



Analysis of Environmental Impacts on Military Systems

**20th Annual NDIA Systems Engineering Conference
October 26, 2017**

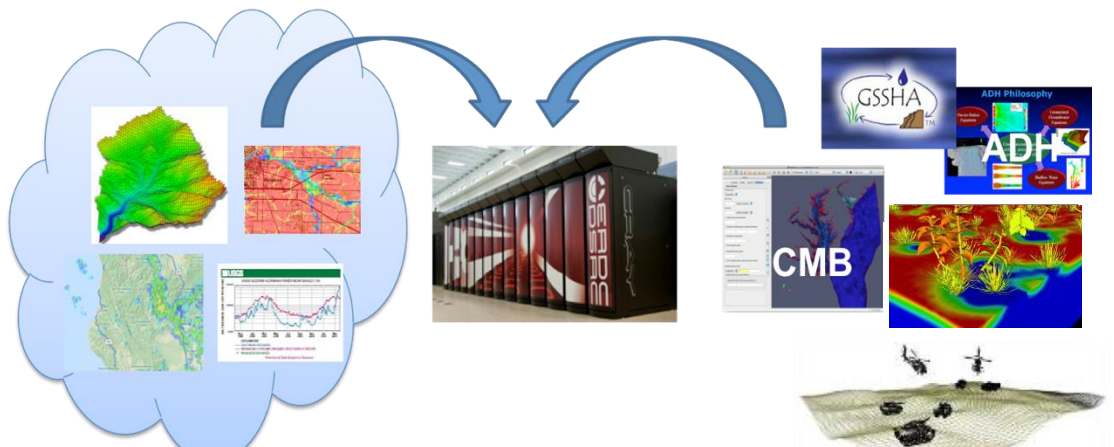
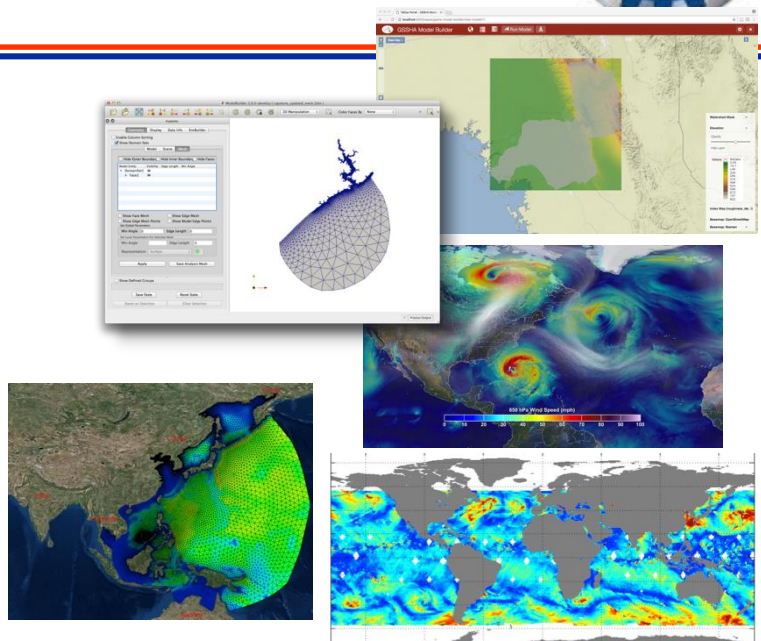
**Dr. Dharhas Pothina
Associate Technical Director
US Army Engineer Research and Development Center**



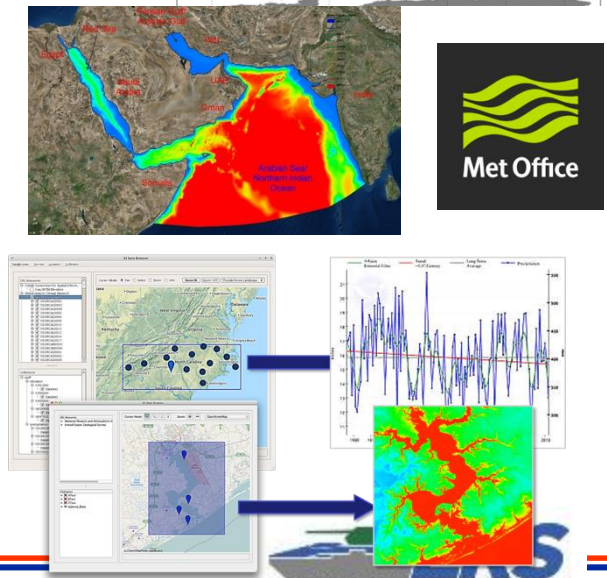
Environmental Simulation

- Data Access/Archival
- Hi Fidelity Physics
- Tradespace Analytics
- Advance Computing Infrastructure

MILITARY SYSTEMS



High Resolution Global Capability with Rapid Turn Around





Why



- **Gaps:**

- DoD has an explosion of environmental data but access and retrieval is difficult
- Demand within DoD for data has expanded but it is challenging to efficiently utilize
- DoD lacks capability to produce high-fidelity, predictive, environmental physics for the entire globe to support operations and acquisitions
- Data sources within the DoD have a scale and parameter mismatch (weather, terrain, etc.) for many classes of problems (operational, in-depth analyses, ...)

