



Computational Research and Engineering Acquisition Tools and Environments – Ground Vehicles (CREATE™-GV)

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Scope

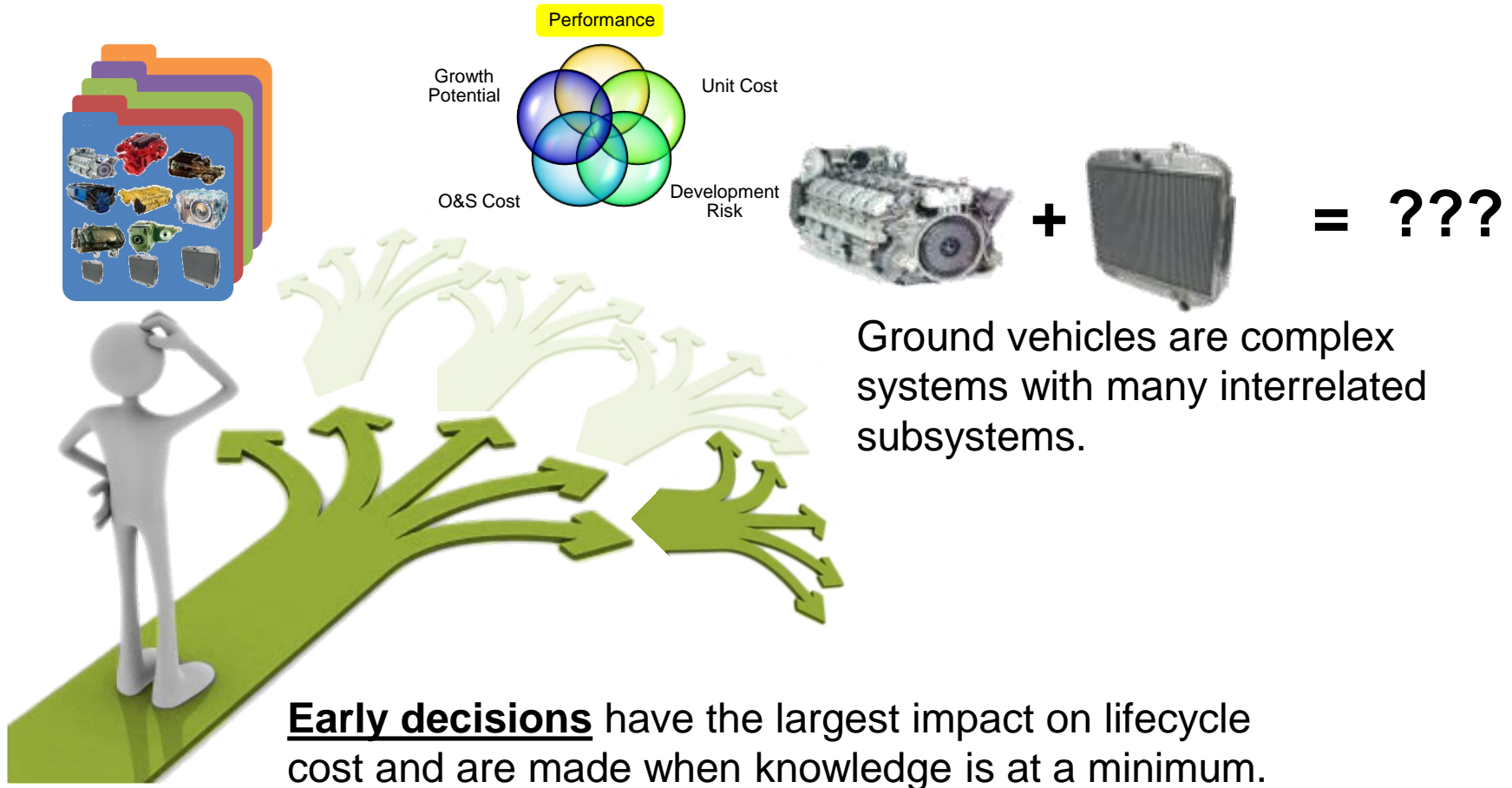
Develop physics-based, High Performance Computer (HPC) tools to enhance ground vehicle concept development, inform requirements development and provide requisite data for trade-space analysis to positively impact cost, schedule and performance with significant reduction in design risk for the acquisition community.

