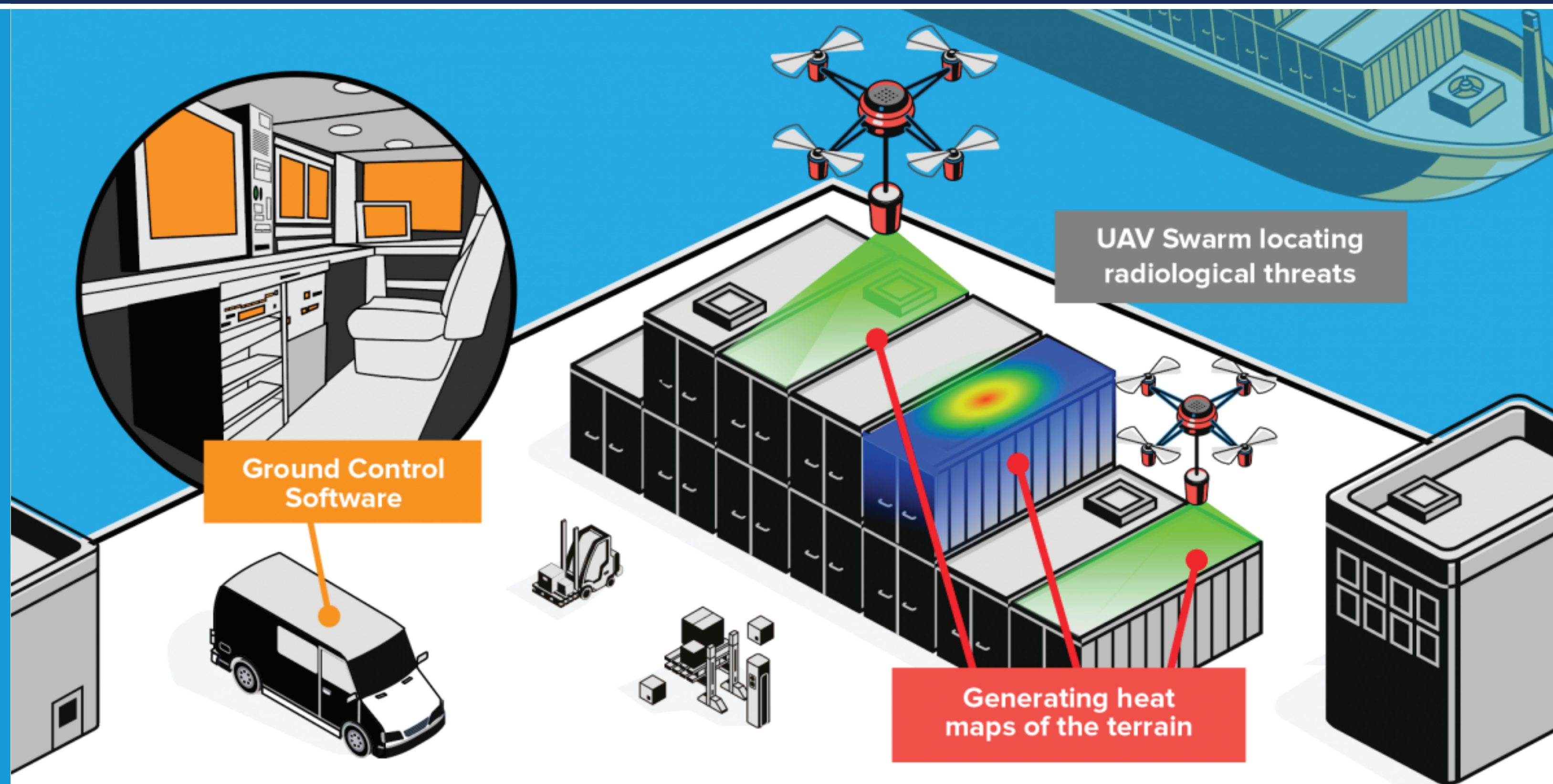