- **ERS Approach:**

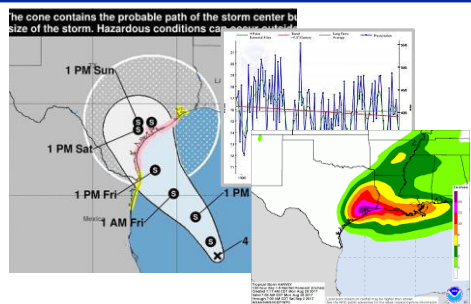
- Develop a modular HPC enabled framework to discover, simulate, and retrieve environmental data
- Develop high-fidelity scene generation and environmental simulation tools
- Demonstrate modeling of environmental scenes worldwide

- **Leverage:**

- DoD, federal, international, geospatial data, and environmental-modeling frameworks
- Army ERS program
- Studies directed by Army MSCoE, NVESD, PEO IEW&S, and others

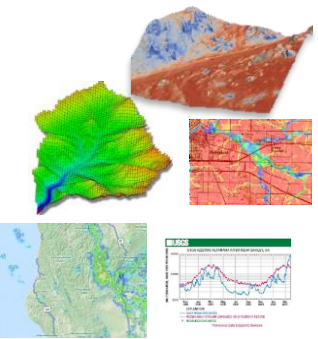


Motivating Example: Hurricane Flooding

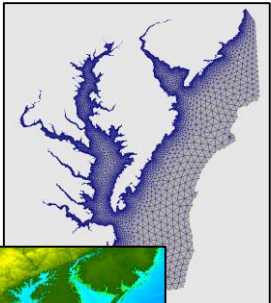


Rapidly evaluate many forecast scenarios anywhere across the globe

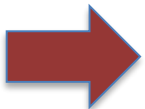
FORECAST SCENARIOS



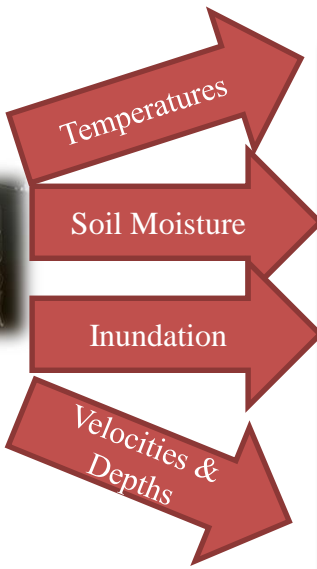
ENVIRONMENTAL DATA



COMPUTATIONAL GEOMETRY



PHYSICS BASED SIMULATION ENGINES



6 Months → Hours

Use Cases



Sensors



Mobility



Fluid Structure Interaction

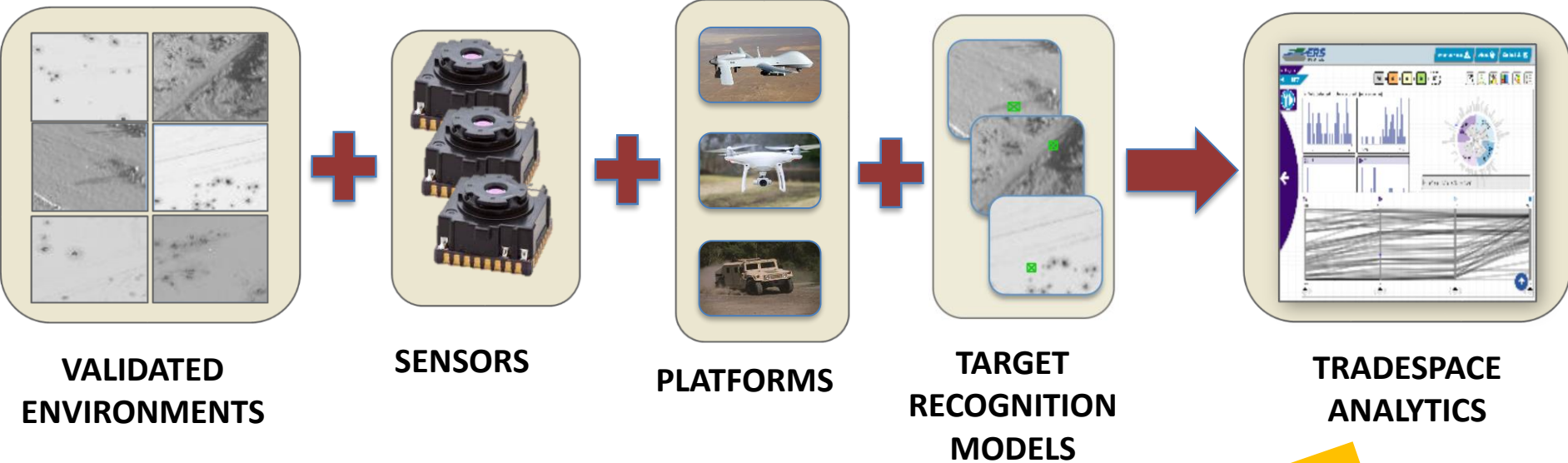
VIZUALIZATION & ANALYSIS



Motivating Example: Sensor Virtual Proving Ground Workflow

Analyze Environmental Impacts

- Access **validated** geotypical simulations and real imagery
- Bring in notional Sensor / Automatic Target Recognition (ATR) Models
- Mount on arbitrary platforms
- Test existing sensors for probability of detection (PD) and false alarm rates (FAR) in new or different environments



Evaluate thousands of sensor/platform/environment combinations with validated physics

Desired Capability



A New Approach

Integrated Product

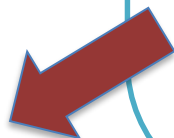
Powerful but heavyweight and inflexible, making it **hard** to:

- Adapt to new tasks
- Make use of available computing hardware
- Automate repetitive steps like parameter sweeping
- Create novel visualizations
- Add support for data larger than previously expected

Ad-Hoc Scientific Python

