### Hybrid Digital Twin Technology for Predictive Maintenance

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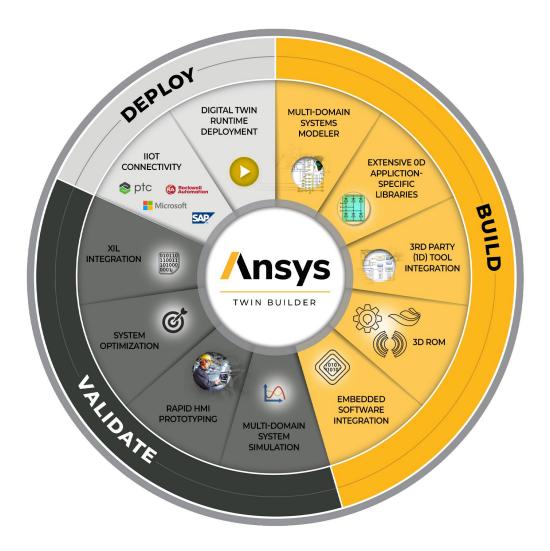
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Approved for public release

# Overview

- Intro
- Digital Twin Challenges
- Hybrid Solution
- Hybrid Analytics Capabilities



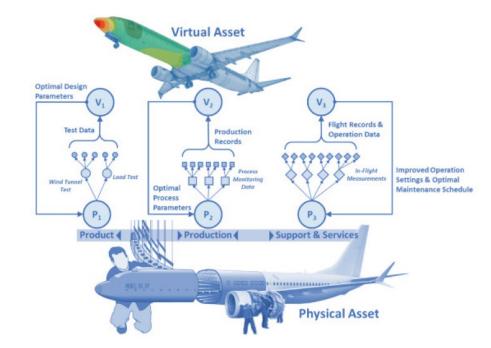




A Digital Twin is a virtual representation of real-world entities and processes, synchronized at a specified frequency and fidelity.

A Digital Twin is a Virtual Representation of a <u>connected</u> Physical Asset





Digital Twin : Definition & Value, AIAA & AIA, December 2020



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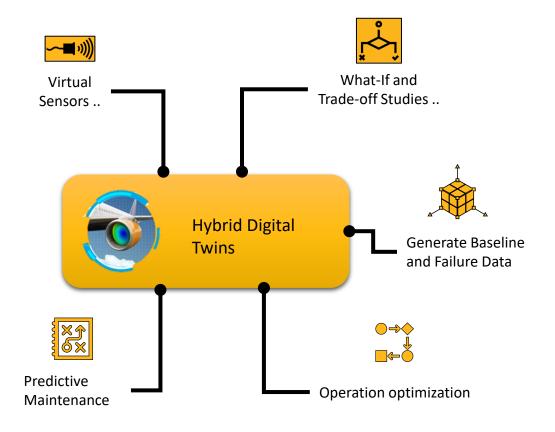
## Value of Digital Twins

Detect, prevent, predict, and optimize through real time analytics to deliver business value



Virtual Commissioning, Trouble Shooting and System Configuration

- Predictive and PrescriptiveMaintenance
  - Production Optimization and Yield-as-aservice





## Challenges in Creating a Digital Twin

#### Accuracy

Adhere as closely as possible to physical behavior

Adaptability

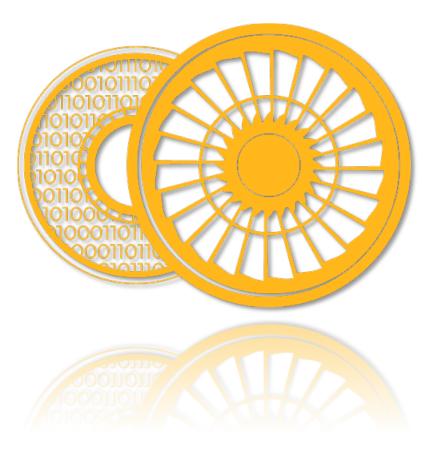
Adapt to changing environments and conditions

