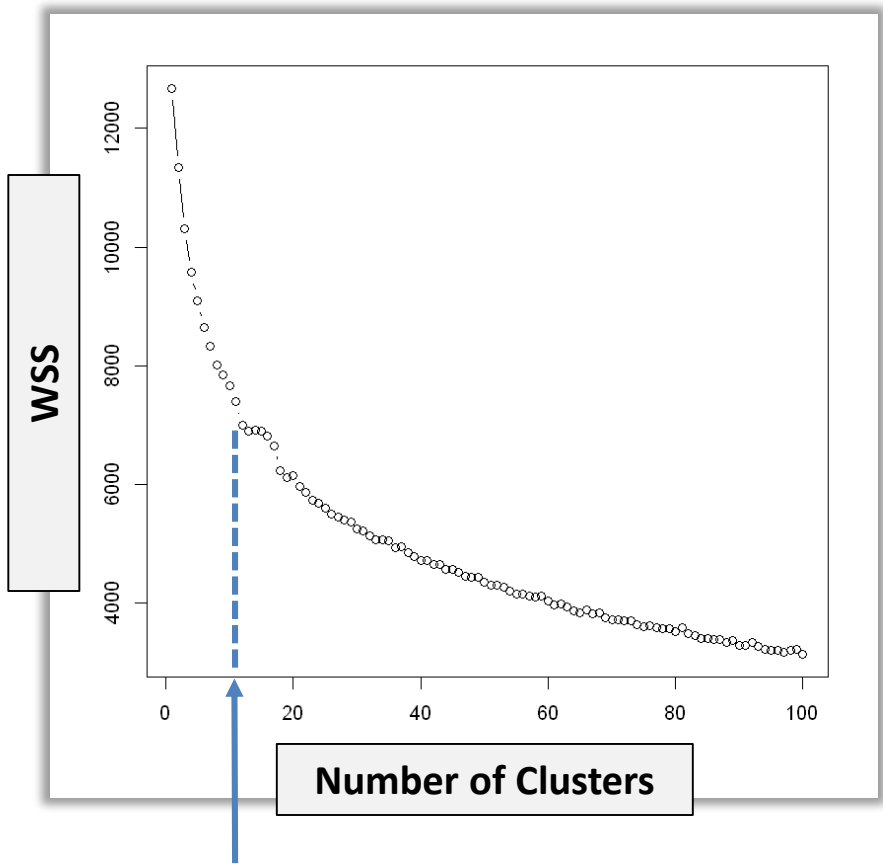




Clustering Analysis – Selecting Cluster Count



- Within Sum of Squares cluster count selection method (WSS)