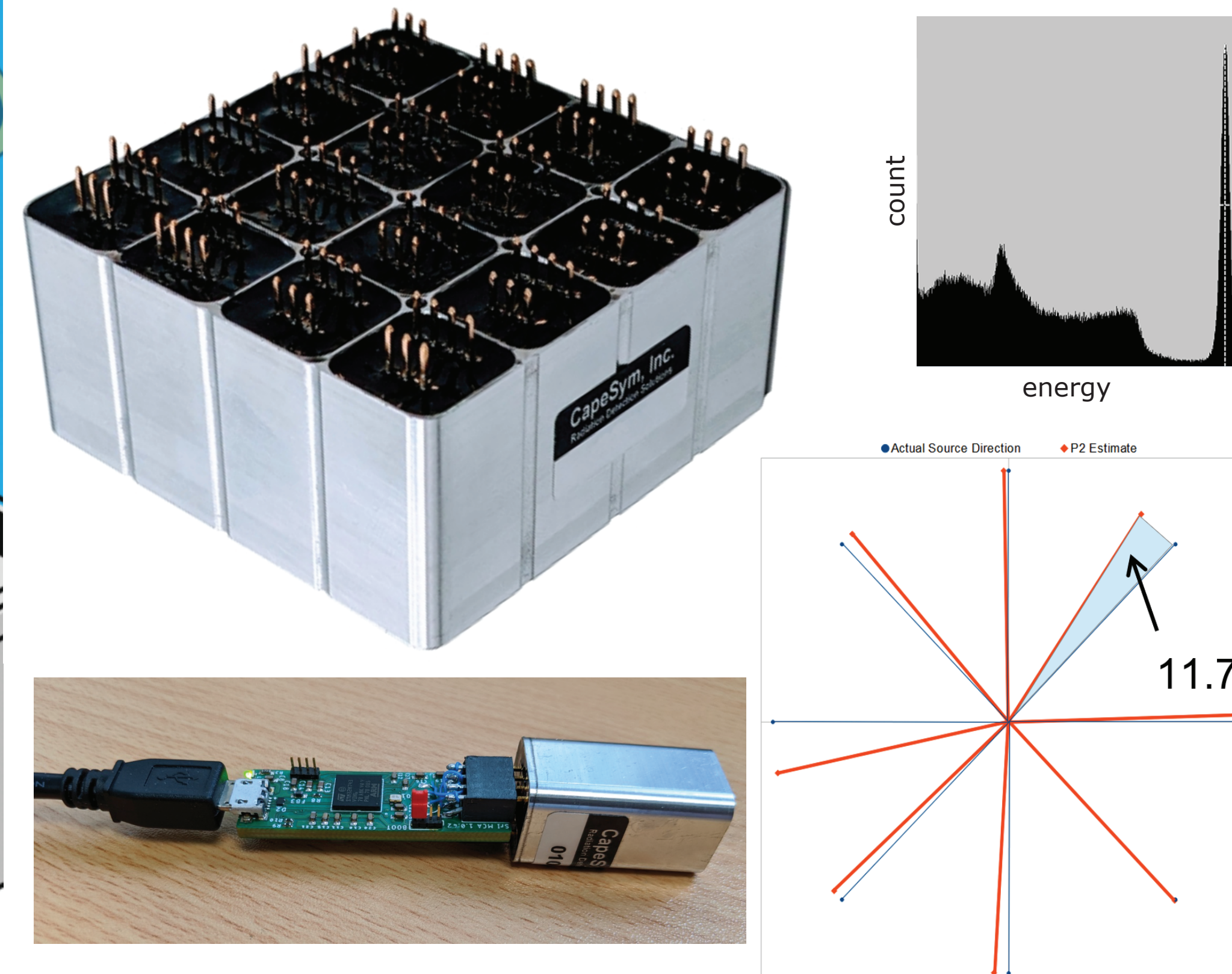