- **Ground Vehicle Interface (GVI)**
 - User interface to provide subject matter experts and power users with simplified and intuitive access to the analysis capabilities of the CREATE™-GV tools. The GVI does not require extensive knowledge of the underlying HPC M&S.
- **Mercury**
 - HPC physics-based co-simulation tool for M&S of terrain mechanics and vehicle systems and components. Incorporates suspension, tire and track, soil modeling, and powertrain simulation.
- **Mobility Analysis Tool (MAT)**
 - Computational tool for analyzing HPC physics data and producing mobility performance metrics required for trade exploration and systems engineering. Incorporates soil condition, vehicle performance and configuration, vegetation density, average surface roughness, average slope, etc.
- **Validation and User Transition**
 - Assist in capturing and integrating user requirements into CREATE™-GV.
 - Develop demonstrations and pilot projects to provide validation of products and processes.
 - Develop documentation and training – transition software products to users.

Early Detection of Design Flaws, Reduced Development Times, Enhanced Mission-Suitable Designs

CREATE-GV Focus is on Performance

Finding the sweet-spot among competing objectives (performance, unit cost, O&S costs, development risk, and growth potential) is a non-trivial task.



Capability and Gaps Document

CRES-GV Capability and Gaps Document

(May 16, 2013)

CRES-GV Capability and Gaps Document

High-Computational-Effort Tools for Ground Systems Design and Development

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CRES-GV

Computational Research for Engineering and Science -
Ground Vehicle

CRES-GV Capability and Gaps Document

(May 16, 2013)

Signatures, Effective Date and Version Control. This document is effective on the date of the last signature below. The Joint Center for Ground Vehicles Governance Board signatures provides the required endorsement from the Army and Marine Corps Ground Vehicle Acquisition and Technology leadership in order to obtain the appropriate financial support for this effort. The Joint Enterprise Development Integration council will provide version control of this document. Minor updates will be presented to the JCGV Governance Board for approval and updated with a version control sheet indicating approved changes. Major updates will require a new release of the document and an updated signature page.

Signatures

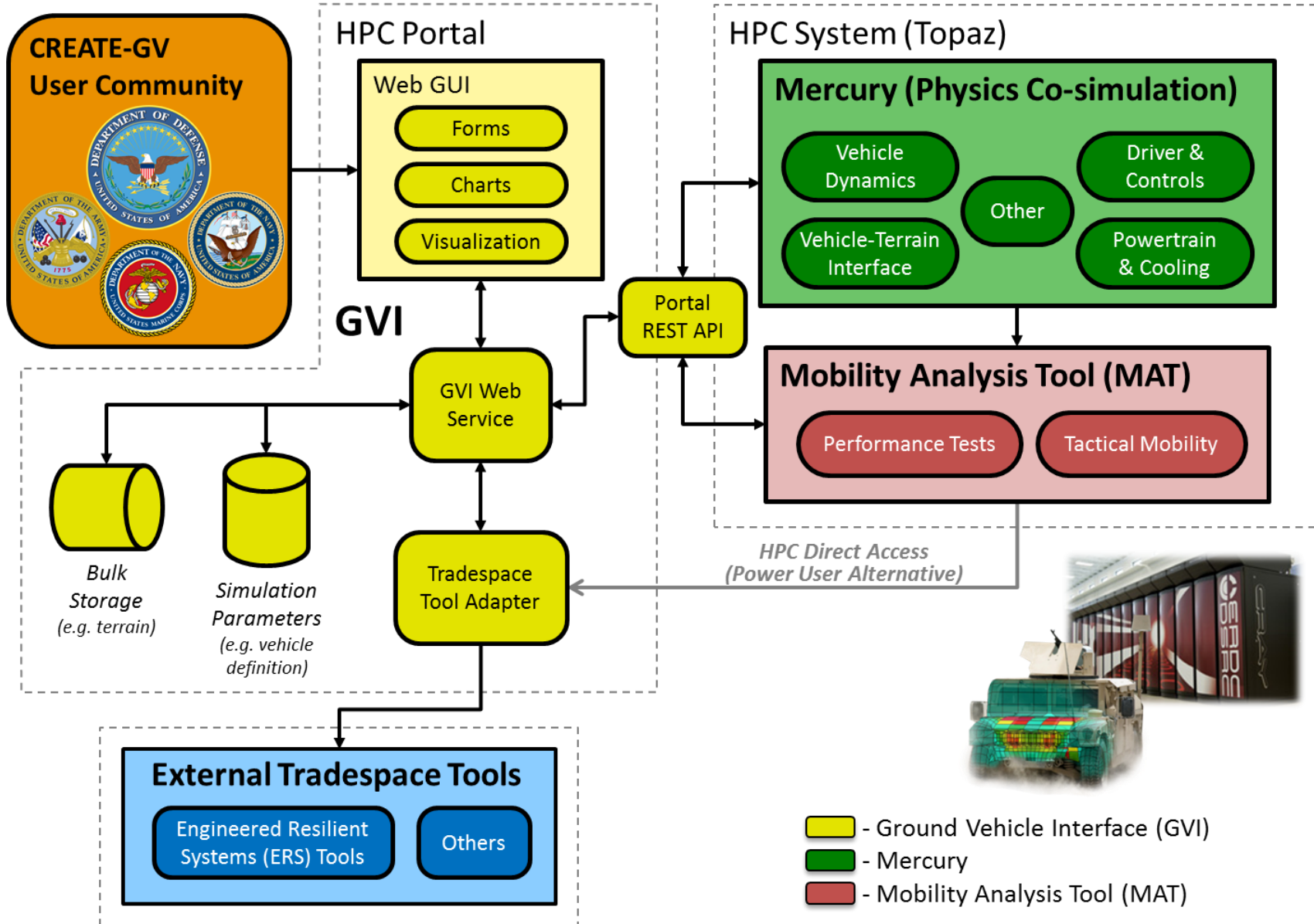
 MICHAEL D. VIGGATO Deputy to the Commander TACOM Life Cycle Management Command	 JAMES H. SMERCHANSKY Deputy Commander, Systems Engineering Interoperability, Architectures & Technology Marine Corps Systems Command
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Starting Point for CREATE™-GV Requirements