### Flexibility

Model multiple scenarios without overfitting to any one

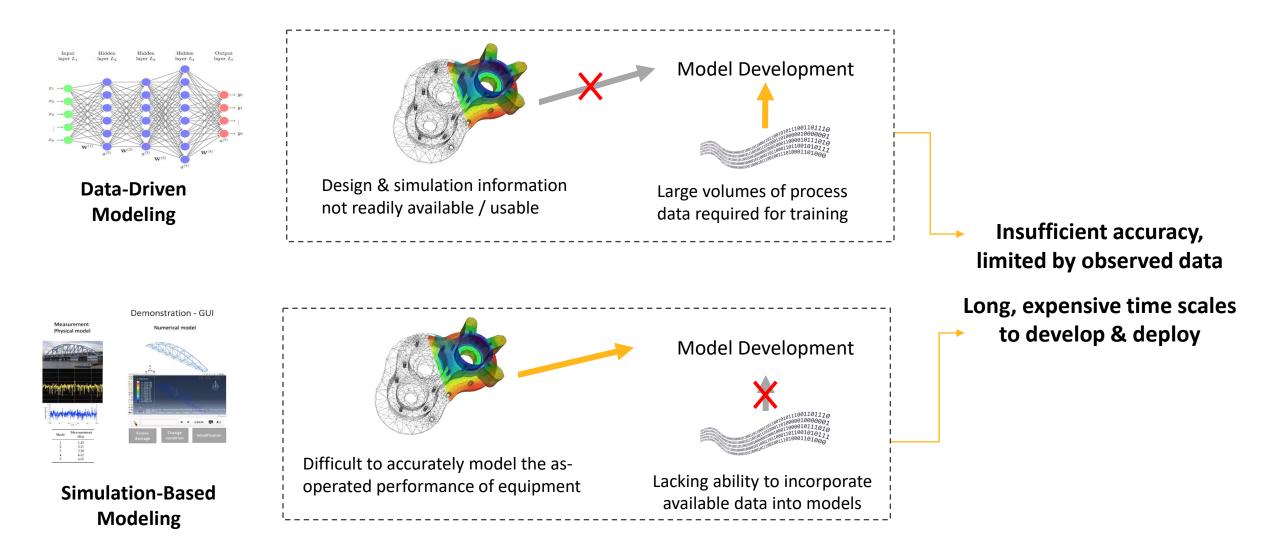
#### Scalability

Rapidly build and deploy adaptable Digital Twins



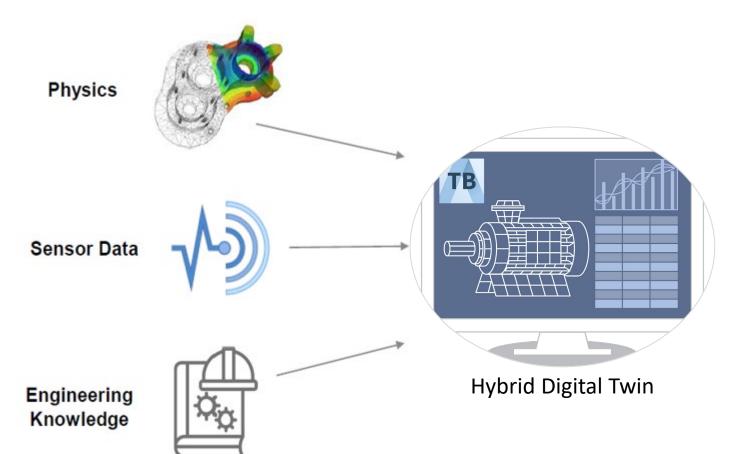


### Digital Twin Challenge: Accuracy, Time & Cost



Insys

### Solution = Hybrid Digital Twin



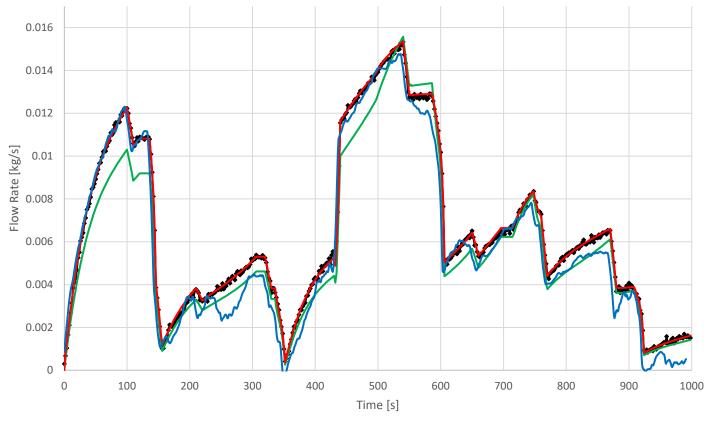
- Combine the best of both approaches
- Use all available information from engineering, physics, and data
- Integrate into a Hybrid Digital Twin



# The Hybrid Approach

 Data and Simulation approaches each make reasonable predictions, but also both face limitations

 Using the same data and the same physics model, the Hybrid Approach resents a better, more efficient solution.