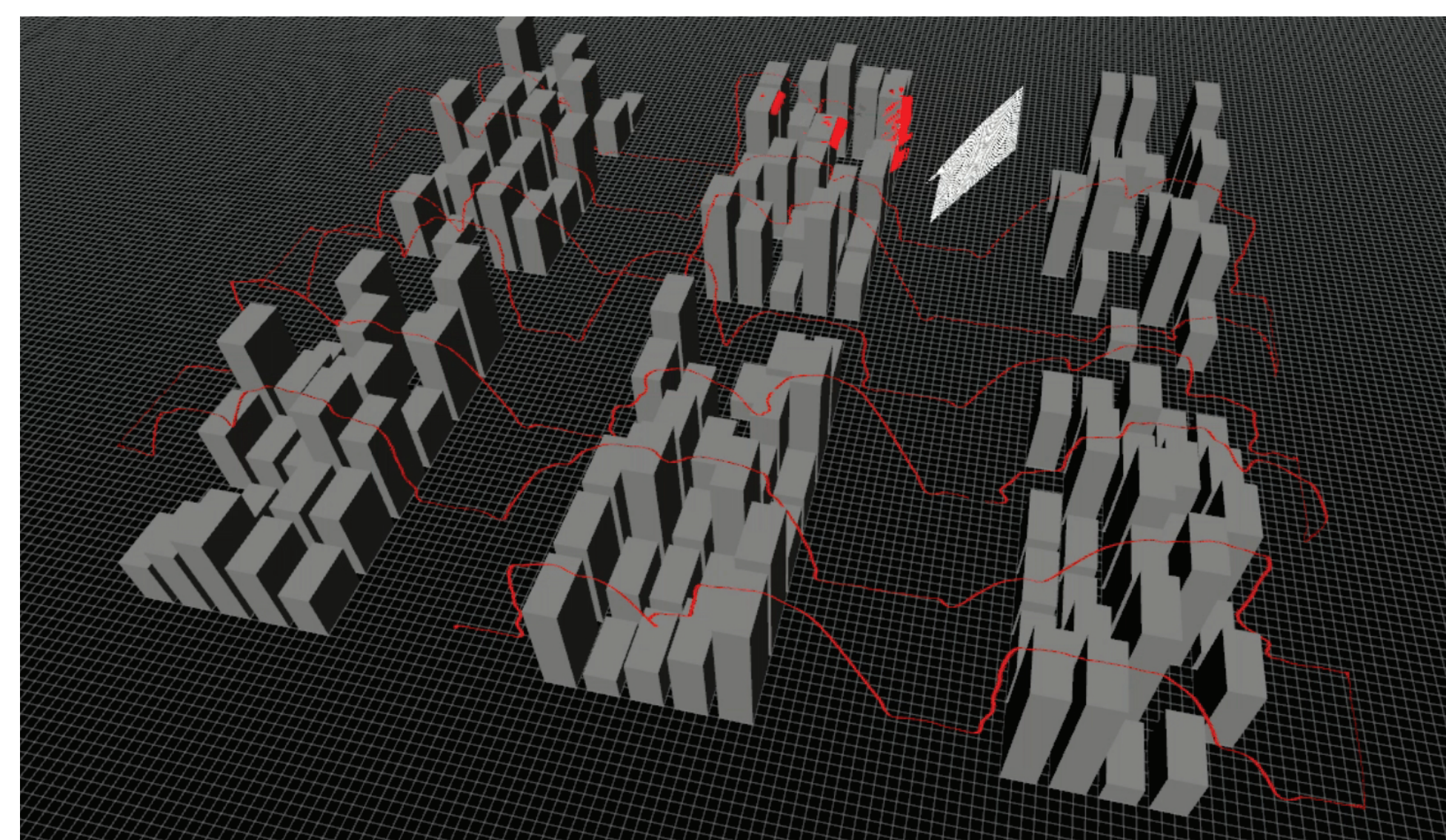