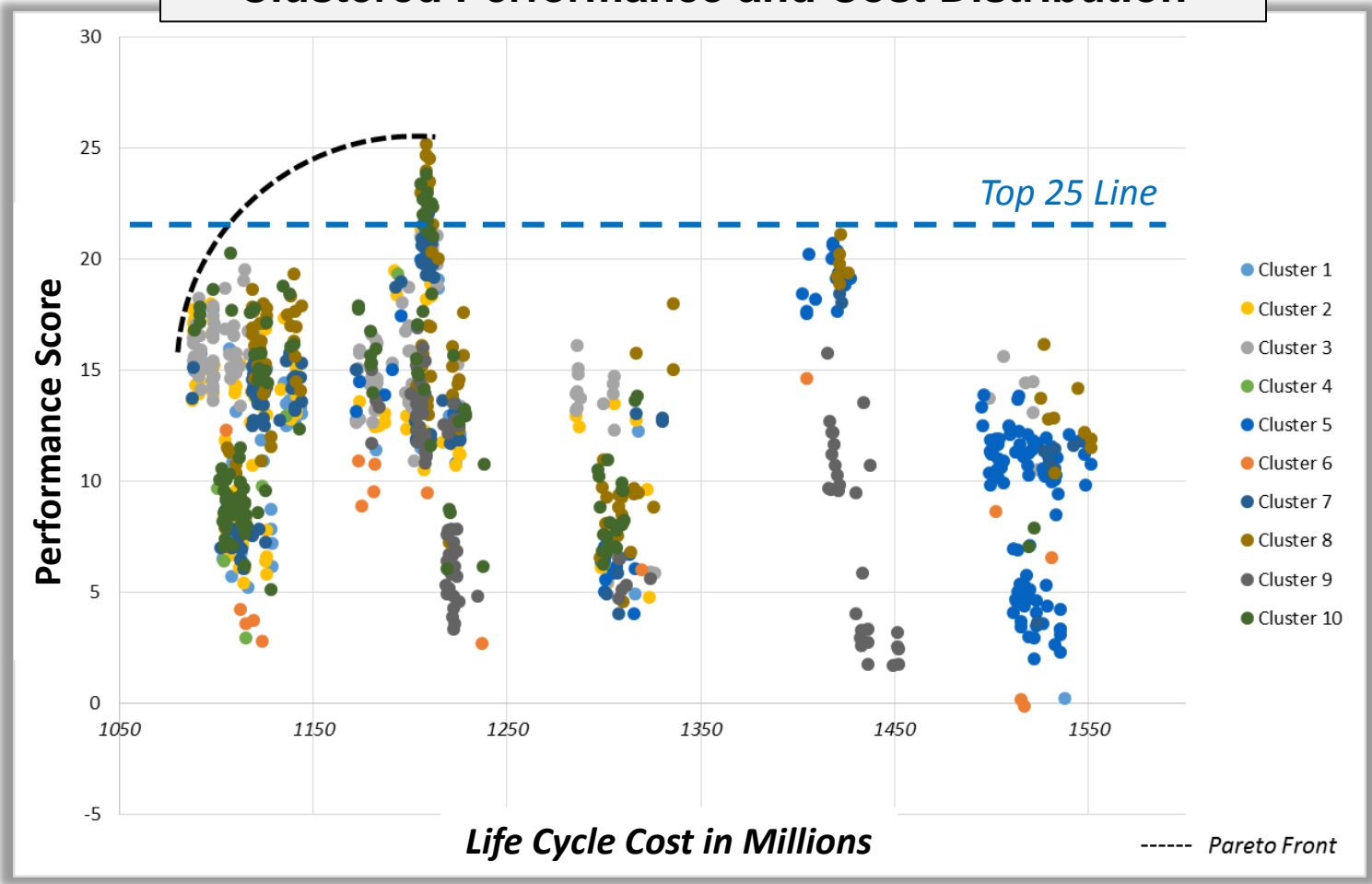
10 Clusters

... at 976 clusters, the sum of squares value would equal 0



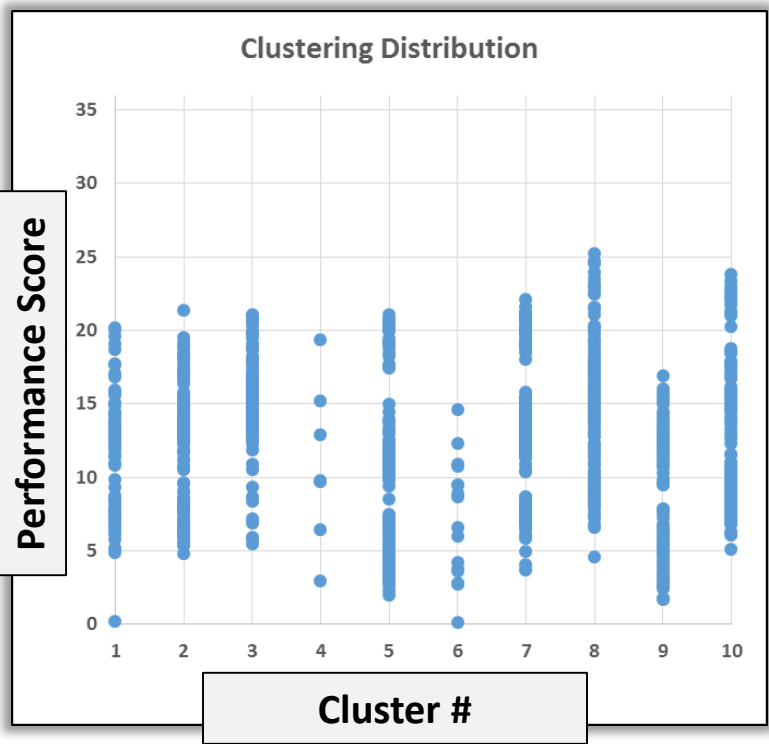
Clustering Analysis – Results

Clustered Performance and Cost Distribution

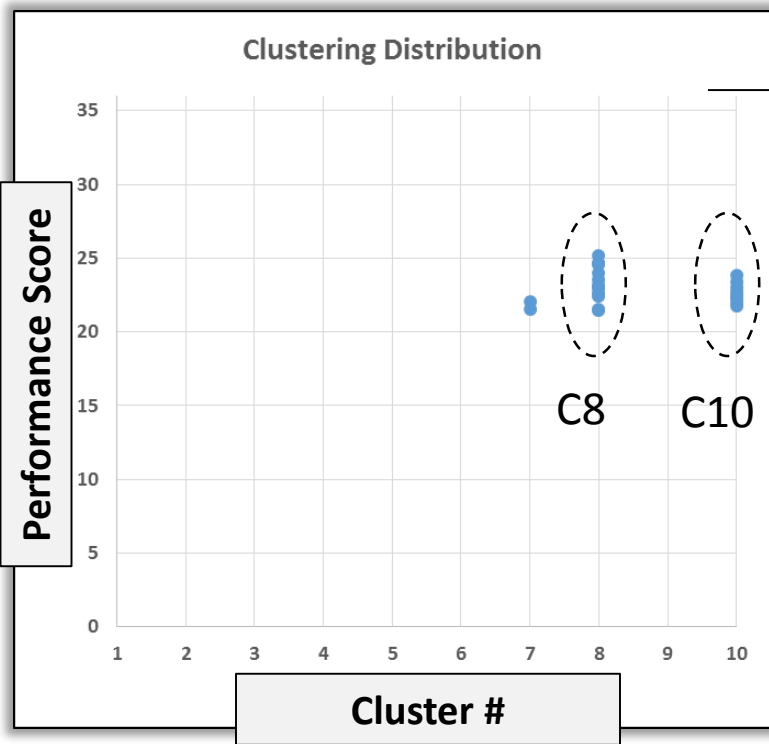




Clustering Analysis – Characterization