Physics Domain Gaps from the GV Capability and Gaps Document

ID	Physics Domain	Brief Description	GV Capability
PD-001	Propulsion	Focus on Powertrain performance	PACE, Mercury
PD-002	Mobility and Vehicle Dynamics	Focus on vehicle dynamics, off- and on-road mobility test metrics, and mission-level analysis	Chrono, Mercury, MAT
PD-008	Under Hood Cooling and Crew Cooling	Focus on cooling point considerations in powertrain performance	PACE, Mercury
PD-009	Soldier Models for Occupant Centric Analysis	Focus on design impacts upon human performance limits	Chrono, Mercury, MSU-CAVS support

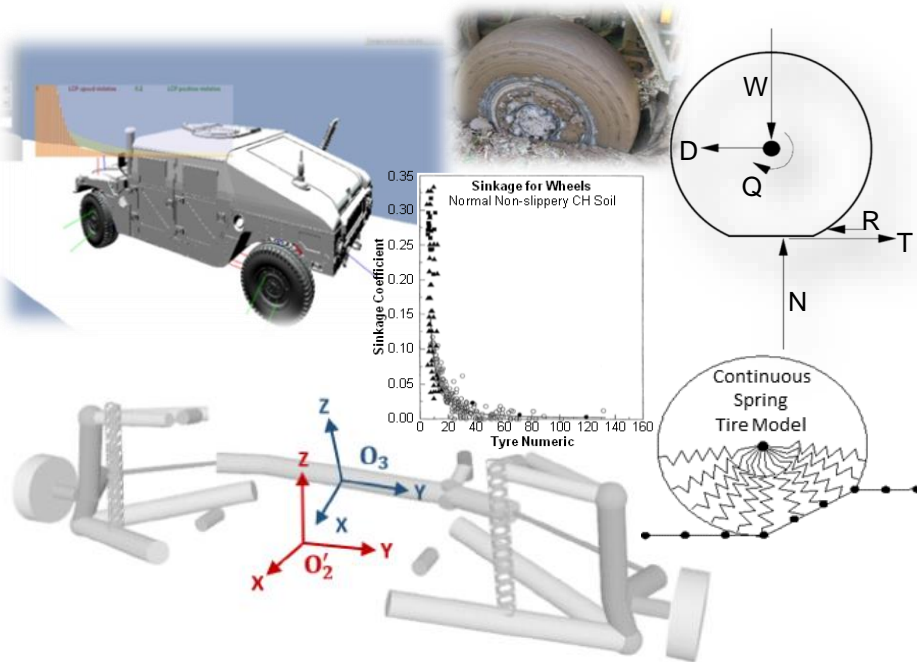
Current Architecture



Key Computational Tools

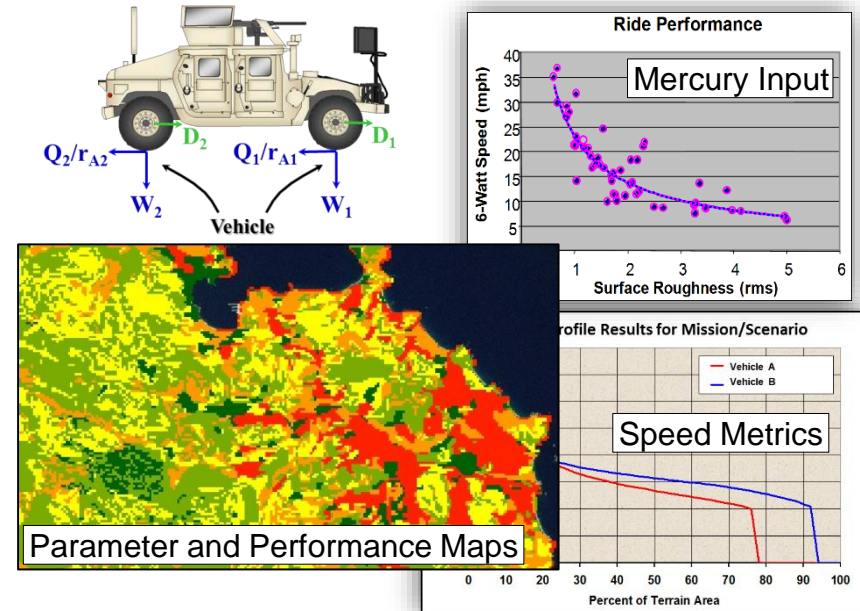