- Flexible by design
- Glue components together to make a workflow
- Components can be substituted/modified at will
- Flexible support for scaling up and out (Numba, Dask)
- Simple visualization via web browsers for local or remote sessions
- Solutions for big data viewed in browsers (Datashader)
- Emerging support for deploying notebooks as apps, dashboards

Can require excessive setup and programming and be complicated to deploy





Designing for Resiliency

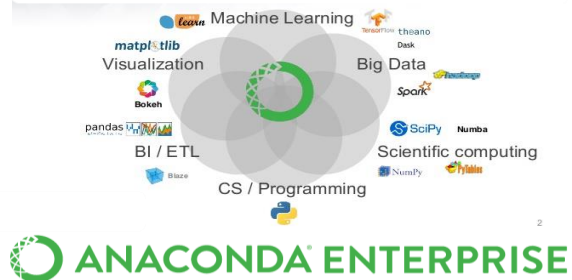


- Modular Python wrapped components
- Flexible workflows
- Front end agnostic
- Scale to multiple architectures
- Enhance existing open tools when possible
- Utilize existing enterprise capabilities when available
- Use standards when possible/feasible but value simplicity over compliance



Notional Architecture

Open Data Science Ecosystem



Rapid Application Development



Enterprise Security
 Secure Collaboration
 Containerized Deployment

Workflow Automation

Frontends



Scale



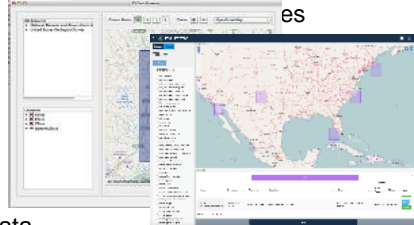
ERS Quest



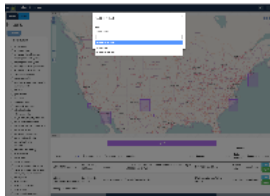
Search, download, and transform environmental data needed to set up high-fidelity, physics based models

- Extensible Plugin Architecture
- Python API
- Abstraction Layer
- Multiple Frontends
- Geospatial/Geotypical Search
- Data Catalog/Retrieval/Archival
- Data Transformation

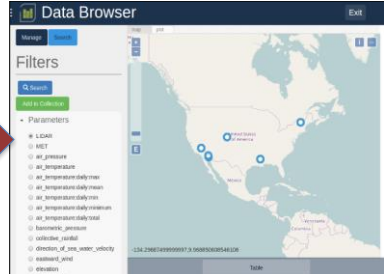
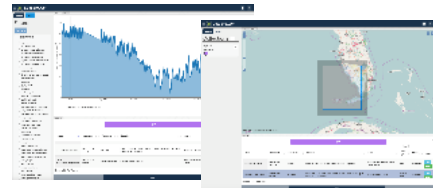
Web-based and Desktop ES



Transform Data



Visualize Time Series and Raster





Demo



Datashader

ERS Quest



HoloViews



Collaborators

Environmental Simulator Team:

Kevin Winters
Scott Christensen
Aaron Valorosa
Gaurav Savant

ERDC Collaborators:

Integrated Simulation Environment
Phenomenology (ISEP) Program

Industry Collaborators:

Anaconda Incorporated
Kitware Incorporated
Aquaveo





Questions