---- Data ----- Nominal ----- Calibrated ----- ML Model



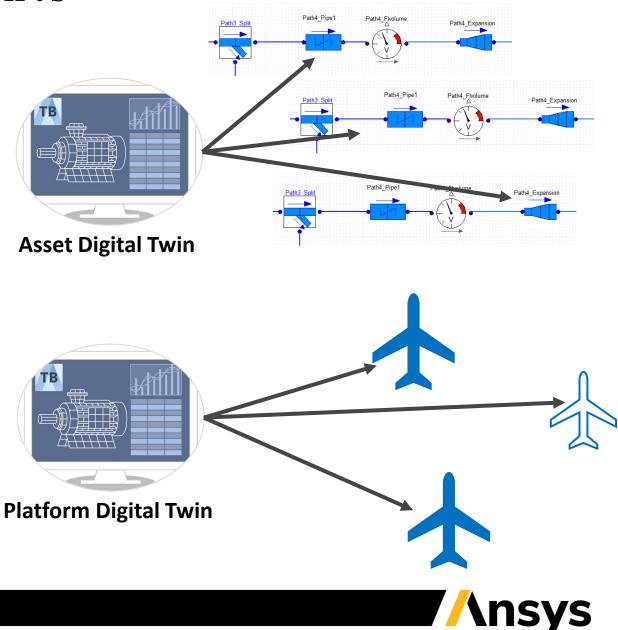
### Use Case – Fleet Deployments

#### **Challenges**

- Deploy the same Digital Twin to multiple assets in a fleet
- Adapt the twin behavior to each asset as it evolves independently of others in the fleet

#### Solution

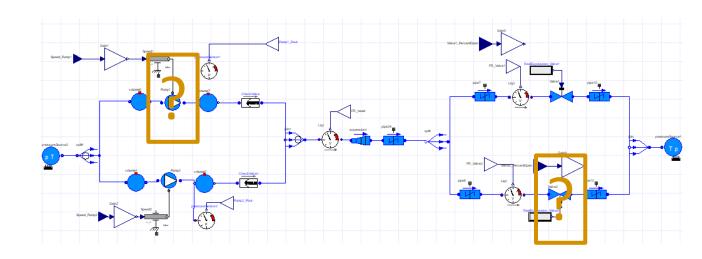
 Use data from each asset to update and adjust the twin to match the asset's unique behavior and environment



### Use Case – Brown field Deployments

### Challenges

- Operators have incomplete information for their system
  - Missing specs or drawings
  - OEM protected IP
- Asset behavior may have changed over time



### Solution

• Learn missing behavior/information my enhancing a model with data



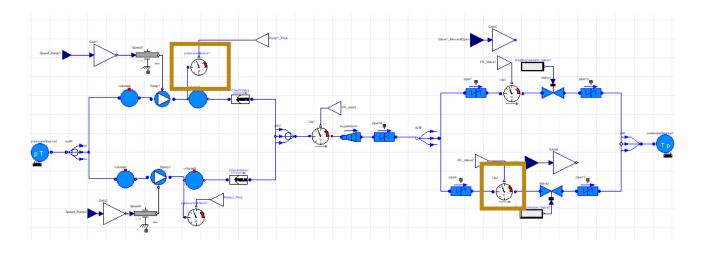
### Use Case – Green field Deployments

#### Challenges

• Physical sensors are expensive

#### Solution

- Decrease cost by replacing physical sensors with virtual sensors
- Optimize where to place sensors





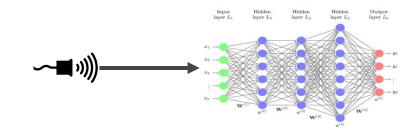
### Use Case – Virtual Sensors

#### **Challenges**

- Missing information for data models
- Inability to collect with physical sensors either due to cost or because there is not sensor for desired information

#### Solution

- Virtual sensors provide missing information
- Validate Digital Twin with some physics sensors and predict other missing quantities

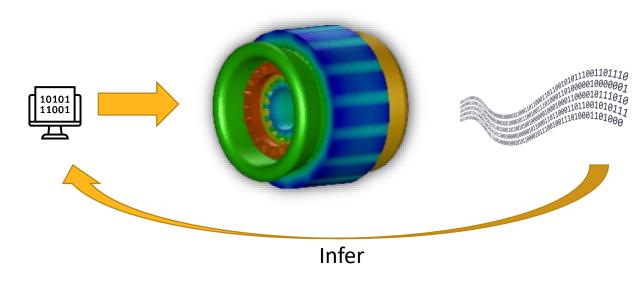




### Use Case – Inverse Problem

#### Challenges

• Understand how to change operation when asset behavior doesn't match desired outcomes



#### Solution

• Use data and a Hybrid Digital Twin to infer what inputs or operating conditions would lead to the desired behavior