# Autonomous drones with directional sensors to locate radioactive sources in complex environments

Perry Franklin, Daniel Stouch, Matt Kwan, Rich Wronski, Shariar Motakef, John Fiala, Ivan Khodyuk



Modeling and simulation help develop and refine autonomous capabilities to explore complex environments



Custom directional 16 module radiation sensor increases detection sensitivity and enables rapid source localization

## Benefits

- Onboard autonomy enables obstacle avoidance
- Dynamic path planning enables faster area searches
- Directional sensing quickly localizes sources
- 3D object mapping provides precise source localization
- Onboard sensor fusion allows heatmap overlays
- Object detection helps determine response priorities
- Multi-UAV coordination reduces search times
- Autonomy reduces operating cost per survey mission
- Capability significantly reduces exposure risk
- Autonomy reduces specialized training requirements

## Approach

Enable specialists to conduct surveys for anomalous radiological threats using autonomous uncrewed aerial vehicles (UAVs)

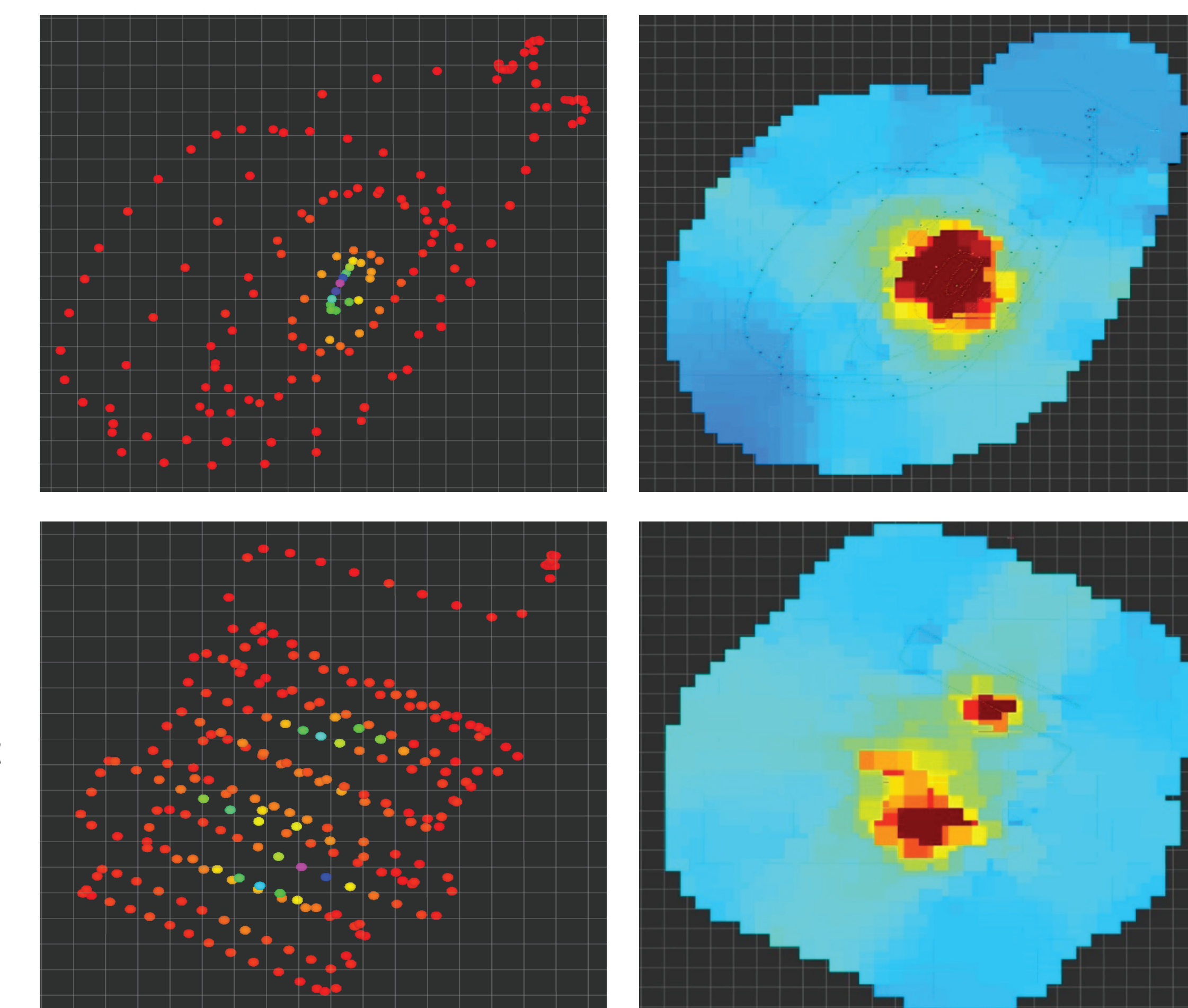
Incorporate state-of-the-art visual perception, mapping, and optimal path planning techniques and perform terrain following at a specified standoff distance enabling the rapid search for radiological threats

Provide directional detection information to a 3D environment model, assisted by a novel radiation crystal configurations