Mercury

- Simulates engineering performance tests of wheeled and tracked ground vehicles for proving-ground type developmental testing.
- Co-simulation framework for integrating physics domains.
 - Powertrain
 - Vehicle Dynamics (wheels and tracks)
 - Tire-soil & track-soil interaction



Mobility Analysis Tool (MAT)

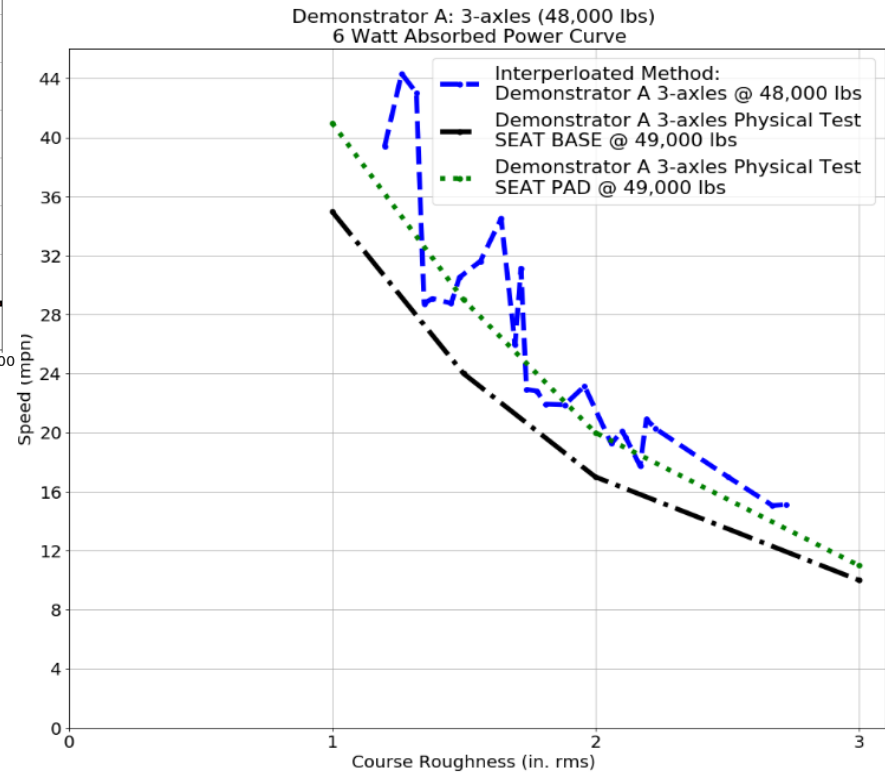
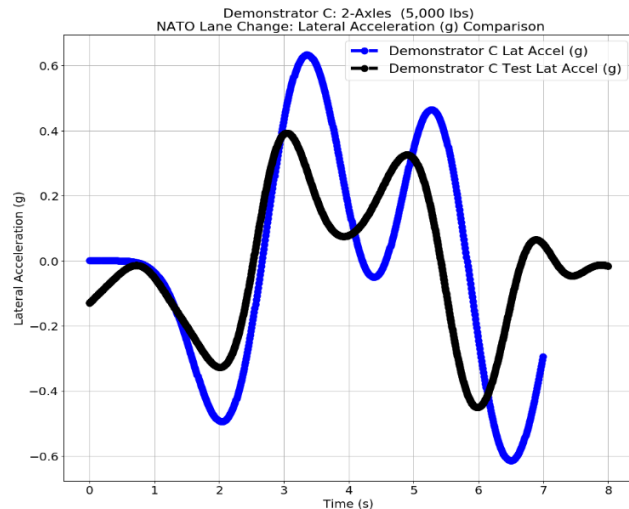
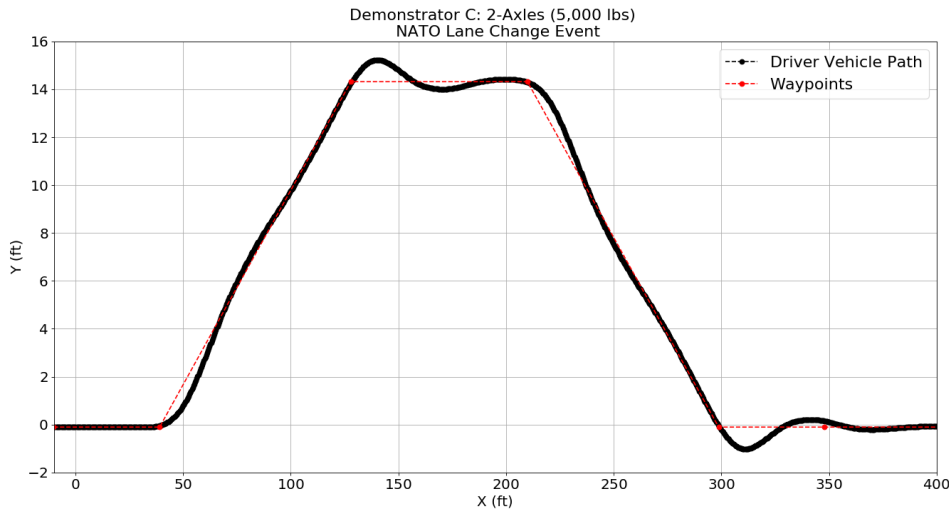
- Converts vehicle performance metrics and terrain information into mission-based analysis of performance over large areas of terrain.
- Predicts multiple metrics currently used in acquisition processes.
 - % NOGO
 - Mission rating speeds