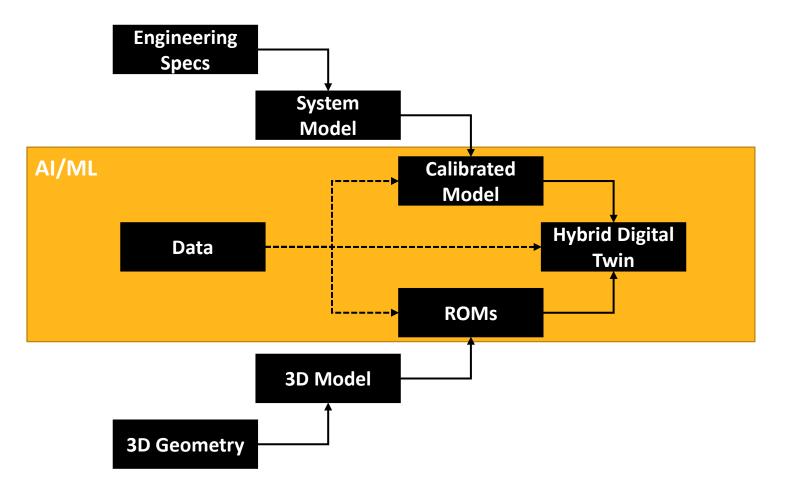


# Building a Hybrid Digital Twin

### -Two Approaches

#### Top Down

- Accuracy is achieved through model calibration based on experimental data
- Real-time simulation achieved through light-weight system models

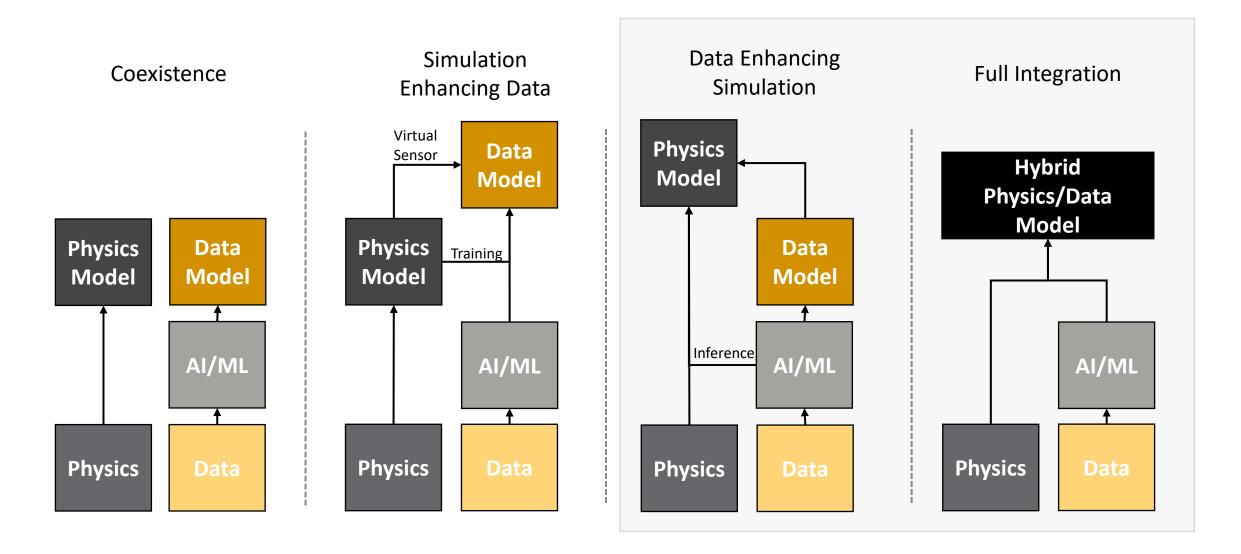


**NSVS** 

#### Bottom Up

- Accuracy is based on high-fidelity modeling of full physics equation and accurate geometry
- Real-time simulation achieved through ROMs