Plot shows clustering results using 10 specified clusters for the 976 vehicles designs investigated



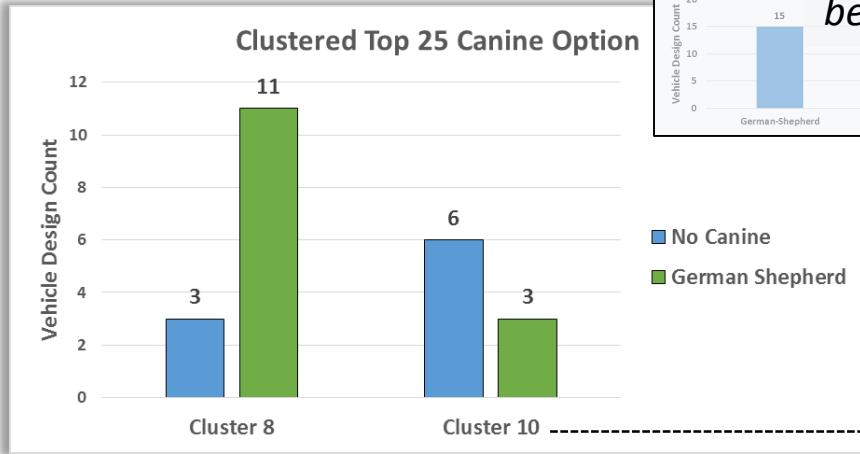
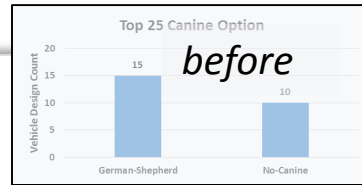
Showing 3 clusters in the top 25:
 Cluster 7 (C7) : 2 designs
 Cluster 8 (C8) : 14 designs
 Cluster 10 (C10) : 9 designs