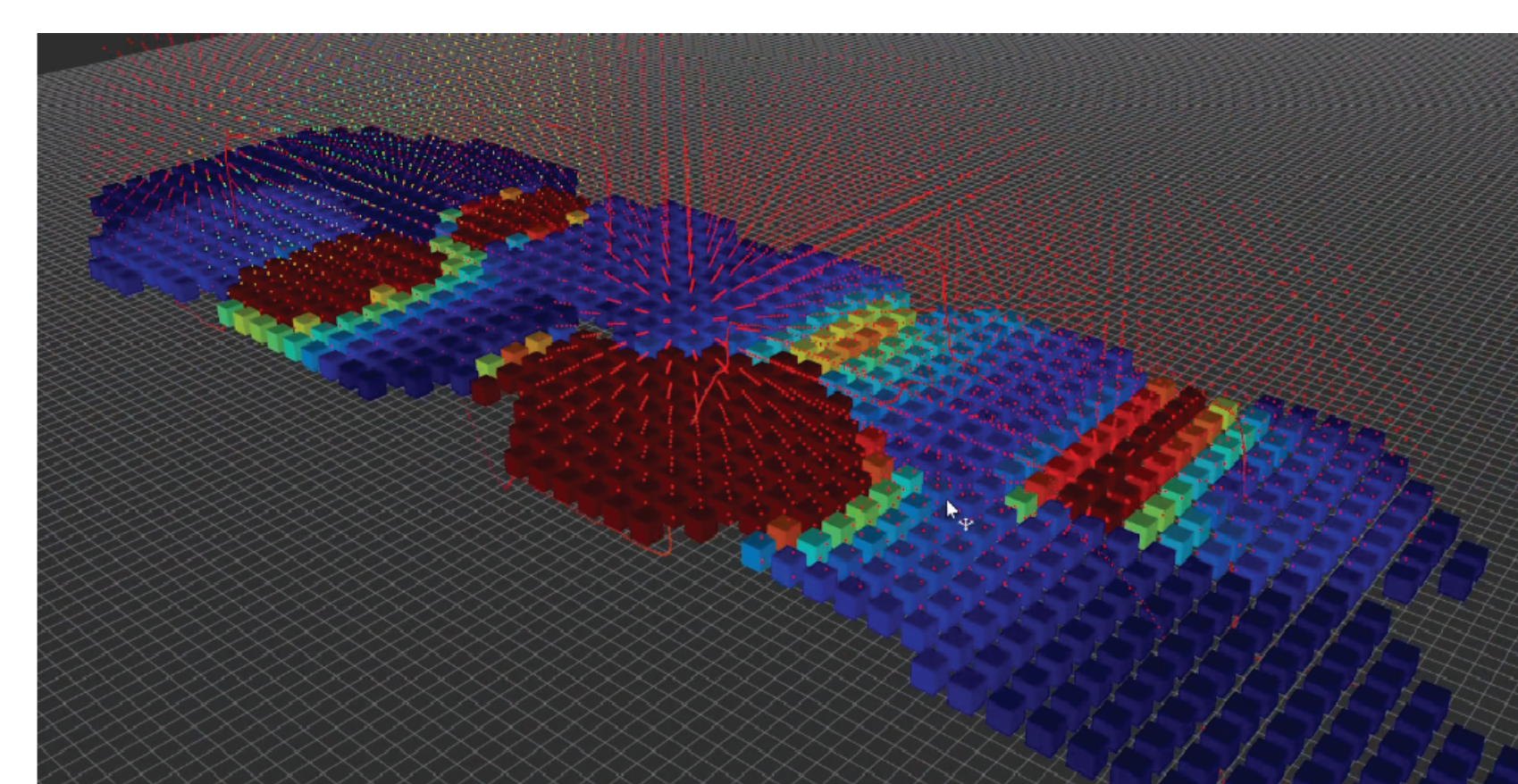
Avoid collisions while exploring challenging and dynamic unknown environments by fusing this directional information with localization and adaptive local path planning capabilities to ensure full search area coverage



Integrated off the shelf components enable low cost, reliable autonomous capabilities



Radiation heatmaps generated in real time using a spiral search for one source (top) and a raster pattern for two sources (bottom)



Real-time 3D heatmap renderings provide geospatial context for response

## Acknowledgement

This work is supported under the U.S. Department of Homeland Security, Countering Weapons of Mass Destruction competitively awarded SBIR contract 70RWMD20C00000003. This support does not constitute an express or implied endorsement on the part of the Government.

DISTRIBUTION STATEMENT A.  
Approved for public release: distribution unlimited.

## Contacts

Perry Franklin, [pfranklin@cra.com](mailto:pfranklin@cra.com)  
Daniel Stouch, [dstouch@cra.com](mailto:dstouch@cra.com)  
Matt Kwan, [mkwan@cra.com](mailto:mkwan@cra.com)  
Rich Wronski, [rwronski@cra.com](mailto:rwronski@cra.com)  
Shariar Motakef, [motakef@capesim.com](mailto:motakef@capesim.com)  
John Fiala, [fiala@capesim.com](mailto:fiala@capesim.com)  
Ivan Khodyuk, [khodyuk@capesim.com](mailto:khodyuk@capesim.com)



charles river analytics