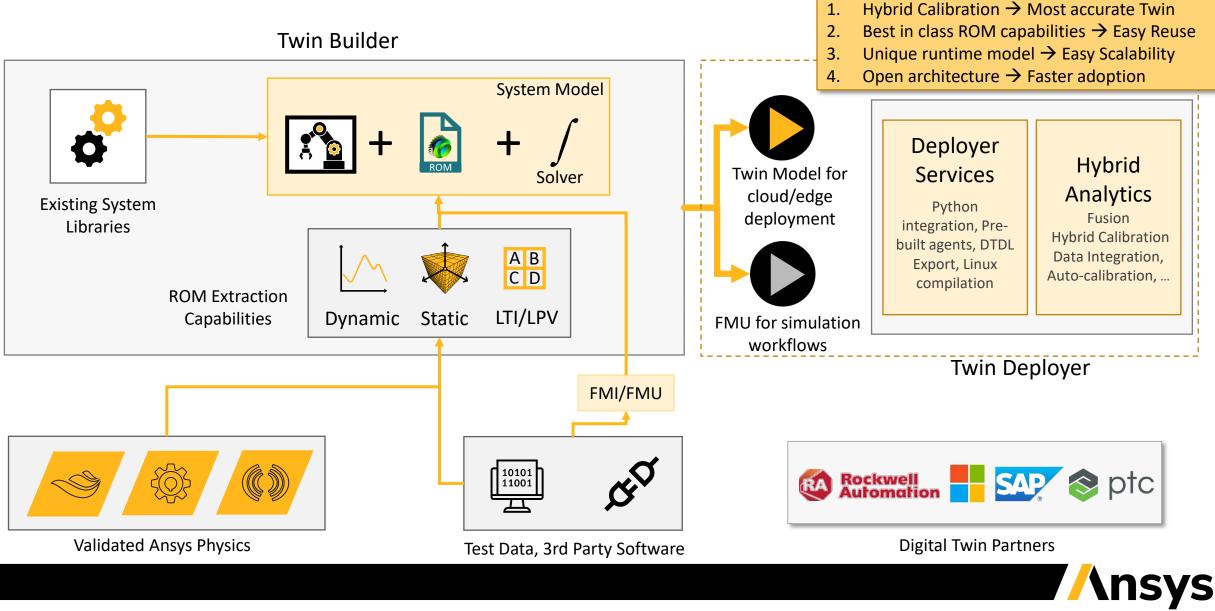
### The Hybrid Framework



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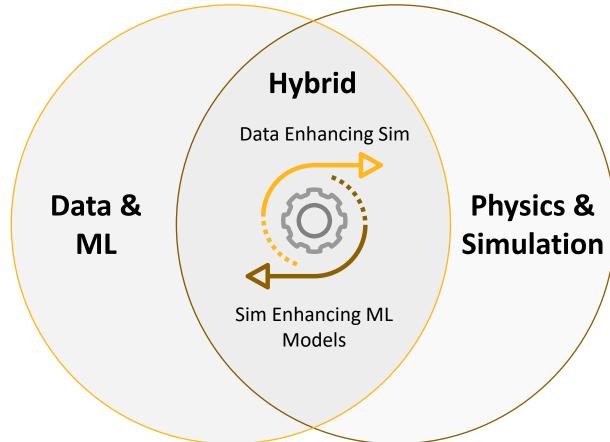
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### Digital Twin Solution Architecture



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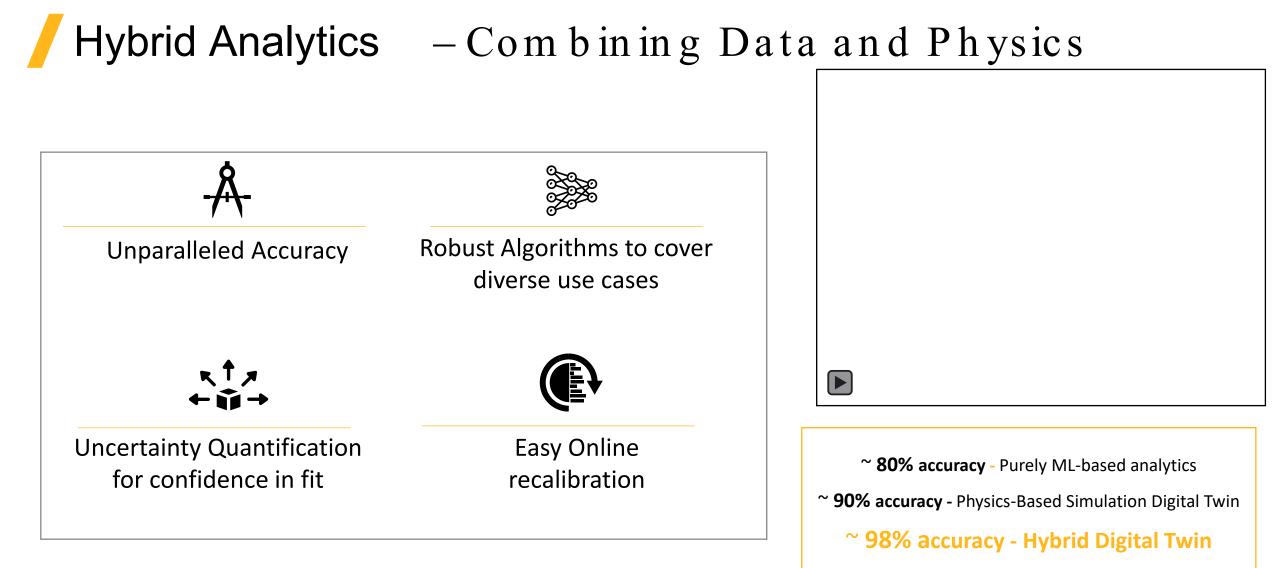
# Hybrid Analytics