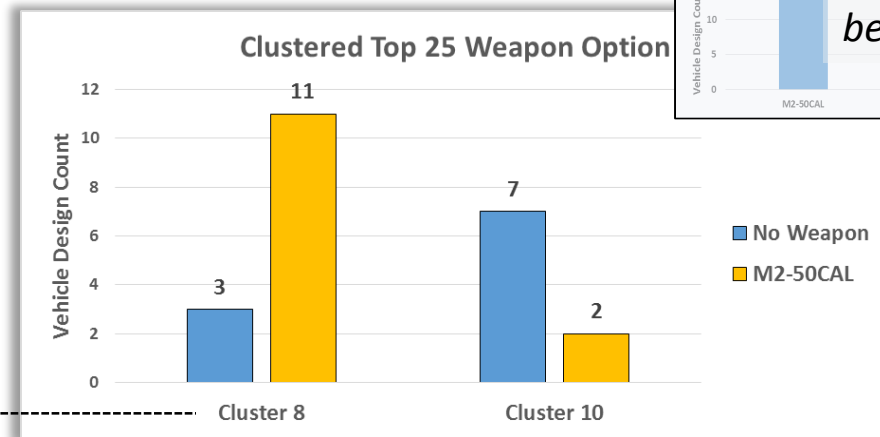
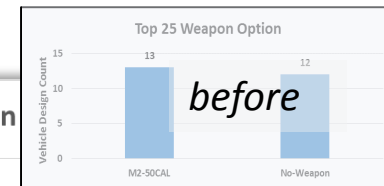


Clustering Characterization Comparison

- Looking at the same two features as before...