Validation and User Transition

Emphasis on validated and useful tools

- Ensure GV products provide credible results to users and key decision makers.
- Facilitate the transition from developers to the user community.



Development Partners



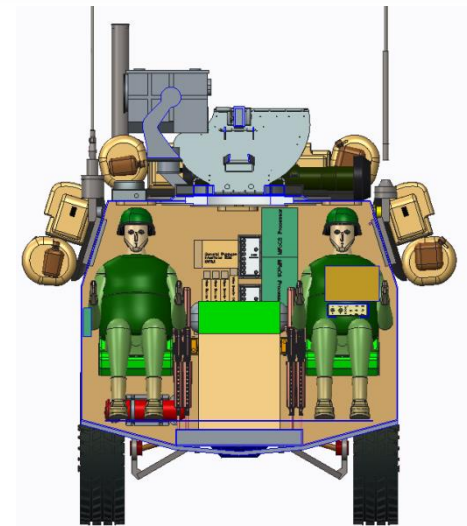
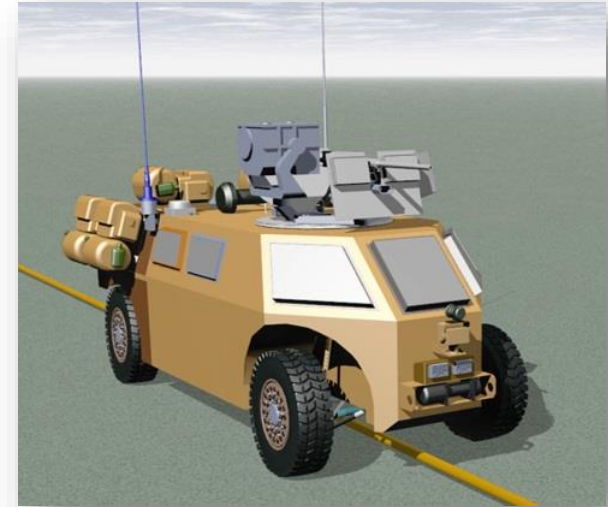
CREATE-GV Impacts

Engineered Resilient Systems (ERS) – Light Reconnaissance Vehicle (LRV) Pilot Program

- The GV HPC tools GVI, Mercury and MAT have been integrated to provide S&T users a simplified capability to generate the requisite data for trade-space analysis.
- Over 65,000 unique LRV configurations have been analyzed for 5 key mobility performance parameters

Future Users

- The limited early successes of the GV tools have initiated interest from various DoD users and from private industry. The tools are currently being deployed for use by key DoD government end-users with objectives for later industry use.





CREATE



Thank You