**Hybrid Analytics** is a toolset for combining data and physics modeling using machine learning techniques



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(ML-based analytics combination with the physics-based approach)



### Hybrid Analytics Calibration



### What is Hybrid Calibration?

- Parameter Estimation
- Uncertainty Quantification on parameters
- Uncertainty Propagation to outputs

• Key use-case is virtual sensors



Learn simulation model parameters from data

**Parameter Estimation** 

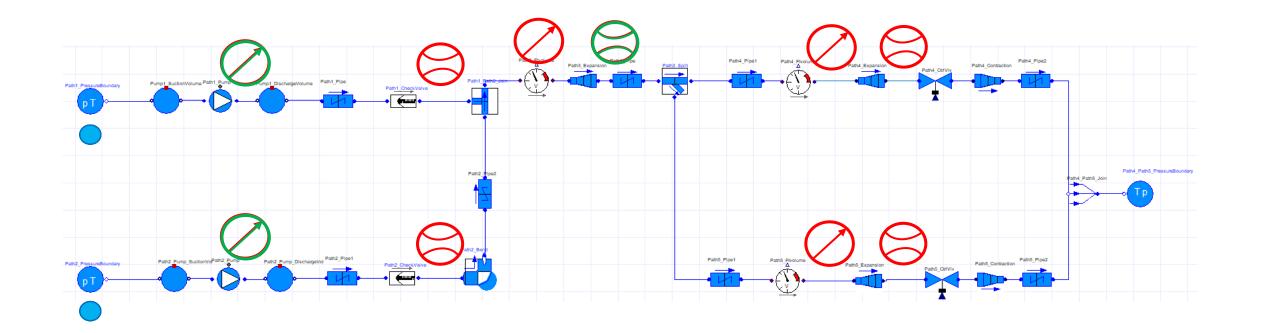


Create virtual sensors to "measure" missing data



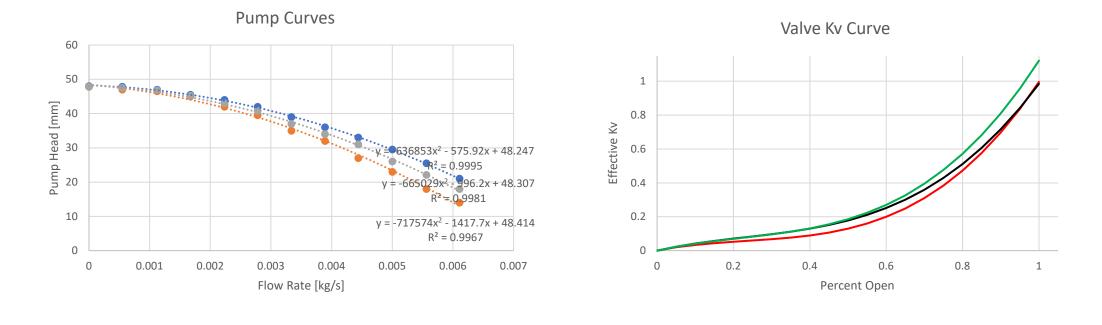


**Challenge:** Determine the flow and pressure on each branch with a minimal number of physical sensors





### Component Models and Parameters



 $H = b_0 + b_1 q + b_3 q^2$ 

 $K_{\nu} = a_0 + a_1 D + a_2 D^2 + a_3 D^3$ 

Three polynomial coefficients as parameters

Four polynomial coefficients as parameters



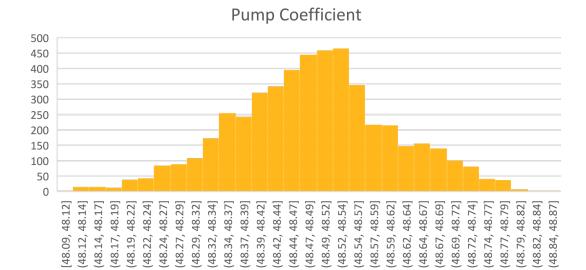
### Results – Model Parameter Distributions