Cluster 10 Designs:
Mostly do not include a weapon or canine

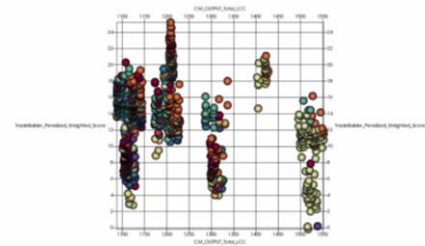
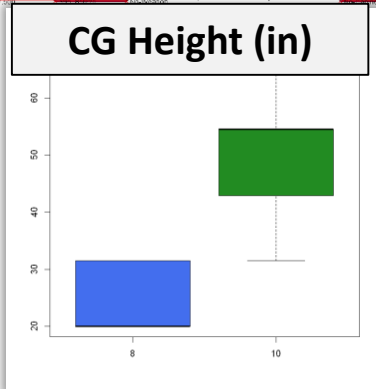
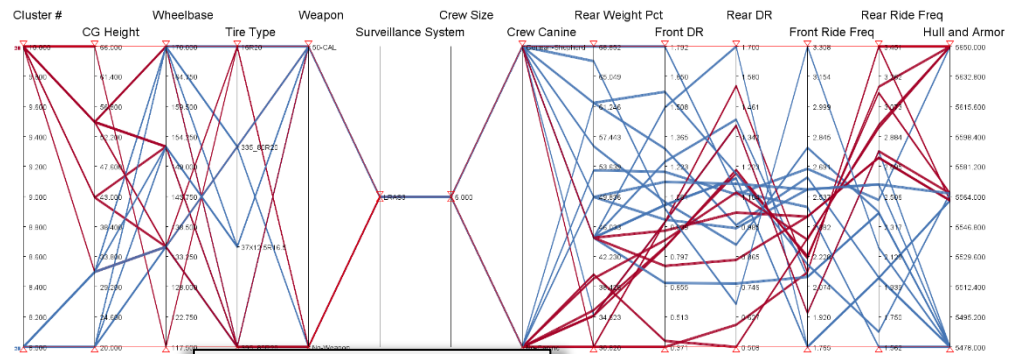
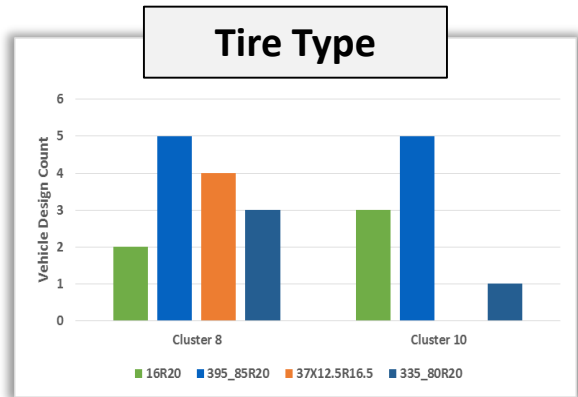
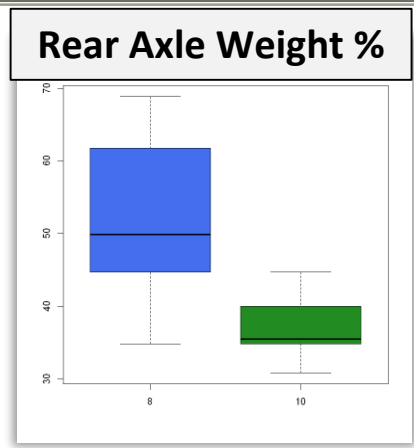


Cluster 8 Designs:
Mostly include weapon and canine



Clustering Characterization - Features

- Various visualizations used to distinguish the differences between the top 25 designs within **clusters 8 and 10** concerning their *design variables and characteristics*





Clustering Characterization - Features

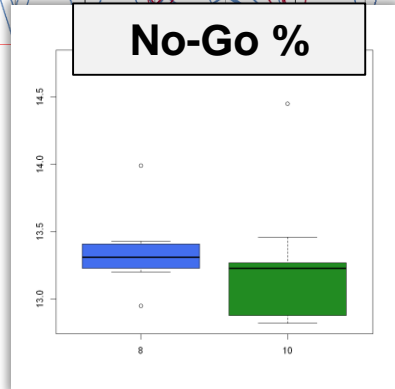
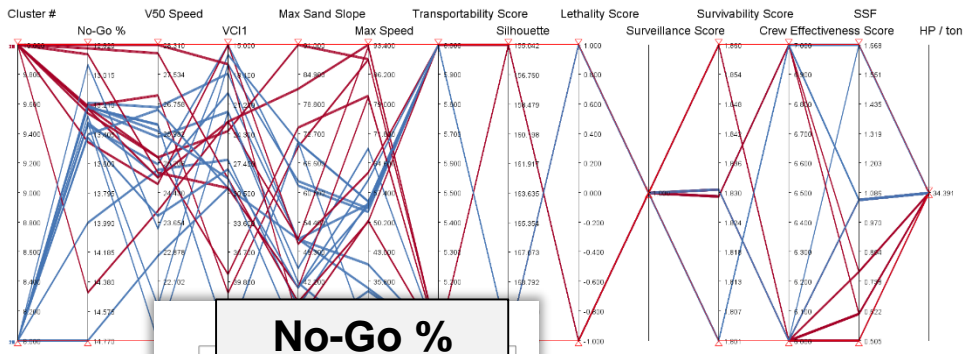
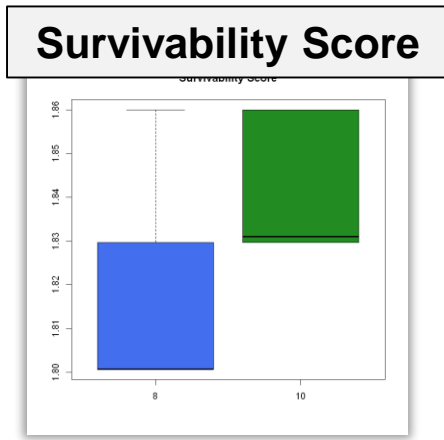
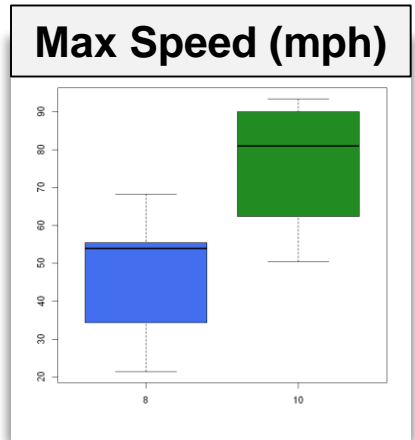
Feature	Cluster 8	Cluster 10
Weapon	Most designs include the M2-50 Cal	Most designs don't include a weapon
Canine	Most designs include a German Shepherd	Most designs don't include a canine
CG Height	Low	High
Wheelbase Length	Longer	Medium
Weight Distribution	More centered to rear heavy designs	More front heavy designs
Front Axle Ride Characteristics	Stiff, Mostly Overdamped	Less Stiff, Underdamped
Rear Axle Ride Characteristics	Stiff, Mostly Overdamped	Very Stiff, Mostly Overdamped