#### Pump Coefficient b<sub>0</sub>

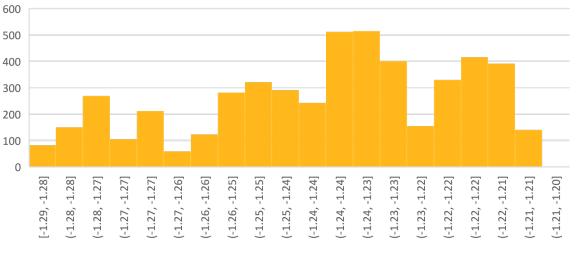
- Peaked distribution shows confidence in prediction
- Range gives uncertainty on measurement

Valve Coefficient a<sub>2</sub>

- Dispersed distribution shows that system behavior is insensitive to this parameter
- The parameter can take a wide range of values without significantly affecting the system behavior

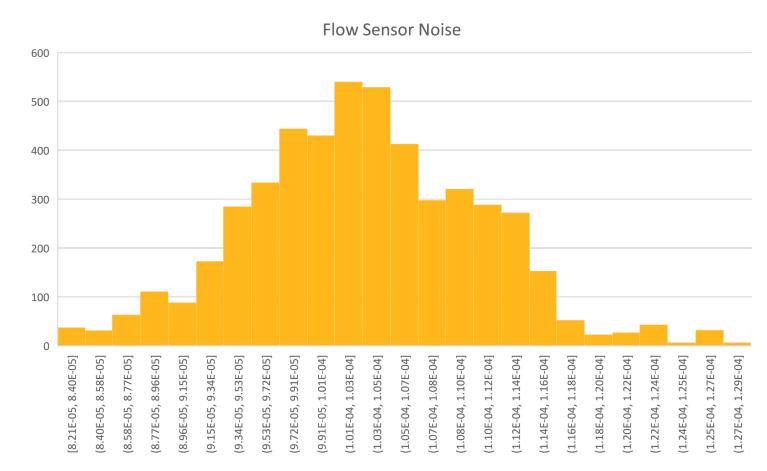


Valve Coefficient



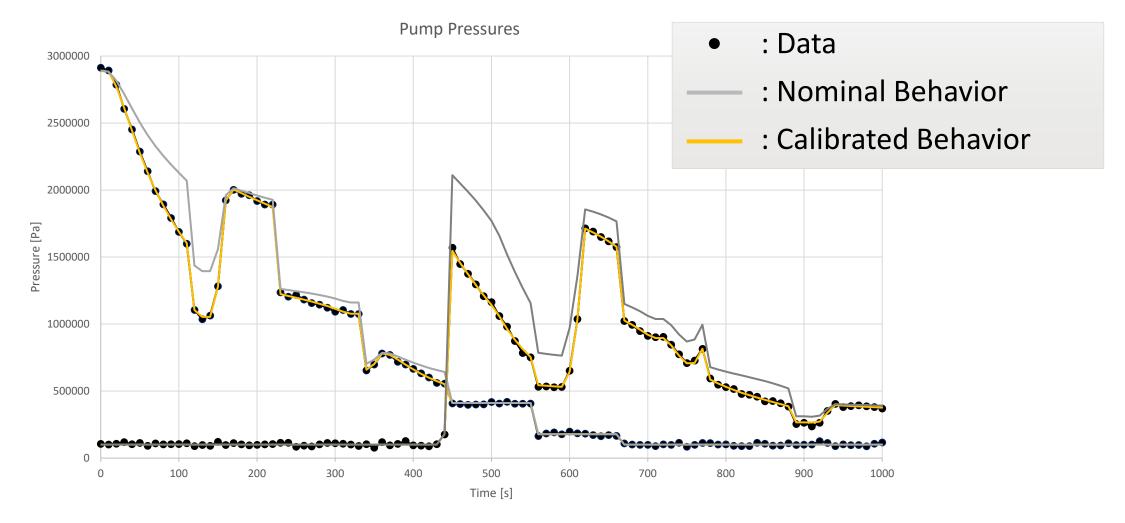
### **Results** – Noise Parameter Distributions

- Manufacturer Spec = 0.1 g/s
- Most Probable = 0.102 g/s
- Accurate virtual sensor value and uncertainty
- Simultaneously fit physical model and noise





### **Results** – Before and After For Physical Sensors



• Updated behavior matches performance much better than nominal manufacturer specs

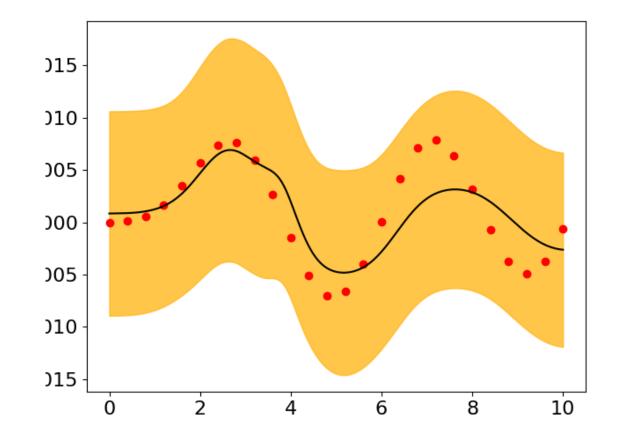
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### Hybrid Analytics Fusion Modeling



### Fusion Models

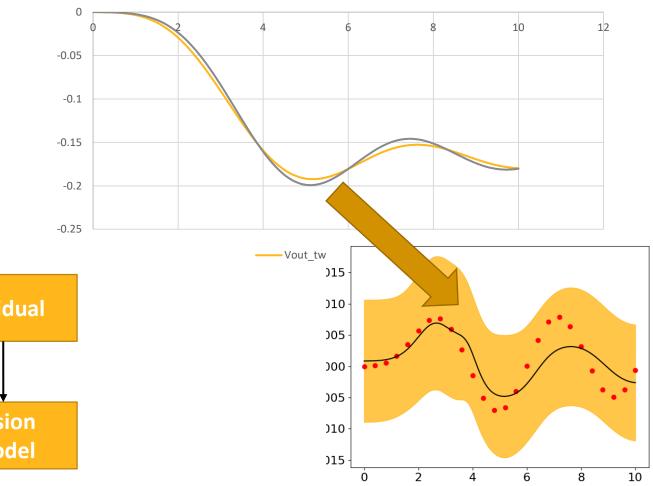
- Multiple machine learning techniques for creating models from data sources
- For some use cases:
  - Automatically search over available techniques and choose the best model
  - Return uncertainty of fit



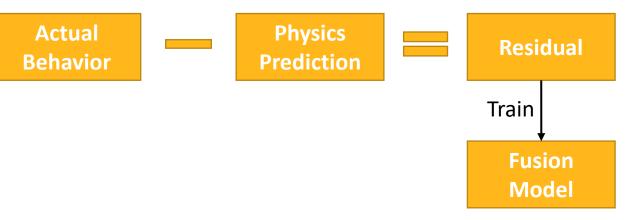


## Fusion Use Case: Residual Modeling

- Often even the best simulations don't perfectly match sensor data
- Instead of training a full data model, use the most accurate physics model available and train an ML model of the residual
- The results of the physics model + the residual model correction give a better outcome.



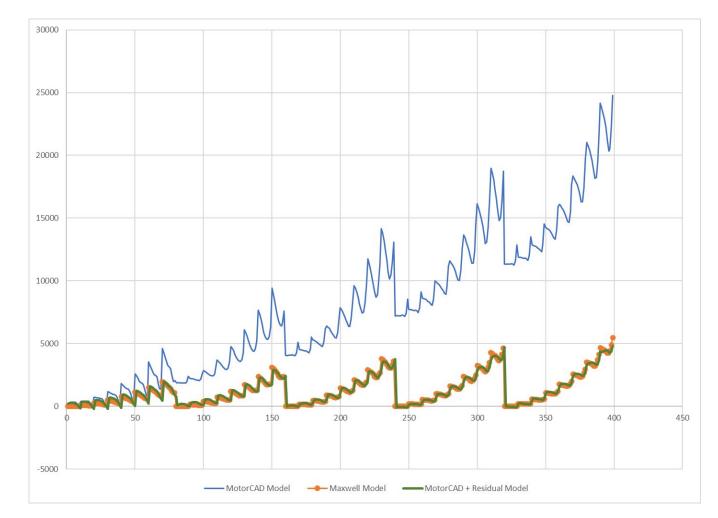
Twin vs Reference





### Fusion Use Case: Approximating 3D Models

- 3D simulations can be costly
- Lower fidelity 1D models are an approximation to 3D simulations
- Build a multifidelity regression model to fill in gaps in 3D model by fitting the difference between the higher fidelity and lower fidelity models
- For the case shown at the left, a Maxwell model gives much higher results than a MotorCAD model
- But, the MotorCAD model plus a trained fusion model performs about the same as the full Maxwell model







- Hybrid Digital Twins solve challenges inherent in creating Digital Twins.
- The Hybrid Analytics toolset combines data and physics modeling together to create the best possible Hybrid Digital Twins.
- Hybrid Digital Twins ingest field data to adapt to changing environmental conditions.