These clustered designs were **similar regarding the Tires, Hull and Armor Weight, Crew Size, and Surveillance System** features



Clustering Characterization - Performance

- Various visualizations used to distinguish the differences between the top 25 designs within **clusters 8 and 10** concerning their *performance*





Clustering Characterization - Performance



Performance	Cluster 8	Cluster 10
<i>Crew Effectiveness</i>	Highest score	Meets requirements
<i>Max Speed</i>	Lower to moderate	Moderate to high
<i>Max Sand Slope</i>	Medium	Medium to high
<i>SSF</i>	High	Medium to low
<i>Visibility (Silhouette)</i>	Larger profile	Smaller profile
<i>Lethality</i>	Higher	Lower

These clustered designs were **similar regarding the Surveillance, No-Go %, VCI1, V50 Speed, HP / ton, Survivability, and Transportability** performance metrics



Clustered Characterization - Conclusions

- Highlighted **two main clusters** in the top 25 ranked vehicle designs and analyzed their features and performance
- Instead of describing one LRV design, now describing **two LRV design variations in the top 25** – two designs that have some distinct differences, but with similar overall performance scores

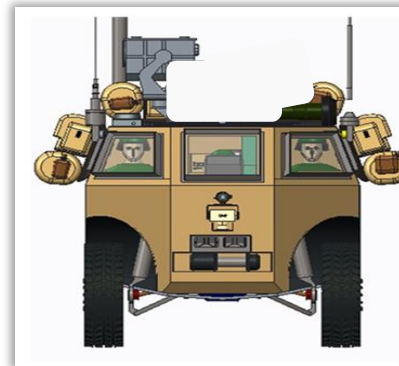
Cluster 8

Well-rounded design concerning all of the areas of performance considered



Cluster 10

Fast, mobile design, with smaller profile



Two potential variants



Conclusions

New trade space exploration process which utilized a **clustering technique** highlighted **two main vehicle variants** out of a set of top performing vehicle designs

- Clustering is a promising trade space analysis process addition to help improve and further automate trade space characterization
- Can help answer important questions about a trade space
- And lead to improved optimal design extraction from trade spaces, and overall improved concept design development
- **More to look into : clustering technique tuning and feature selection**



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